# The algebra of alternation and synchronisation of finite dynamical systems 

Antonio E. Porreca • aeporreca.org Aix-Marseille Université \& LIS

## The team

Florian Bridoux
Johan Couturier
Alberto Dennunzio

François Doré
Valentina Dorigatti
Enrico Formenti
Caroline Gaze-Maillot

Luca Manzoni
Émile Naquin
Kévin Perrot
Antonio E. Porreca
Sara Riva
Marius Rolland
Ekaterina Timofeeva

# Finite, discrete-time dynamical systems Just a finite set with a transition function $(A, f)$ 



## Finite, discrete-time dynamical systems

 Just a finite set with a transition function $(A, f)$ modulo isomorphism

## General shape of a dynamical system

A few limit cycles


## General shape of a dynamical system

A few limit cycles with trees going in


## General shape of a dynamical system

 A few limit cycles with trees going in
## General shape of a dynamical system

A few limit cycles with trees going in


## General shape of a dynamical system

A few limit cycles with trees going in


# Isomorphism of dynamical systems is easy 

2009 24th Annual IEEE Conference on Computational Complexity

Planar Graph Isomorphism is in Log-Space

Samir Datta* ${ }^{*}$, Nutan Limaye ${ }^{\dagger}$, Prajakta Nimbhorkart, Thomas
Email: sdatta@cmi.ac.in
†The Institute of Mathematical Sciences, Chennai
Email: \{nutan,prajakta\}@imsc.res.in
$\ddagger$ Fakultät für Elektronik und Informatik, HTW Aalen
Email: thomas.thierauf@uni-ulm.de
§Institut für Theoretische Informatik, Universität Ulm
für Theoretische Ingormer@uni-ulm.de
Email: fabian.wagner
The problem is clearly in NP and by a group theoretic

Abstract
Graph Isomorphism is the prime example of a computational problem with a wide difference between the bere is known lower and upper bounds lower and upper bounds for a significant gap between We bridge the gap for this natural planar graphs as well. We becial case by presenting an upper bound and important special cas los-space hardness [JKMT®]. In
proof also in SPP [AK06]. This is the current frontier of our knowledge as far as upper bounds go. The inability one give efficient algorithms for the proble hard. NP-hardness to believe that the problem is protes if GI is NP-hard then is precluded by a result that states if GI second level the polynomial time hierarchy collapses surprising is that not even [BHZ87], [Sch88]. What is more sulem. The best we know $P$-hardness is known for the problem. The class of problems is that GI is hard for Determinant, defined by Cook [Coo85].

# Isomorphism of dynamical systems is easy 

2009 24th Annual IEEE Conference on Computational Complexity<br>Samir Datta* ${ }^{*}$ Nutan Limaye ${ }^{\dagger}$, Prajakta Nimbhorkar ${ }^{\star}$, Thennai Mathematical Institute<br>Email: sdatta@cmi.ac.in<br>${ }^{\dagger}$ The Institute of Mathematical<br>Email: \{nutan,prajakta\}@imatik, HTW Aalen<br>$\ddagger$ Fakultät für Elektronik Emil: thomas.thierauf@uni-ulm.de<br>Email: thomas. Informatik, Universität Ulm<br>§Institut für Theoretische Informatik, Un.de

Graph Isomorphism is the prime example of a computational problem with a wide differencemplexity. There is known lower and upper boundst lower and upper bounds for a significant gap between extant be bridge the gap for this natural planar graphs as well. We bridgeresenting an upper bound and important special case b-space hardness [JKMT93]. In

The problem is clearly in NP and by a group theoretic proof also in SPP [AK06]. This is the current frontier of our knowledge as far as upper bounds go. Thould lead one give efficient algorithms for the provably hard. NP-hardness to believe that the problem is prates if GI is NP-hard then is precluded by a result that states if Ge second level the polynomial time hierarchy collapses ing is that not even [BHZ87], [Sch88]. What is more sublem. The best we know P-hardness is known for the problem. The class of problems is that GI is hard for Determinant, defined by Cook [Coo85]. is that GI is hard the determinant, defined by Costudy of iso-

## INTERMISSION

## How to efficiently generate dynamical systems, aka functional digraphs

## How to efficiently generate dynamical systems, aka functional digraphs

- In theory: Antonio E. Porreca, Ekaterina Timofeeva, Polynomial-delay generation of functional digraphs up to isomorphism, arXiv:2302.13832


## How to efficiently generate dynamical systems, aka functional digraphs

- In theory: Antonio E. Porreca, Ekaterina Timofeeva, Polynomial-delay generation of functional digraphs up to isomorphism, arXiv:2302.13832
- In practice: funkdigen2, a fast implementation of the above, github.com/aeporreca/funkdigen2


