Fixed points and attractors of reaction systems

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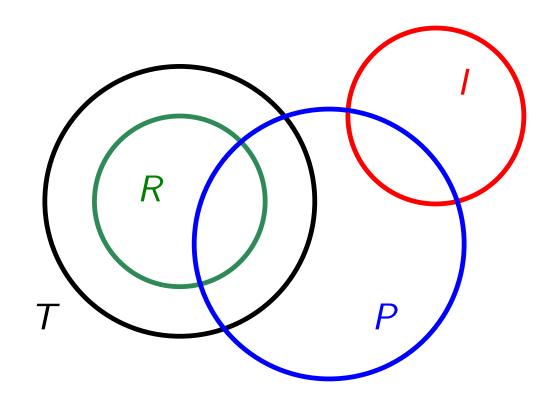
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Reactions

$$a = (R, I, P) \qquad \in 2^{S} \times 2^{S} \times 2^{S}$$
$$\operatorname{res}_{a}(T) = \begin{cases} P & \text{if } R \subseteq T \text{ and } I \cap T = \emptyset \\ \emptyset & \text{otherwise} \end{cases}$$

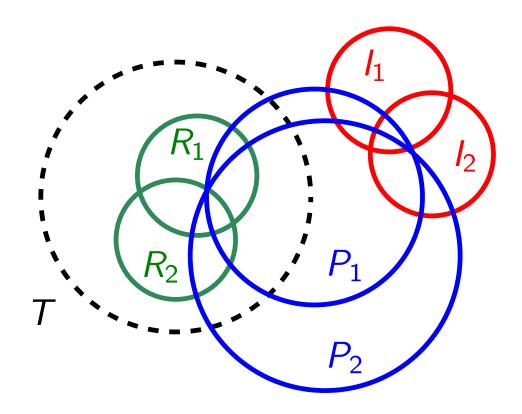


Reaction systems

 $\mathcal{A} = (S, A)$

 $\operatorname{res}_{\mathcal{A}}(T) = \bigcup \{\operatorname{res}_{a}(T) : a \in A\}$

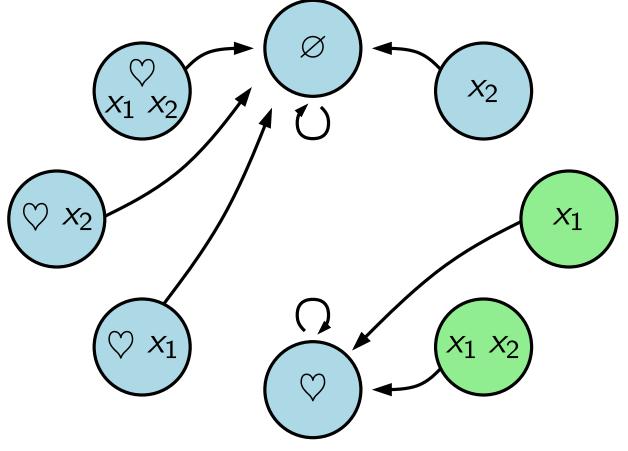
no multiplicities no competition no permanence



An example: evaluating DNF formulae

$$\varphi \equiv (x_1 \land \neg x_2) \lor (x_1 \land x_2)$$

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(\operatorname{pos}(\varphi_j), \operatorname{neg}(\varphi_j) \cup \{\heartsuit\}, \{\heartsuit\})(\{\heartsuit\}, \{x_i\}, \{\heartsuit\})
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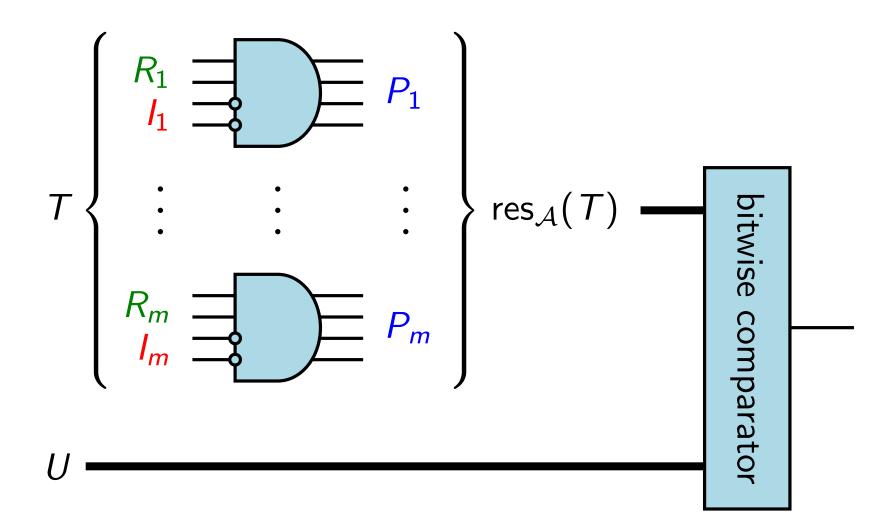
Dynamics of reaction systems

