

Composing behaviours in the semiring of dynamical systems

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- Luca Manzoni (Università degli Studi di Trieste )
- Antonio E. Porreca (Aix-Marseille Université & LIS )

Finite dynamical systems and their category

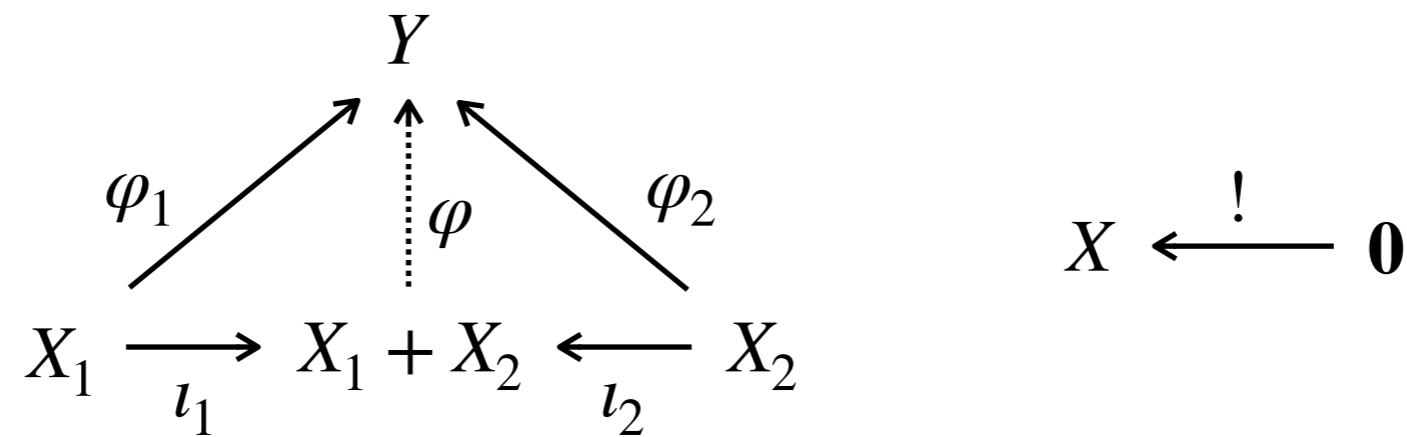
Finite dynamical systems

- A **finite dynamical system** is just a finite set X with a transition function $f: X \rightarrow X$
- The **category \mathbf{D}** of finite dynamical systems has
 - as **objects**, the dynamical systems (X, f) themselves
 - as **arrows** between (X, f) and (Y, g) , the functions $\varphi: X \rightarrow Y$ that make the diagram commute:

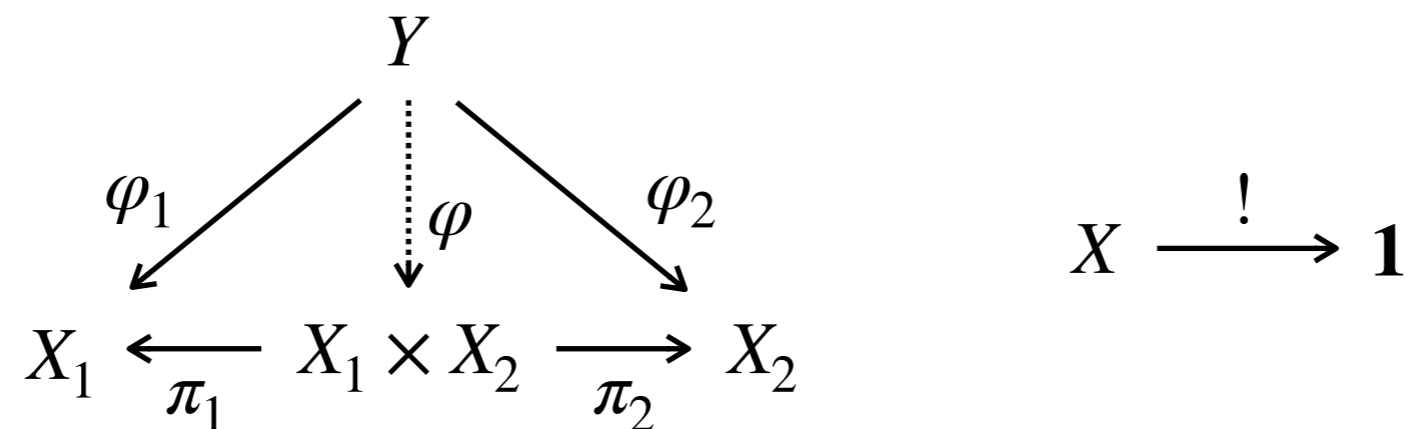
$$\begin{array}{ccc} X & \xrightarrow{f} & X \\ \varphi \downarrow & & \downarrow \varphi \\ Y & \xrightarrow{g} & Y \end{array}$$