# A toy example from engineering 

## Traffic lights



# A toy example from science 

## A planetary system



## A planetary system



## Evolution in time



## Evolution in time



## Evolution in time



## Evolution in time



## Evolution in time



## Evolution in time



## Evolution in time



## Decomposing the system

## Decomposing the system

## Decomposing the system



## Decomposing the system



## Decomposing the system



## Decomposing the system



## Decomposing the system



## Decomposing the system



## Decomposing the system



## What if our instruments are less sophisticated?

# Abstract evolution of the system 



# Abstract evolution of the system 



# Product of dynamical systems 

## Product of systems



# Give temporary names to the states 


$=$

# Compute the <br> <br> Cartesian product 

 <br> <br> Cartesian product}


## Add the arcs between states



## Forget the names once again



# Products "preserve" behaviours $A$ is a minor of $A \times B$ for $B \neq \varnothing$ 





# Products "preserve" behaviours $A$ is a minor of $A \times B$ for $B \neq \varnothing$ 



# Products "preserve" behaviours $A$ is a minor of $A \times B$ for $B \neq \varnothing$ 



## Products "preserve" behaviours $A$ is a minor of $A \times B$ for $B \neq \varnothing$


more precisely: a connected $A$ is a minor of each connected component of $A \times B$ for $B \neq 0$

## Back to our

## planetary system

## Decomposition



## Decomposition



## Decomposition



## Any other decomposition?

## Another decomposition



## Another decomposition



## Another decomposition



More concretely...

## More concretely...

6 months


## More concretely...



## More concretely...

6 months



## Untangling complex systems

## Traffic lights at a crossroads



## Traffic lights at a crossroads



## Traffic lights at a crossroads



## Traffic lights at a crossroads



## Traffic lights at a crossroads



## More abstractly...


$\square$


## The operations + and $\times$ are a commutative semiring

## The operations + and $\times$ are a commutative semiring

- Commutative: $X+Y=Y+X$ and $X \times Y=Y \times X$


## The operations + and $\times$ are a commutative semiring

- Commutative: $X+Y=Y+X$ and $X \times Y=Y \times X$
- Associative: $X+(Y+Z)=(Y+X)+Z$ and $X \times(Y \times Z)=(Y \times X) \times Z$


## The operations + and $\times$ are a commutative semiring

- Commutative: $X+Y=Y+X$ and $X \times Y=Y \times X$
- Associative: $X+(Y+Z)=(Y+X)+Z$ and $X \times(Y \times Z)=(Y \times X) \times Z$
- Neutral elements: $\varnothing+X=X$ and $8 \times X=X$


## The operations + and $\times$ are a commutative semiring

- Commutative: $X+Y=Y+X$ and $X \times Y=Y \times X$
- Associative: $X+(Y+Z)=(Y+X)+Z$ and $X \times(Y \times Z)=(Y \times X) \times Z$
- Neutral elements: $\varnothing+X=X$ and $8 \times X=X$
- Distributive: $X \times(Y+Z)=X \times Y+X \times Z$


## The operations + and $\times$ are a commutative semiring

- Commutative: $X+Y=Y+X$ and $X \times Y=Y \times X$
- Associative: $X+(Y+Z)=(Y+X)+Z$ and $X \times(Y \times Z)=(Y \times X) \times Z$
- Neutral elements: $\varnothing+X=X$ and $8 \times X=X$
- Distributive: $X \times(Y+Z)=X \times Y+X \times Z$
- Multiplication by zero: $\varnothing \times X=\varnothing$


## The inspiration

The category of endomaps of sets

Conceptual Mathematics
A first introduction to categories Second Edition
F. William Lawere Stephen H. Schanuel

## Multiplication table



## Equations for

## decomposing systems

## Eqns over dynamical systems



## Eqns over dynamical systems

$$
\begin{aligned}
& \overbrace{6}^{9} X+Y^{2}={ }_{6}^{9} \\
& X=\$_{6} \\
& Y=\Omega \\
& Z=0
\end{aligned}
$$

## $\mathbb{N}$ is a subsemiring of $\mathbf{D}$

- There is an injective homomorphism $\varphi: \mathbb{N} \rightarrow \mathbf{D}$

$$
\varphi(n)=\underbrace{\mathbf{1}+\mathbf{1}+\cdots+\mathbf{1}}_{n \text { times }}=\underbrace{\bigcirc_{!}+\bigcap_{!}+\cdots+\complement_{!}}_{n \text { times }}
$$