$\mathcal{A} = (S, A) \implies (\operatorname{res}_{\mathcal{A}}^{t}(T))_{t \in \mathbf{N}}$

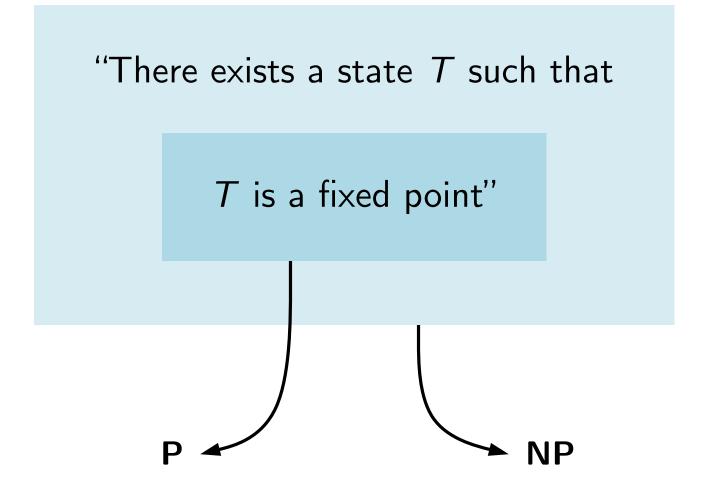
Questions (biologically inspired):

- Is T a fixed point?
- Does \mathcal{A} have fixed points?
- Similarity of ${\mathcal A}$ and ${\mathcal B}$ wrt fixed points
- Does \mathcal{A} have (local) fixed point attractors?
- Similarity of ${\mathcal A}$ and ${\mathcal B}$ wrt fixed point attractors

Computing res_A and "fixedness" $\in AC^0$ (FO-uniform)