The category \mathbf{D} of finite dynamical systems

- Has **sums** (coproducts) and **initial objects**

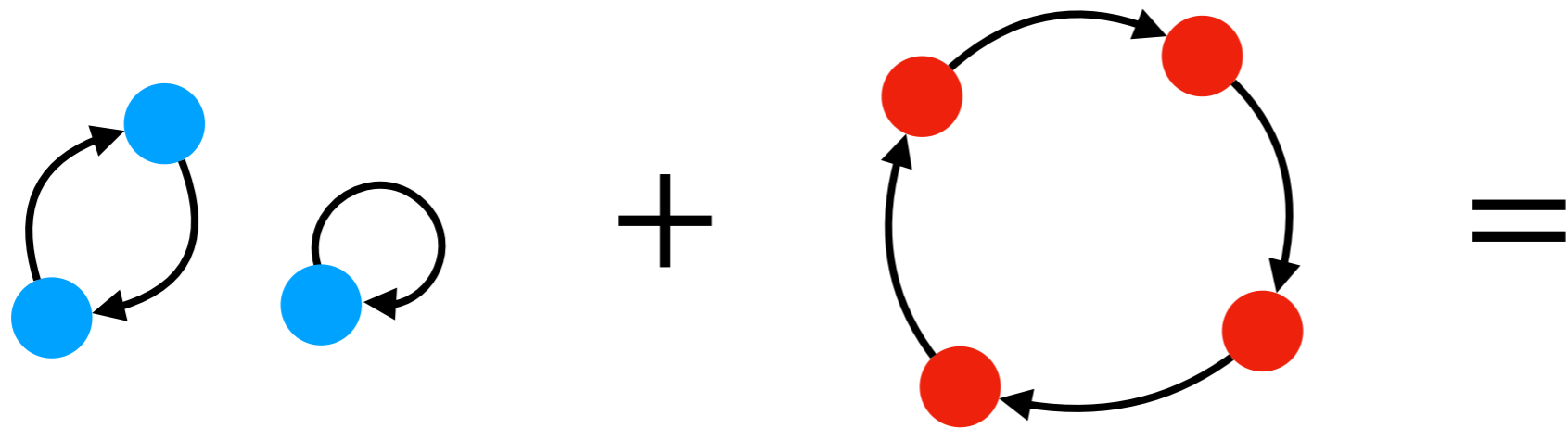


- Has **products** and **terminal objects**

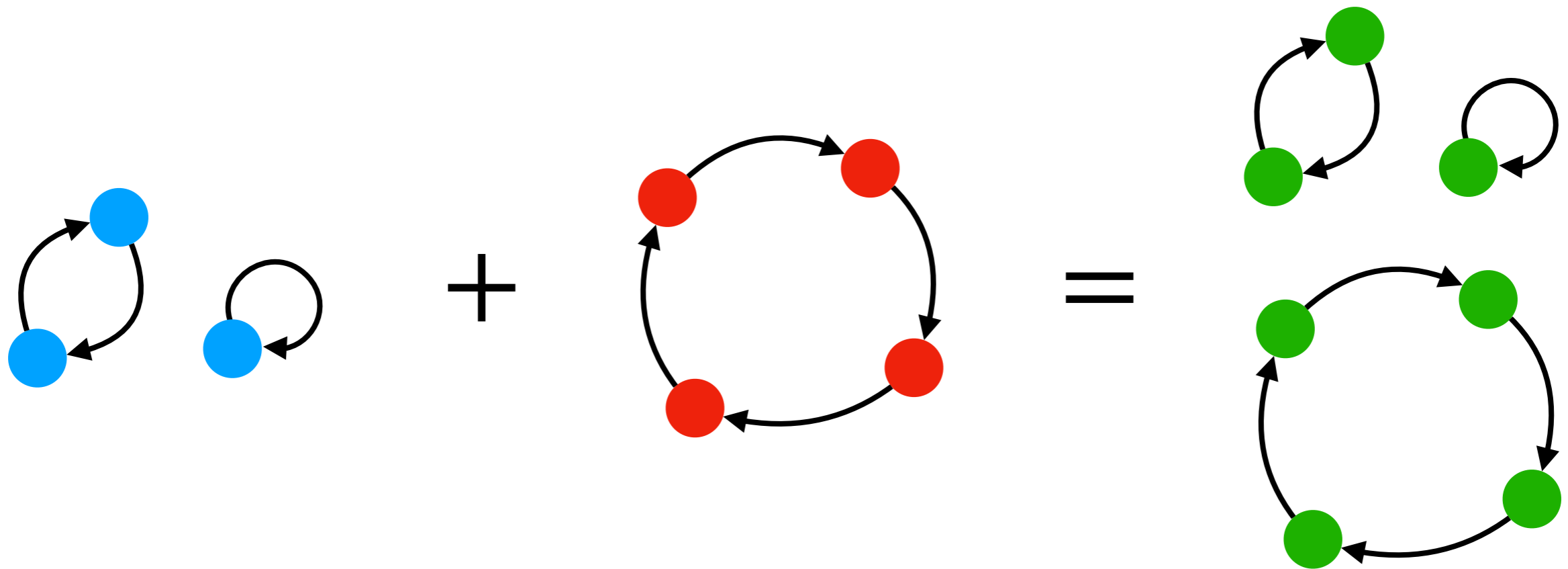


More concretely...