- $n$ fixed points behave exactly as the integer $n$
- So $\mathbf{D}$ contains a isomorphic copy of $\mathbb{N}$


## Natural polynomial equations

- Let $p(X, Y)=2 X^{2}$ and $q(X, Y)=3 Y$ with $p, q \in \mathbb{N}[X, Y] \leq \mathbf{D}[X, Y]$
- Then $2 X^{2}=3 Y$ has the non-natural solution

$$
X=
$$

- But, of course, it also has the natural solution $X^{\prime}=3, Y^{\prime}=6$
- Notice how $X^{\prime}=|X|$ and $Y^{\prime}=|Y|$
- This is not a coincidence!


# The function "size" $|\cdot|: \mathbf{D} \rightarrow \mathbb{N}$ It's a semiring homomorphism 

- $|\varnothing|=0$
- $|\Omega|=1$
- Since + is the disjoint union, we have

$$
|A+B|=|A|+|B|
$$

- Since $\times$ is the cartesian product, we have

$$
|A B|=|A| \times|B|
$$

# Notation for polynomials $p \in \mathbf{D}[\vec{X}]$ 

 Of degree $\leq d$ over the variables $\vec{X}=\left(X_{1}, \ldots, X_{k}\right)$$$
\begin{aligned}
& p=\sum_{\vec{i} \in\{0, \ldots, d\}^{k}} a_{\vec{i}} \overrightarrow{X^{i}} \\
& \text { where } \quad \vec{X}^{\vec{i}}=\prod_{j=1}^{k} X_{j}^{i_{j}}
\end{aligned}
$$

## Theorem

## Solvability of natural equations

- If a polynomial equation over $\mathbb{N}\left[X_{1}, \ldots, X_{k}\right]$ has a solution in $\mathbf{D}^{k}$, then it also has a solution in $\mathbb{N}^{k}$
- In the larger semiring $\mathbf{D}$ we may find extra solutions, but only if the equation is already solvable over the naturals
- Then, by reduction from Hilbert's 10th problem, we obtain the undecidability in $\mathbf{D}$ of equations over $\mathbb{N}[\vec{X}] \ldots$
- ...and thus of arbitrary equations over $\mathbf{D}[\vec{X}]$


## Proof

Consider $p(\vec{X})=q(\vec{X})$ with $p, q \in \mathbb{N}[\vec{X}]$

$$
\sum_{\{0, \ldots, d\}^{k}} a_{\vec{i}} \vec{X}^{\vec{i}}=\sum_{i \in\{0, \ldots, d\}^{k}} b_{\vec{i}} \overrightarrow{X^{\vec{i}}}
$$

## Proof

Suppose that $\vec{A} \in \mathbf{D}^{k}$ is a solution

$$
\sum_{\{0, \ldots, d\}^{k}} a_{\vec{i}} \overrightarrow{A^{i}}=\sum_{i \in\{0, \ldots, d\}^{k}} b_{\vec{i}} \overrightarrow{A^{\vec{i}}}
$$

## Proof

Apply the size function |•|

$$
\left|\sum_{i \in\{0, \ldots, d\}^{k}} a_{\vec{i}} \vec{A} \vec{i}\right|=\left|\sum_{i \in\{0, \ldots, d\}^{k}} b_{\vec{i}} \vec{A} \vec{i}\right|
$$

## Proof

The size function $|\cdot|$ is a homomorphism

$$
\sum_{\left\{\{0, \ldots, d\}^{k}\right.}\left|a_{\vec{i}} \overrightarrow{A^{\vec{i}}}\right|=\sum_{i \in\{0, \ldots, d\}^{k}}\left|b_{\vec{i}} \overrightarrow{A^{i}}\right|
$$

## Proof

The size function $|\cdot|$ is a homomorphism


## Proof

The coefficients are natural

$$
\sum_{\{0, \ldots, d\}^{k}} a_{\vec{i}}\left|\overrightarrow{A^{i}}\right|=\sum_{i \in\{0, \ldots, d\}^{k}} b_{\vec{i}}\left|\overrightarrow{A^{i}}\right|
$$

## Proof

We have $\overrightarrow{A^{i}}=\prod_{j=1}^{k} A_{j}^{i_{j}}$


## Proof

The size function $|\cdot|$ is a homomorphism


## Proof

The size function $|\cdot|$ is a homomorphism


## Proof

So $|\vec{A}|=\left(\left|A_{1}\right|, \ldots,\left|A_{k}\right|\right)$ is also a solution, QED

$$
p\left(\left|A_{1}\right|, \ldots,\left|A_{k}\right|\right)=q\left(\left|A_{1}\right|, \ldots,\left|A_{k}\right|\right)
$$