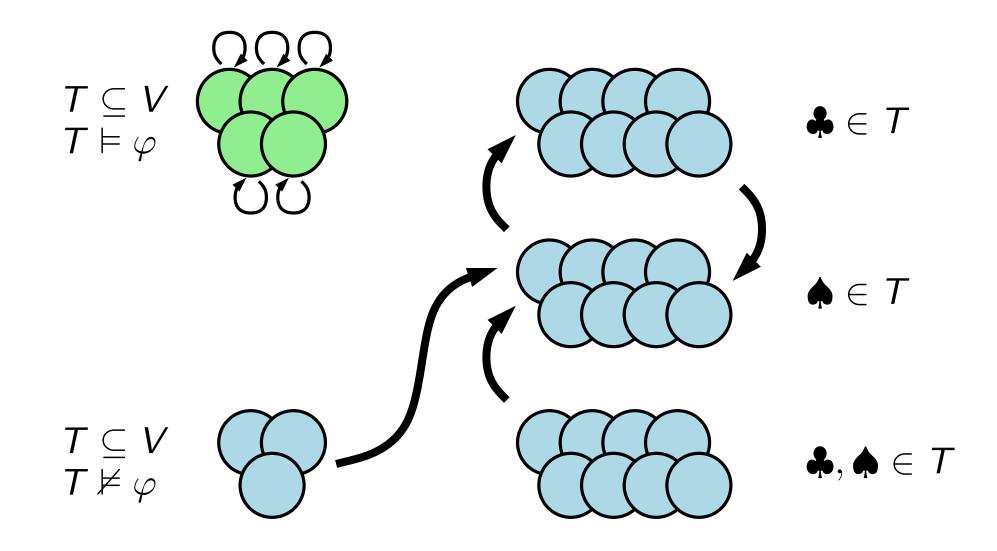


Existence of fixed points $\in \mathbf{NP}$

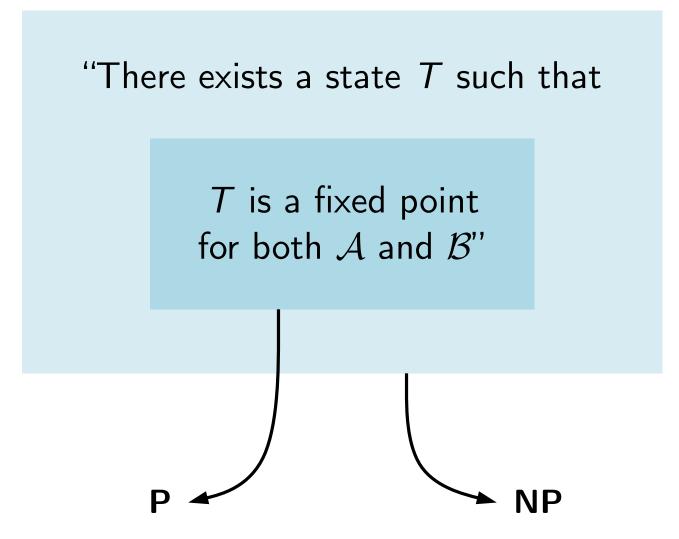


Existence of fixed points is NP-hard

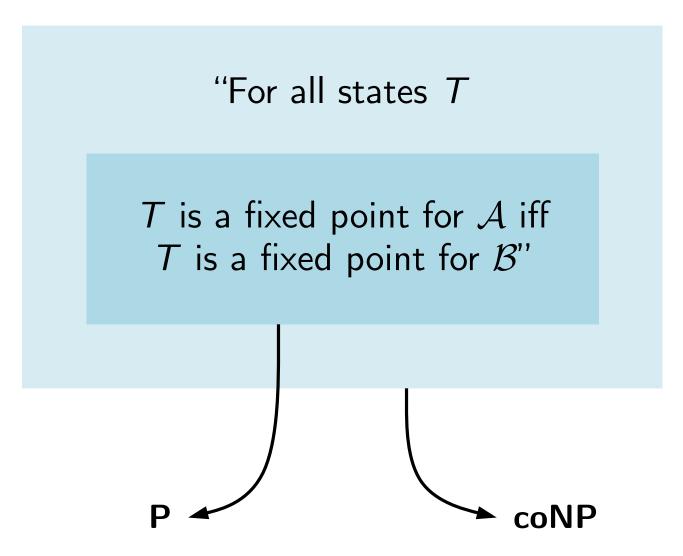
CNF formula $\exists V \varphi$



Existence of shared fixed points is NP-complete

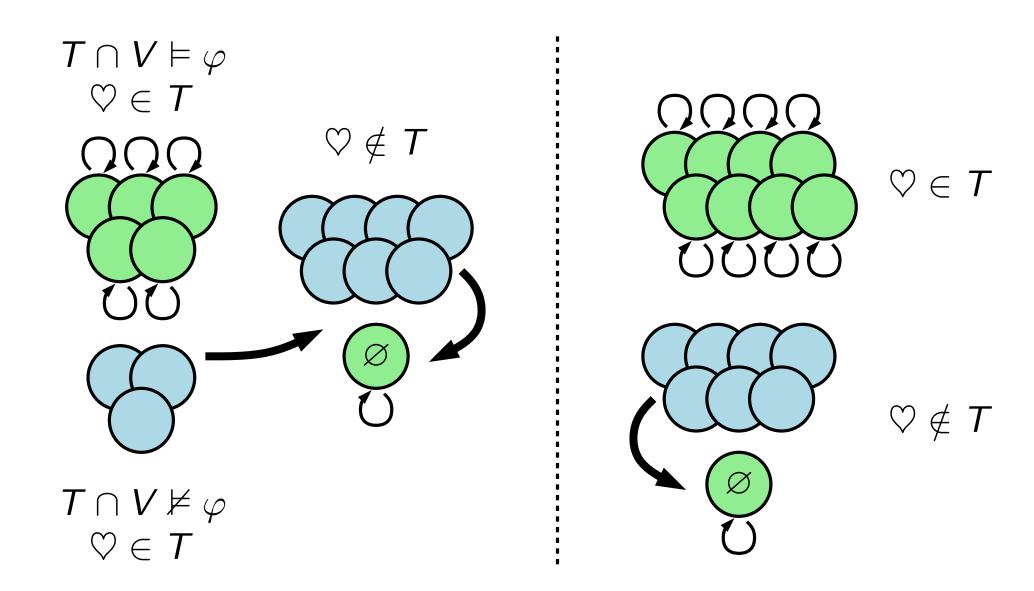