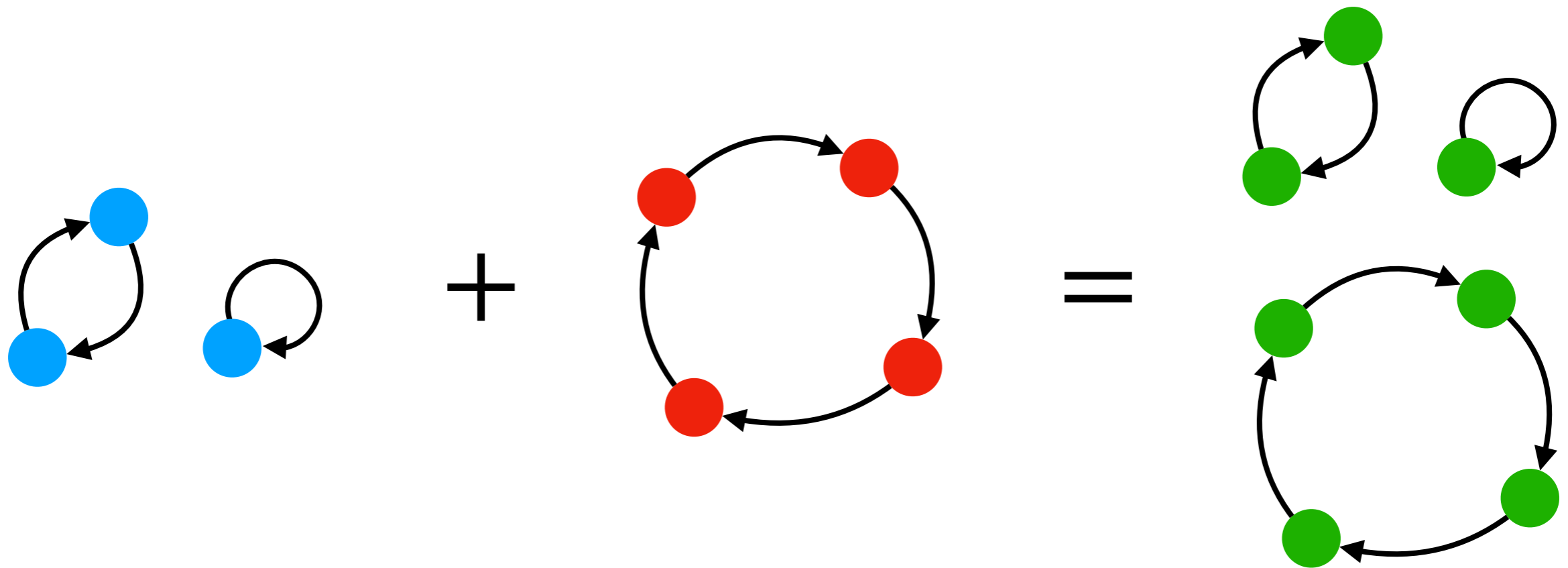
Sum in \mathbf{D} = disjoint union



Sum in \mathbf{D} = disjoint union

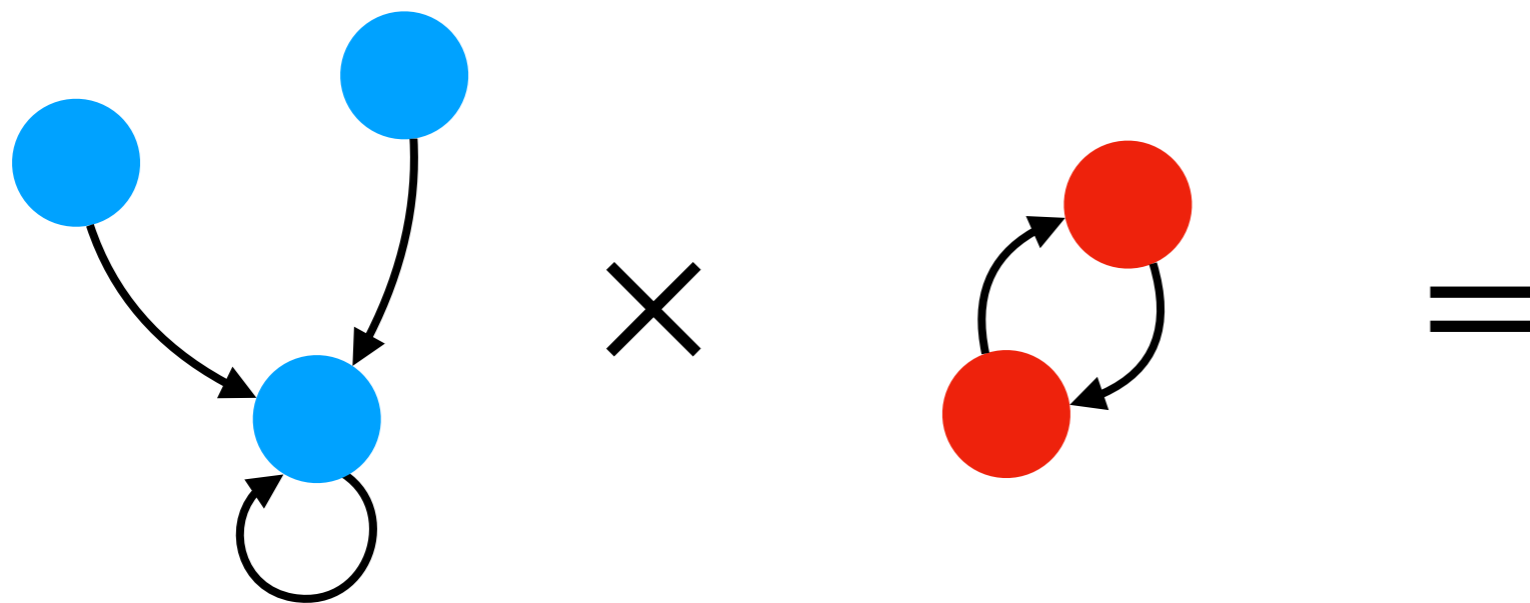


Sum in \mathbf{D} = disjoint union

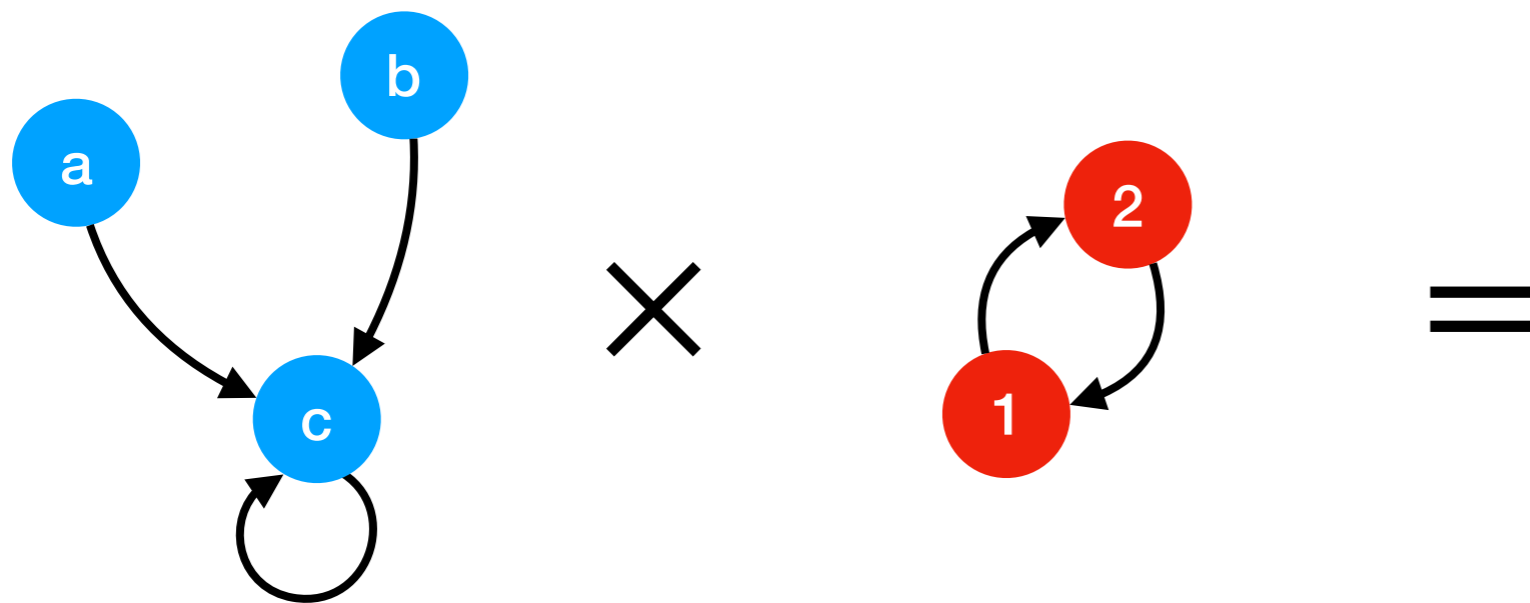


identity = $\mathbf{0}$ = \emptyset , the empty dynamical system

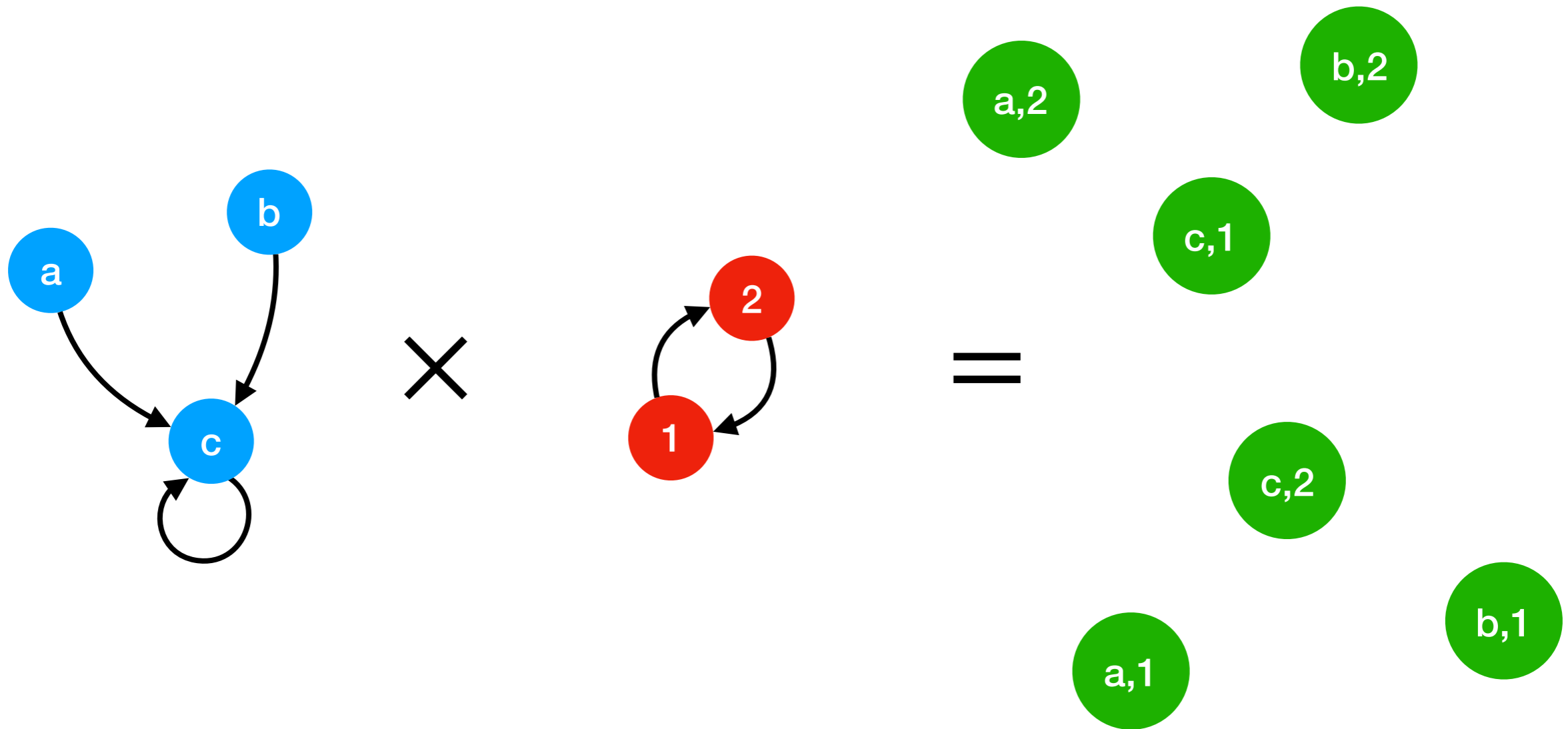
Product in $\mathbf{D} =$ cartesian product