## Bad news about solving equations !

## Bad news about solving equations !

- There is no algorithm at all for solving general equations


## 4 Bad news about

 solving equations !- There is no algorithm at all for solving general equations
- Equations without variables on one side admit an algorithm, but even linear ones of this form are NP-complete:

$$
A_{1} X_{1}+A_{2} X_{2}+\cdots+A_{n} X_{n}=B
$$

## 4. Bad news about

## solving equations !

- There is no algorithm at all for solving general equations
- Equations without variables on one side admit an algorithm, but even linear ones of this form are NP-complete:

$$
A_{1} X_{1}+A_{2} X_{2}+\cdots+A_{n} X_{n}=B
$$

- We are still unsure if equations in one single variable, like $A X=B$, can be solved efficiently (conjecture: no)


# Reducibility of dynamical systems 

## Most dynamical systems are irreducible

- Formally:

- Notice that this is the opposite of $\mathbb{N}$, where irreducible (aka prime) integers are scarce


## No unique factorisation into irreducibles!







## Multiple factorisations


$\times$




## Multiple factorisations





## Multiple factorisations



Prime systems

## Prime systems

- A prime is a system $P$ such that, whenever it appears in a factorisation into irreducibles of $A \times B$, it appears in the factorisation of either $A$ or $B$


## Prime systems

- A prime is a system $P$ such that, whenever it appears in a factorisation into irreducibles of $A \times B$, it appears in the factorisation of either $A$ or $B$
- In other words, if $P$ divides $A \times B$ then it divides $A$ or $B$


## Prime systems

- A prime is a system $P$ such that, whenever it appears in a factorisation into irreducibles of $A \times B$, it appears in the factorisation of either $A$ or $B$
- In other words, if $P$ divides $A \times B$ then it divides $A$ or $B$
- If a prime appears in one factorisation of a system, then it appears in all the others as well (it is irreplaceable)


## An example of nonprime



## Finding primes

## Finding primes

- We haven't been able to find even a single prime yet!


## Finding primes

- We haven't been able to find even a single prime yet!
- We have found infinitely many non-primes though


## Finding primes

- We haven't been able to find even a single prime yet!
- We have found infinitely many non-primes though
- This guy here? it is not prime


## Finding primes

- We haven't been able to find even a single prime yet!
- We have found infinitely many non-primes though
- This guy here? it is not prime
- A counterexample to the primality of $P$ is two systems $A, B$ such that $P$ divides $A \times B$ but neither $A$ nor $B$


## Finding primes

- We haven't been able to find even a single prime yet!
- We have found infinitely many non-primes though
- This guy here? it is not prime It took us two years to find out that
- A counterexample to the primality of $P$ is two systems $A, B$ such that $P$ divides $A \times B$ but neither $A$ nor $B$
- Those $A$ and $B$ can be bigger than $P$, but we don't know how much, so no algorithm yet...


## What do primes look like, if they exist at all?

## What do primes look like, if they exist at all?



## What do primes look like, if they exist at all?

- Connected



## What do primes look like, if they exist at all?

- Connected
- Fixed point (no cycles of length >1)



## What do primes look like, if they exist at all?

- Connected
- Fixed point (no cycles of length > 1)
- gcd of the number of predecessors across all states must be 1



## Future developments

## Future developments

- Find more solvable equations, and at least one class of equations that is solvable efficiently


## Future developments

- Find more solvable equations, and at least one class of equations that is solvable efficiently
- How many solutions for a given equation?
E.g., $A X=B$ has at most one if $X$ is connected (recent result by É. Naquin and M. Gadouleau)


## Future developments

- Find more solvable equations, and at least one class of equations that is solvable efficiently
- How many solutions for a given equation?
E.g., $A X=B$ has at most one if $X$ is connected (recent result by É. Naquin and M. Gadouleau)
- Find out if prime systems exist, or at least find a primality algorithm!


## Bibliography

- A. Dennunzio, V. Dorigatti, E. Formenti, L. Manzoni, A.E. Porreca, Polynomial equations over finite, discrete-time dynamical systems
- F. Doré, E. Formenti, A.E. Porreca, S. Riva, Algorithmic reconstruction of discrete dynamics (and its bibliography)
- É. Naquin, M. Gadouleau, Factorisation in the semiring of finite dynamical systems
- A.E. Porreca, E. Timofeeva, Polynomial-delay generation of functional digraphs up to isomorphism


# Thanks for your attention! Merci de votre attention! 

 Any questions?