All fixed points are shared $\in \mathbf{coNP}$

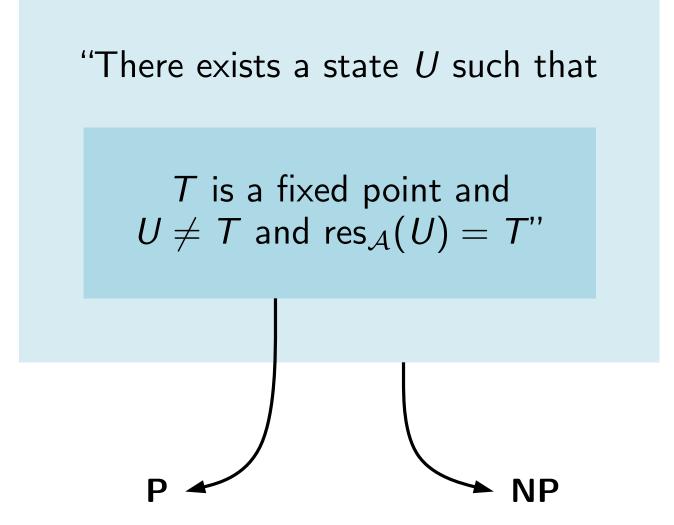


All fixed points are shared is coNP-hard

DNF formula $\forall V \varphi$

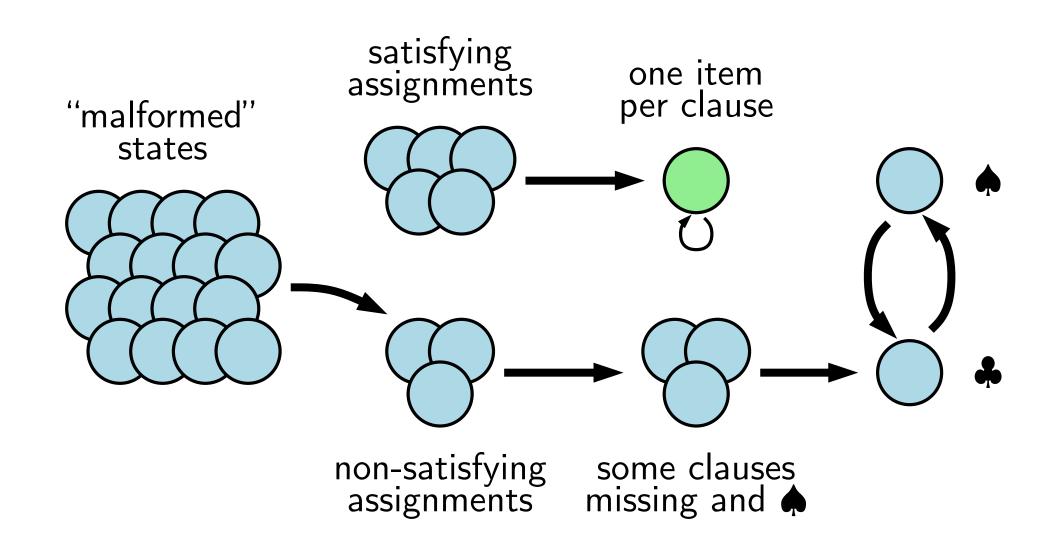


Is T a fixed point attractor? $\in NP$



Is T a fixed point attractor? is NP-hard

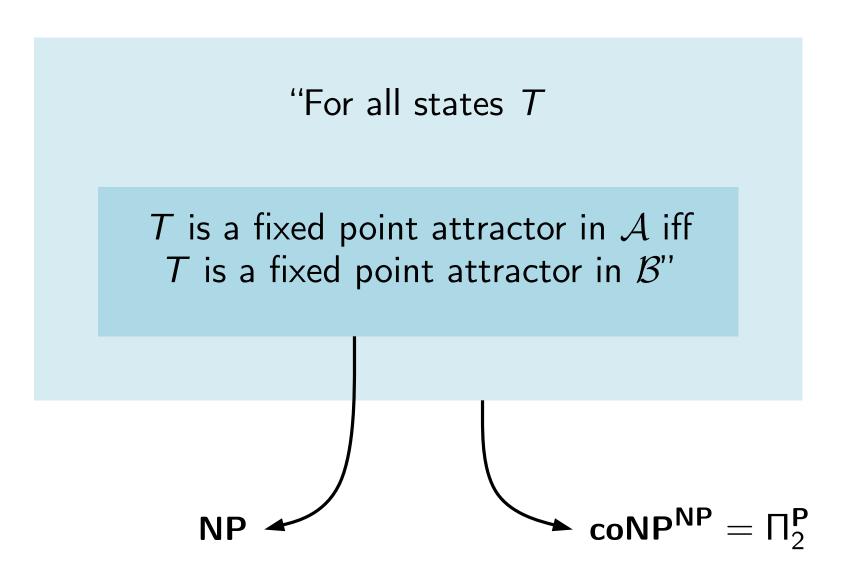
CNF formula $\exists V \varphi$