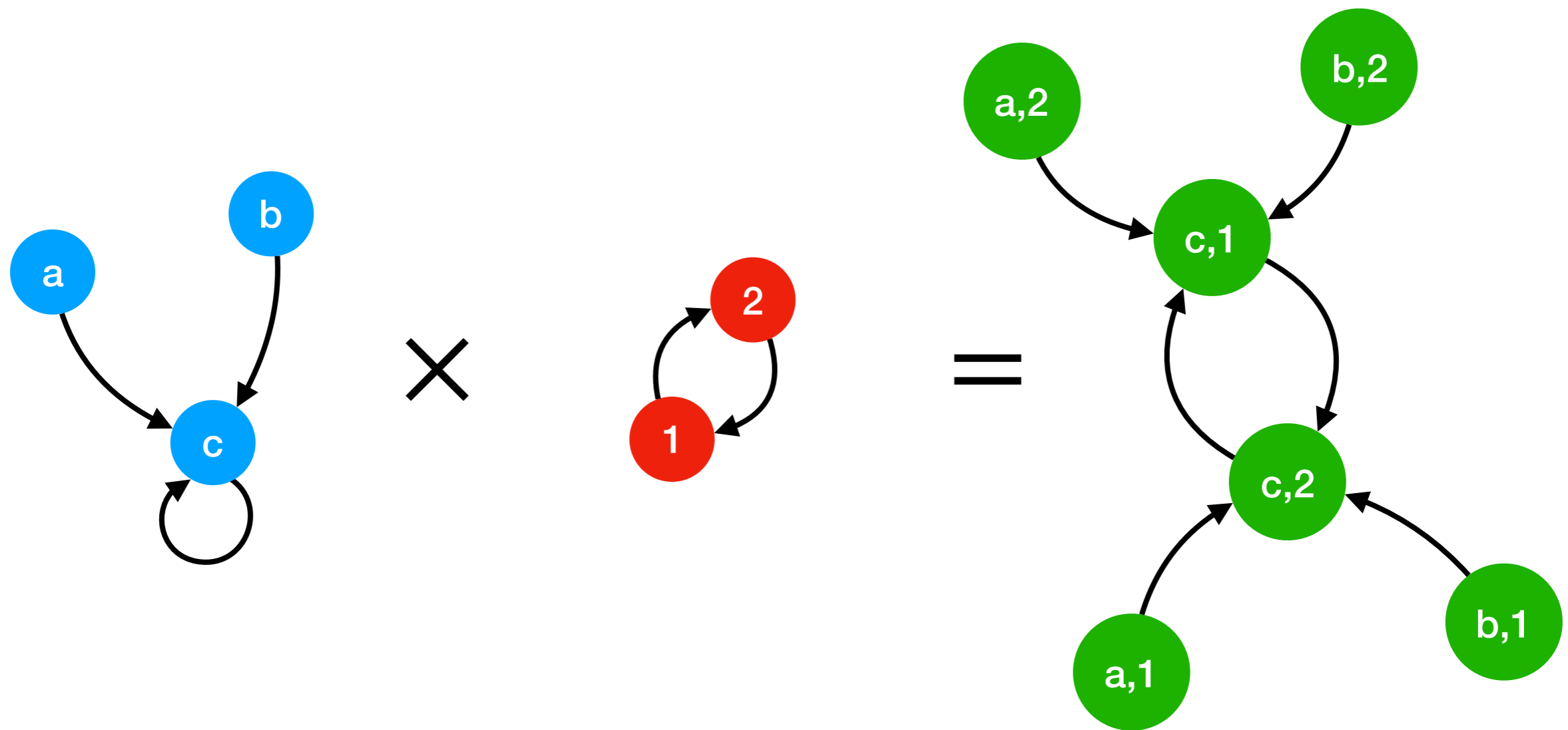
Product in $\mathbf{D} =$ cartesian product



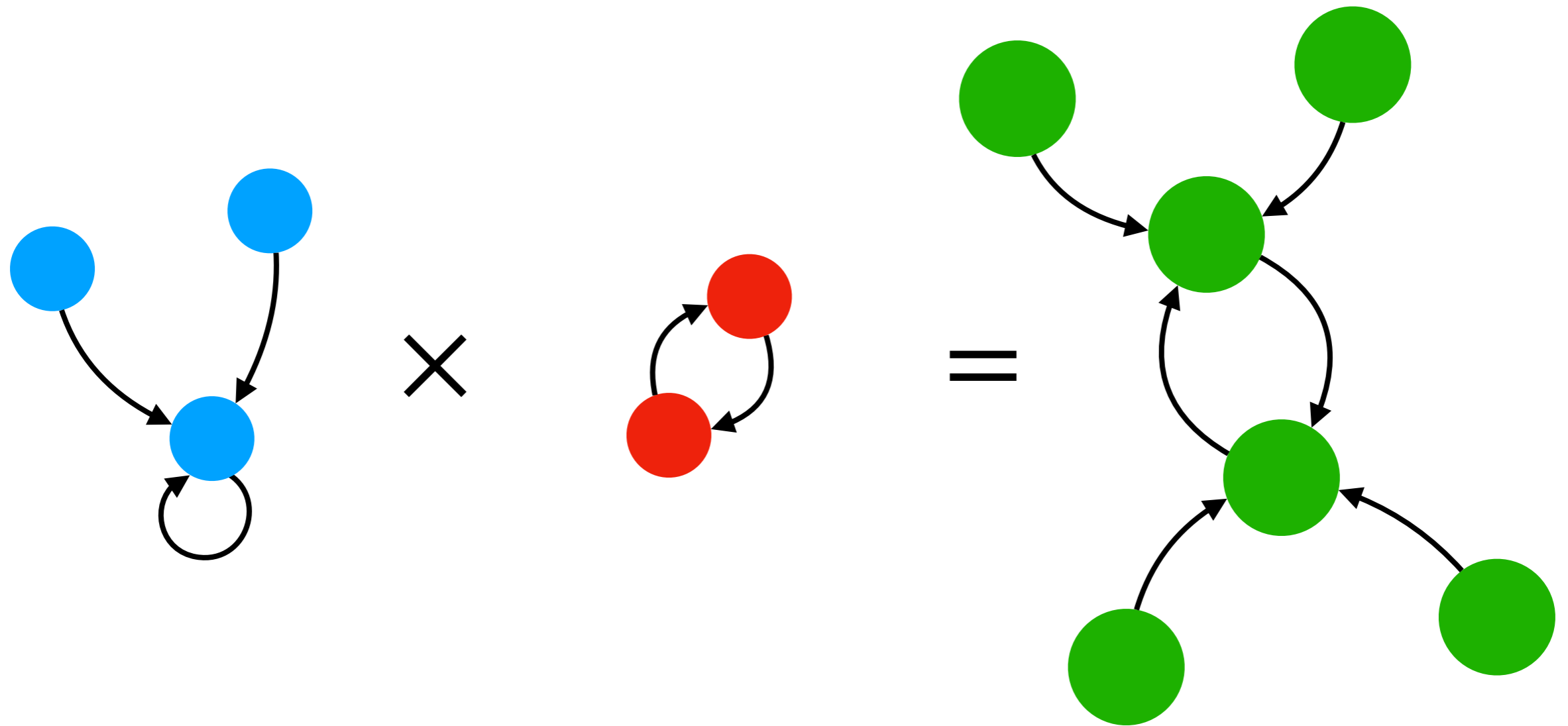
Product in $\mathbf{D} =$ cartesian product



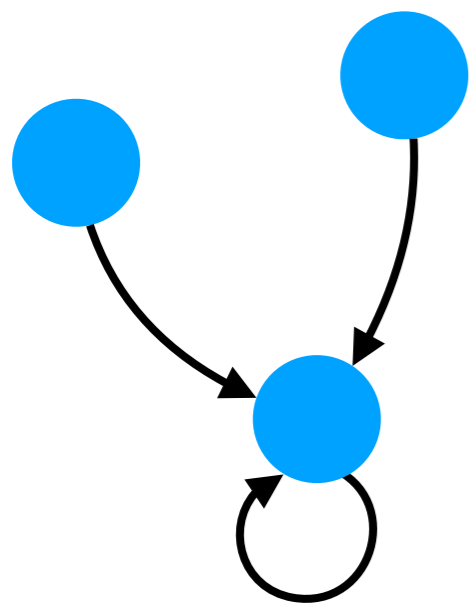
Product in $\mathbf{D} =$ cartesian product



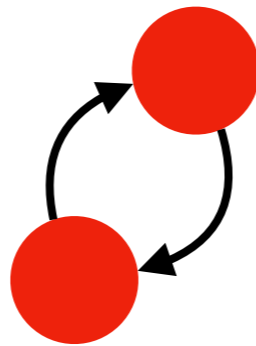
Product in $\mathbf{D} =$ cartesian product