Other problems about fixed point attractors

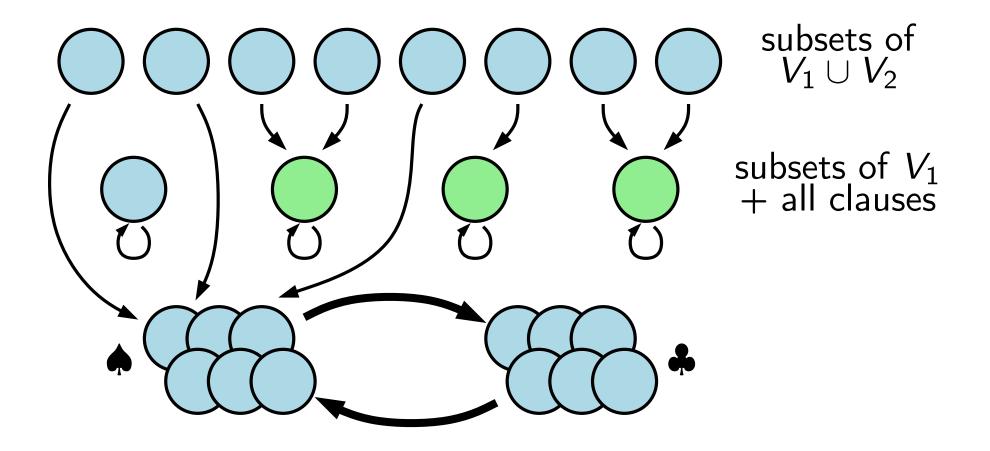
Has \mathcal{A} got a fixed point attractor? **NP**-complete Do \mathcal{A} and \mathcal{B} share a fixed point attractor? **NP**-complete

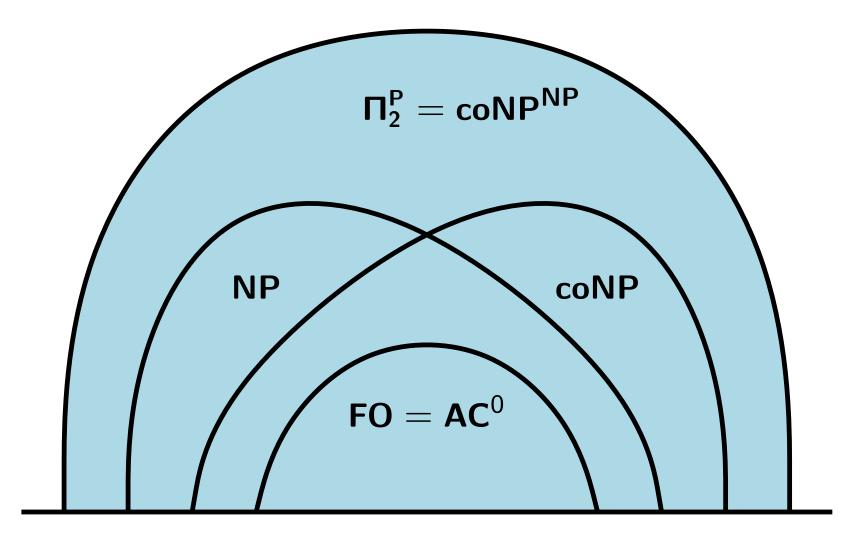
All fixed point attractors are shared $\in \Pi_2^{\mathbf{P}} = \mathbf{coNP}^{\mathbf{NP}}$