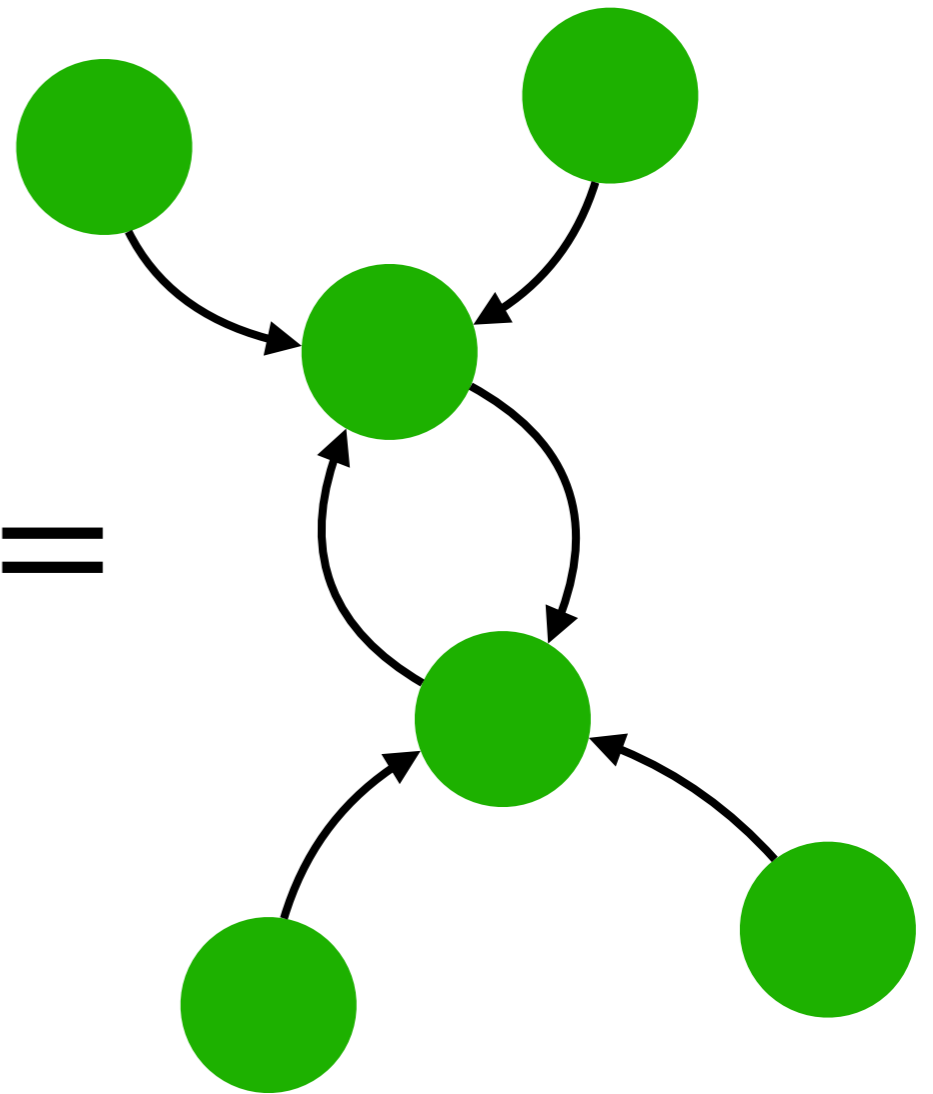
Product in $\mathbf{D} =$ cartesian product




\times



$=$





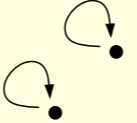

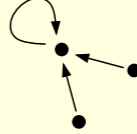
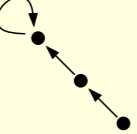



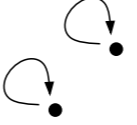

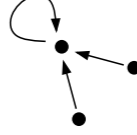
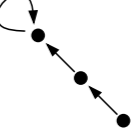
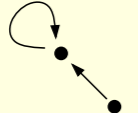
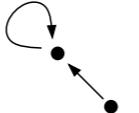
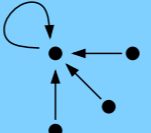
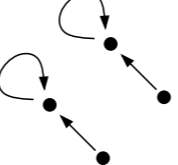
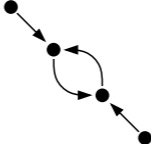
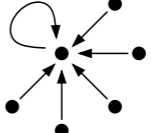
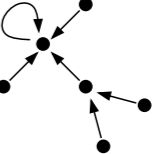
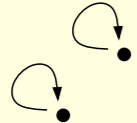
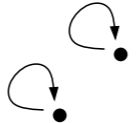
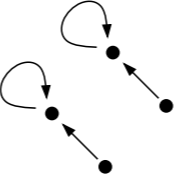
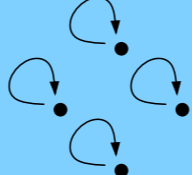
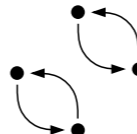
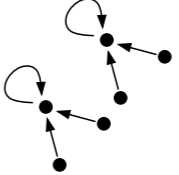
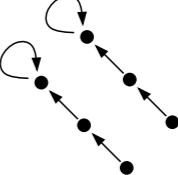


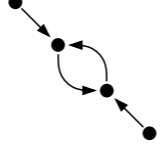
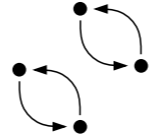
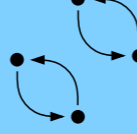
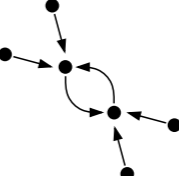
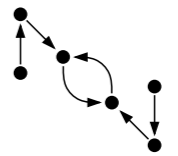
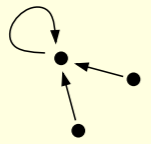
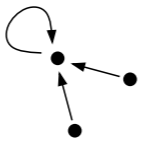
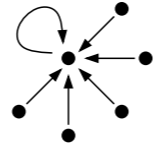
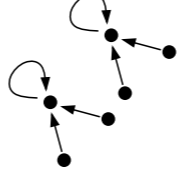
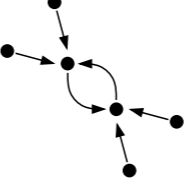
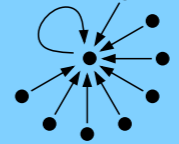
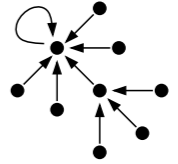
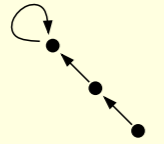
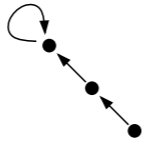
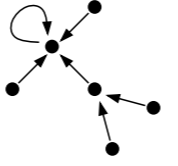
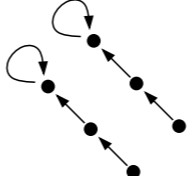
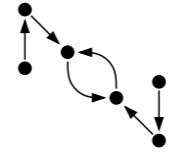
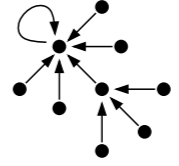
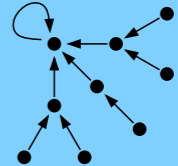
identity = $\mathbf{1}$ = 

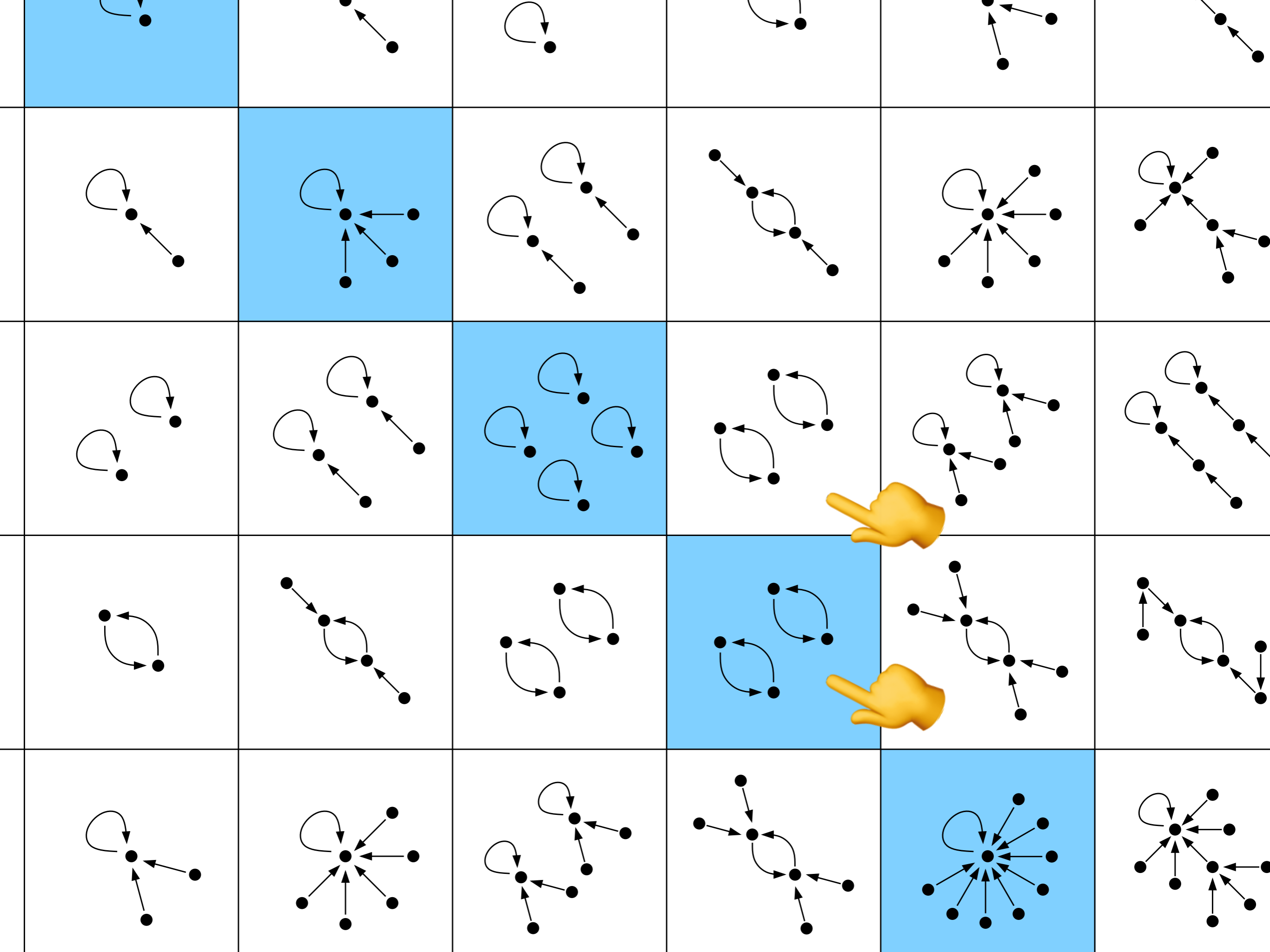
The semiring of finite dynamical systems

The semiring $(\mathbf{D}, +, \times)$

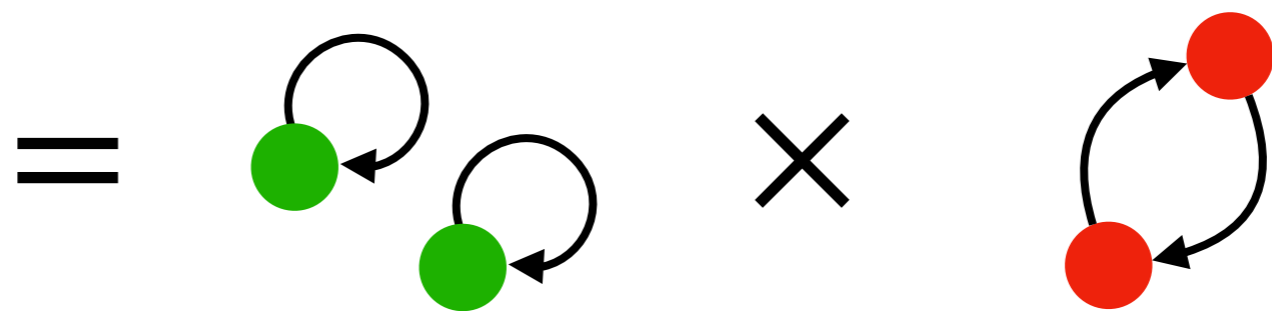
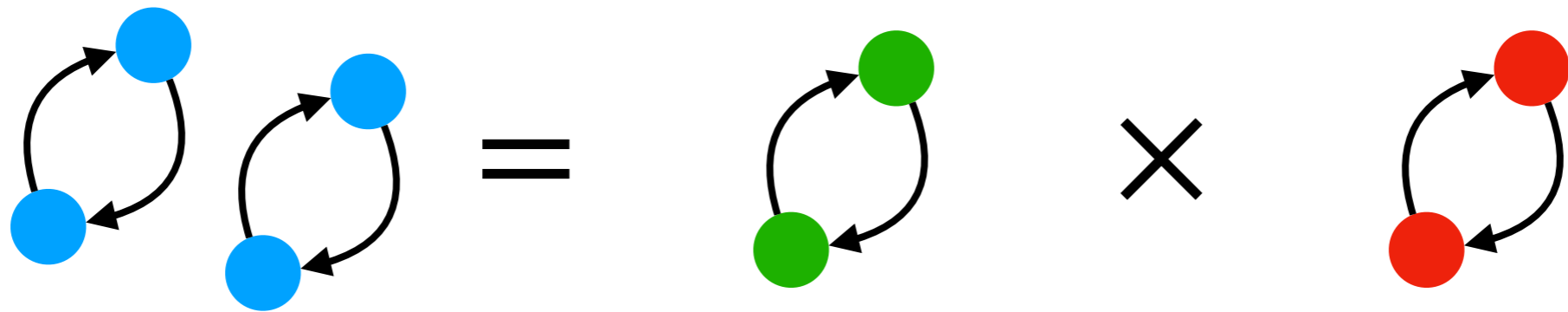
- The finite dynamical system **modulo isomorphism** are an infinite set \mathbf{D} which is a **commutative semiring**:
 - $(\mathbf{D}, +)$ is a commutative monoid with identity $\mathbf{0} = \emptyset$
 - (\mathbf{D}, \times) is a commutative monoid with identity $\mathbf{1} = \text{blue dot with self-loop}$
 - Distributivity: $x(y + z) = xy + xz$
 - Absorption: $\mathbf{0}x = \mathbf{0}$
- This semiring is not a ring, because **there are no additive inverses**

Multiplication table of \mathbf{D}

\times	\emptyset						
\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset
	\emptyset						
	\emptyset						
	\emptyset						
	\emptyset						
	\emptyset						
	\emptyset						



! No unique factorisation into irreducible elements! !

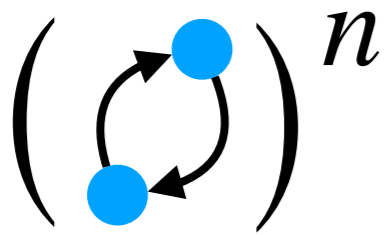


Theorem (Gadouleau)

For each n , there exist a dynamical system with at least n factorisations

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For each n , there exist a dynamical system with at least n factorisations

$$\left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^n = \begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \times \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^{n-1}$$

The diagram illustrates the factorization of a cycle of n blue nodes into a cycle of 2 green nodes and a cycle of $n-1$ red nodes. The left side shows a cycle of n blue nodes, represented by two blue nodes with arrows forming a cycle, enclosed in large parentheses with a superscript n . This is equal to a cycle of 2 green nodes (two green nodes with arrows forming a cycle) multiplied by a cycle of $n-1$ red nodes (two red nodes with arrows forming a cycle, enclosed in large parentheses with a superscript $n-1$).

Theorem (Gadouleau)

For each n , there exist a dynamical system with at least n factorisations

$$\begin{aligned} \left(\begin{array}{c} \bullet \\ \circlearrowleft \\ \bullet \end{array} \right)^n &= \begin{array}{c} \bullet \\ \circlearrowleft \\ \bullet \end{array} \times \left(\begin{array}{c} \bullet \\ \circlearrowleft \\ \bullet \end{array} \right)^{n-1} \\ &= \left(\begin{array}{c} \bullet \\ \circlearrowleft \\ \bullet \end{array} \right)^2 \times \left(\begin{array}{c} \bullet \\ \circlearrowleft \\ \bullet \end{array} \right)^{n-2} \end{aligned}$$

Theorem (Gadouleau)

For each n , there exist a dynamical system with at least n factorisations

$$\begin{aligned} \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^n &= \begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \times \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^{n-1} \\ &= \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^2 \times \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^{n-2} \\ &= \dots = \left(\begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \right)^{n-1} \times \begin{array}{c} \bullet \\ \curvearrowright \\ \bullet \end{array} \end{aligned}$$

The **majority**
of dynamical systems
is irreducible:

$$\lim_{n \rightarrow \infty} \frac{\text{reducible dyn sys over } n \text{ points}}{\text{total dyn sys over } n \text{ points}} = 0$$

Proof idea (Dorigatti)

- It is a simple combinatorial argument
- There are exponentially many dynamical systems (modulo isomorphism) over n points, asymptotically cd^n / \sqrt{n} with $c \approx 0.4$ and $d \approx 3 \dots$
- ...and “not enough” products in the upper-left corner of the multiplication table, so the majority must be irreducible

**The semiring D contains the
natural numbers \mathbb{N}
as a subsemiring**

A **monomorphism** $\mathbb{N} \rightarrow \mathbf{D}$

$$\varphi(n) = \underbrace{\begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \dots + \begin{array}{c} \circlearrowleft \\ \bullet \end{array}}_{n \text{ times}}$$

A **mono**morphism $\mathbb{N} \rightarrow \mathbf{D}$

$$\varphi(n) = \underbrace{\begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \dots + \begin{array}{c} \circlearrowleft \\ \bullet \end{array}}_{n \text{ times}}$$

$$0 \mapsto \emptyset$$

$$1 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

$$2 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

$$3 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

A **mono**morphism $\mathbb{N} \rightarrow \mathbf{D}$

$$\varphi(n) = \underbrace{\begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \begin{array}{c} \circlearrowleft \\ \bullet \end{array} + \cdots + \begin{array}{c} \circlearrowleft \\ \bullet \end{array}}_{n \text{ times}}$$

$$0 \mapsto \emptyset$$

$$\varphi(0) = \mathbf{0}$$

$$1 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

$$\varphi(1) = \mathbf{1}$$

$$2 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

$$\varphi(x + y) = \varphi(x) + \varphi(y)$$

$$3 \mapsto \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array} \begin{array}{c} \circlearrowleft \\ \bullet \end{array}$$

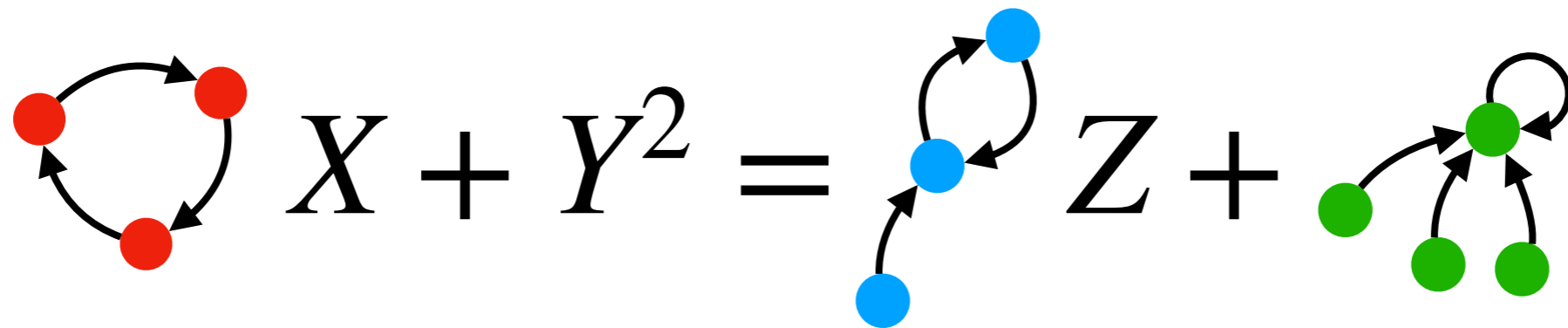
$$\varphi(xy) = \varphi(x) \times \varphi(y)$$

Some subsemirings of \mathbf{D}

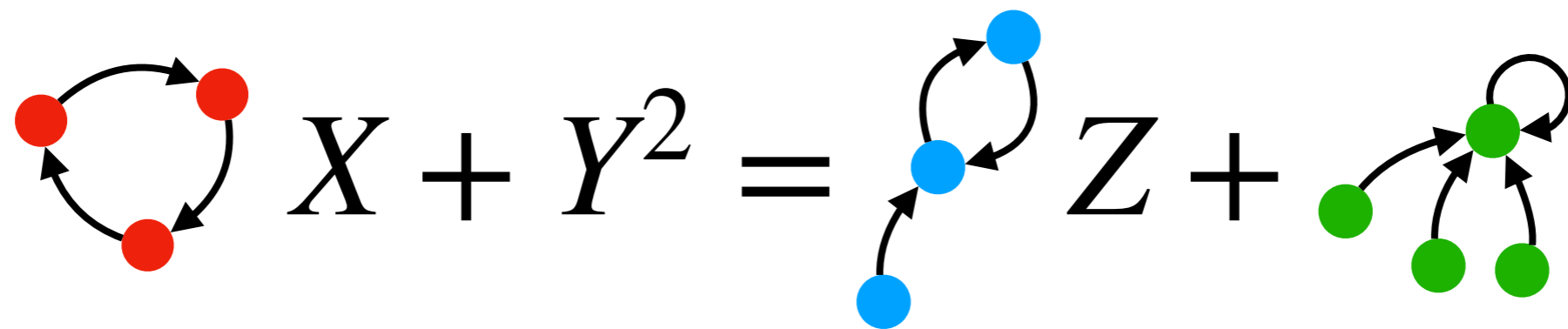
- The **natural numbers** \mathbb{N}
- The bijections, aka dynamics only containing cycles (including fixed points), aka asymptotic behaviours of dynamical systems
- Dynamical systems without limit cycles of length > 1

Polynomial equations over $\mathbf{D}[X_1, \dots, X_m]$

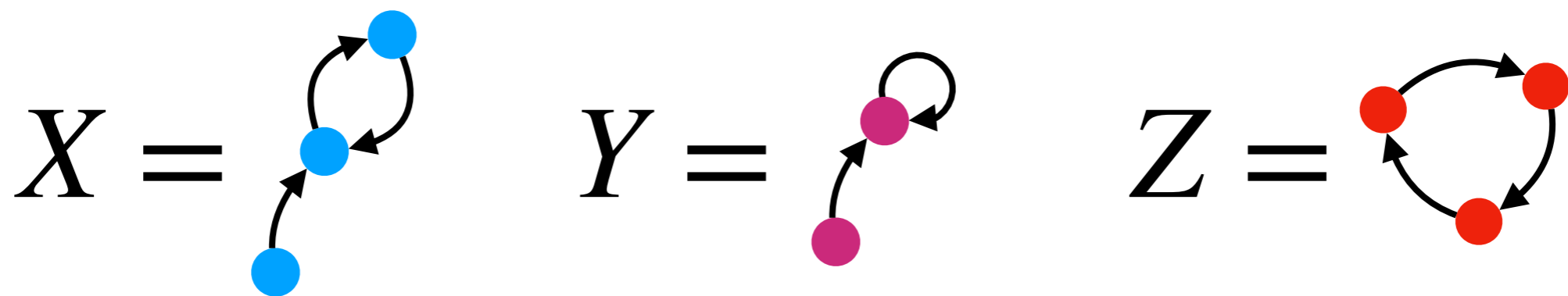
Polynomial equations for the analysis of complex behaviours



Polynomial equations for the analysis of complex behaviours



one solution:



Polynomial equations in semirings vs rings

- A ring has additive inverses (aka, it has subtraction)
- So each polynomial equation in a ring can be written as $p(\vec{X}) = 0$
- This is **not** the case for our semiring, which has no subtraction
- So the general polynomial equation has the form $p(\vec{X}) = q(\vec{X})$ with **two** polynomials $p, q \in \mathbf{D}[\vec{X}]$

**Solvability
of polynomial equations
over D is undecidable**

Polynomial equations over \mathbb{D} are undecidable

- By reduction from the unsolvability of diophantine equations over \mathbb{N} (**Hilbert's 10th problem**)
- **Not an immediate consequence** of having a subsemiring isomorphic to \mathbb{N}
- For example, the solvability of polynomial equations over \mathbb{R} is decidable, even trivial over \mathbb{C} , even if they contain \mathbb{N}

Natural equations with non-natural solutions

- Let $p(X, Y) = 2X^2 = \begin{matrix} \bullet \\ \curvearrowright \\ \bullet \end{matrix} X^2$, $q(X, Y) = 3Y = \begin{matrix} \bullet \\ \curvearrowright \\ \bullet \\ \curvearrowright \\ \bullet \end{matrix} Y$
- Then $2X^2 = 3Y$ has the non-natural solution $X = \begin{matrix} \bullet \\ \curvearrowright \\ \bullet \\ \curvearrowright \\ \bullet \end{matrix}$, $Y = 2 \begin{matrix} \bullet \\ \curvearrowright \\ \bullet \end{matrix}$
- But it also has a **natural** solution, namely $X = 3$, $Y = 6$
- The natural solution is the size of the dynamical systems of the non-natural one
- This is **not a coincidence!**

The function “size” $|\cdot|: \mathbf{D} \rightarrow \mathbb{N}$ is a semiring homomorphism

- $|\emptyset| = 0$
- $|\circlearrowleft| = 1$
- Since $+$ is the disjoint union, $|x + y| = |x| + |y|$
- Since \times is the cartesian product, $|xy| = |x| \times |y|$

Notation for polynomials $p \in \mathbf{D}[\vec{X}]$
of degree $\leq d$ with $\vec{X} = (X_1, \dots, X_k)$

$$p = \sum_{\vec{i} \in \{0, \dots, d\}^k} a_{\vec{i}} \vec{X}^{\vec{i}}$$

where $\vec{X}^{\vec{i}} = \prod_{j=1}^k X_j^{i_j}$

Solvability of polynomial equations with **natural** coefficients

Theorem

- If a polynomial equation over $\mathbb{N}[X_1, \dots, X_k]$ has a solution in \mathbf{D}^k , then it also has a solution in \mathbb{N}^k
- That is, in the largest semiring \mathbf{D} we may **find extra solutions** to natural polynomial equations, but **only if there is already a natural one**

Proof

- Let $p(\vec{X}) = q(\vec{X})$ with $p, q \in \mathbb{N}[\vec{X}]$ and suppose $p(\vec{D}) = q(\vec{D})$ for some $\vec{D} \in \mathbf{D}^k$:

$$\sum_{i \in \{0, \dots, d\}^k} a_{\vec{i}} \vec{D}^{\vec{i}} = \sum_{i \in \{0, \dots, d\}^k} b_{\vec{i}} \vec{D}^{\vec{i}}$$

- Apply the size function $|\cdot|$, which is a homomorphism:

$$\left| \sum_{i \in \{0, \dots, d\}^k} a_{\vec{i}} \vec{D}^{\vec{i}} \right| = \left| \sum_{i \in \{0, \dots, d\}^k} b_{\vec{i}} \vec{D}^{\vec{i}} \right| \Rightarrow \sum_{i \in \{0, \dots, d\}^k} a_{\vec{i}} |\vec{D}^{\vec{i}}| = \sum_{i \in \{0, \dots, d\}^k} b_{\vec{i}} |\vec{D}^{\vec{i}}|$$

- where $|\vec{D}^{\vec{i}}| = \prod_{j=1}^k |D_j|^{i_j}$; notice that $|a_{\vec{i}}| = a_{\vec{i}}$ and $|b_{\vec{i}}| = b_{\vec{i}}$ since they are \mathbb{N}

- But that means $p(|\vec{D}|) = q(|\vec{D}|)$ where $|\vec{D}| = (|D_1|, \dots, |D_k|)$,
so $|\vec{D}|$ is a natural solution

Unsolvability of polynomial equations in $\mathbf{D}[\vec{X}]$

- A polynomial equation **with natural coefficients** has a solutions over the dynamical systems **if and only** if it has a natural solution
- Being able to solve polynomial equations over $\mathbf{D}[\vec{X}]$ would then contradict the unsolvability of Hilbert's 10th problem

Equations with non-natural coefficients

- Notice that equations with **non-natural coefficients** might have only non-natural solutions
- For instance

$$X^2 = Y + \text{⌚}$$

- has the non-natural solution $X = \text{⌚}$, $Y = 2 \text{⌚}$ but no natural solutions

**Polynomial equations with
constant RHS are in NP**

Nondeterministic algorithm for

$$p(\vec{X}) = D \text{ with } D \in \mathbf{D}$$

- Since $+$ and \times are monotonic wrt the sizes of the operands, each X_i in a solution to the equation has size $\leq |D|$
- So it suffices to guess a dynamical system of size $\leq |D|$ for each variable in polynomial time, then calculate LHS
- Finally we check whether LHS and RHS are isomorphic, exploiting the fact that graph isomorphism is in **NP**
- Only one **caveat**: if at any time during the calculations the LHS becomes larger than $|D|$, we halt and reject (otherwise the algorithm might take exponential time)

Solvability of a **systems** of
linear equations with constant
RHS is **NP**-complete

Systems of linear equations are NP-complete

- In **NP** by the same algorithm as above, only with multiple equations
- **NP**-hard by reduction from the **NP**-complete problem
One-in-three-3SAT: given a 3CNF formula φ , is there a satisfying assignment such that exactly one literal per clause is true?
- For each variable x in φ we have an equation $x + x' = 1$, forcing exactly one variable between x and x' to be 0 and the other to be 1
- For each clause, for instance $(x \vee \neg y \vee z)$, we have an equation, for instance $x + y' + z = 1$, which forces the solution to be a satisfying assignment with one true literal per clause

**Solvability of an equation of
unbounded degree with
constant RHS is NP-complete**

Reducing n equations with RHS = 1 to a single equation

- We multiply the LHS and RHS of the linear equations of the **One-in-three-3SAT** reduction:

$$\begin{cases} p_1(\vec{X}) = 1 \\ \vdots \\ p_m(\vec{X}) = 1 \end{cases} \iff p_1(\vec{X}) \times \cdots \times p_m(\vec{X}) = 1$$

- The new equation has the same solutions of the old one:
each $p_i(\vec{X})$ must be 1
- Thus, solving equations of unbounded degree with constant RHS is **NP**-complete

Is a **single** linear equation NP-complete?

- Over a ring that is also an **integral domain** (no nonzero elements a, b such that $ab = 0$), we can always have 0 as RHS and reduce a system to a single equation:

$$\begin{cases} p_1(\vec{X}) = 0 \\ \vdots \\ p_m(\vec{X}) = 0 \end{cases} \iff p_1(\vec{X}) \times \cdots \times p_m(\vec{X}) = 0$$

- We cannot do that in our semiring \mathbf{D} due to the lack of subtraction, even if there are no nontrivial zero divisors

Reducing a system of linear equations to a single one (Bridoux)

- Possible solution: given the system of linear equations

$$\begin{cases} p_1(\vec{X}) = q_1(\vec{X}) \\ \vdots \\ p_m(\vec{X}) = q_m(\vec{X}) \end{cases}$$

- find “linearly independent” elements $e_1, \dots, e_m \in \mathbf{D}$ such that the equation

$$e_1 p_1(\vec{X}) + \dots + e_m p_m(\vec{X}) = e_1 q_1(\vec{X}) + \dots + e_m q_m(\vec{X})$$

- ...has the same solutions of the original system
- Conjecture: it is possible to find the “linearly independent” $e_1, \dots, e_m \in \mathbf{D}$

**Open problems and
work in progress**

Open problems & WIP 1

- Find subclasses of polynomial equations that are solvable in **polynomial time**, or that are solvable but **harder than NP**
- Find an **NP**-complete equation problem which does not depend on the **NP**-completeness of the **same problem over the naturals**
 - (Bridoux) Transforming a system of equations into a single equation having the same solutions (nontrivial over semirings)
- Conjecture (Gadouveau): there is a polynomial-time algorithm for computing $\sqrt[n]{x}$ when it exists

Open problems & WIP 2

- Is finding a factorisation **NP**-hard?
- (Gadouleau) Counting factorisations
- More detailed **algebraic analysis** of the semiring **D**
(find other subsemirings? ideals? generators? primes?)
- Conjecture (Guilhem Gamard @ LIS): maybe we can find an interpretation for category-theoretical **exponentiation** in **D**

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¡Gracias por su atención!

¡Thanks for your attention!