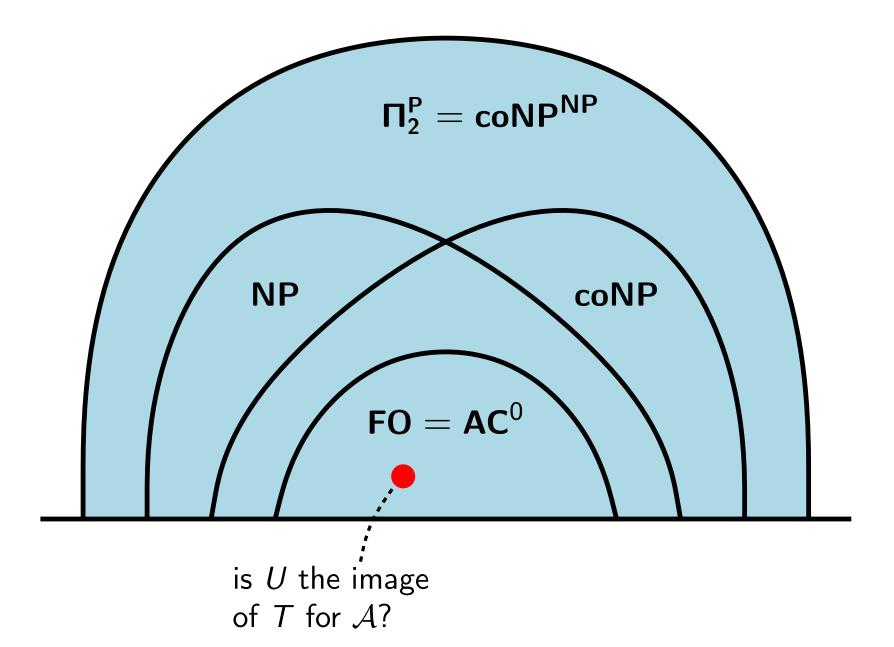


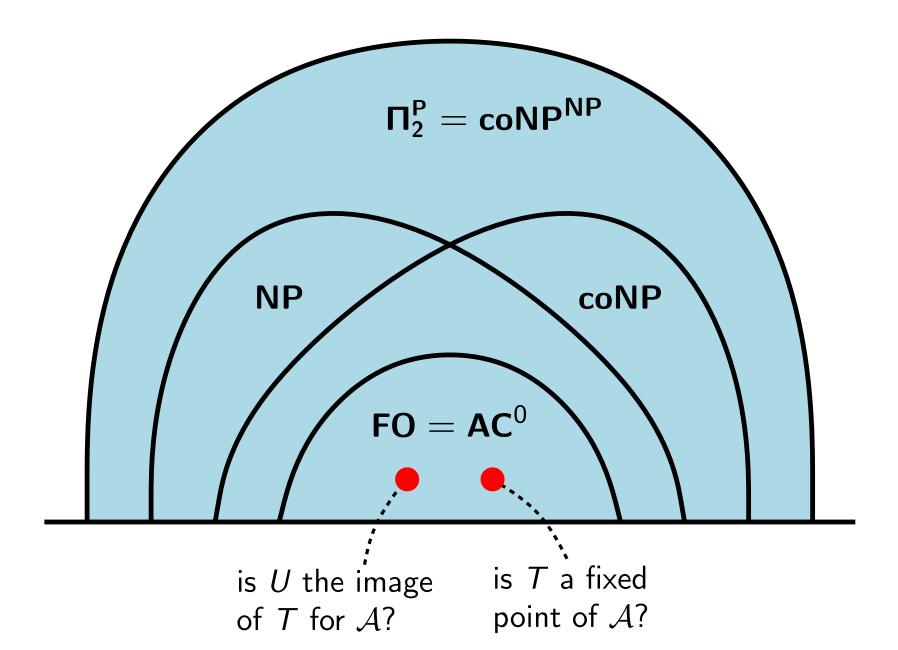
All fixed point attractors are shared is $\Pi_2^{\mathbf{P}}$ -complete

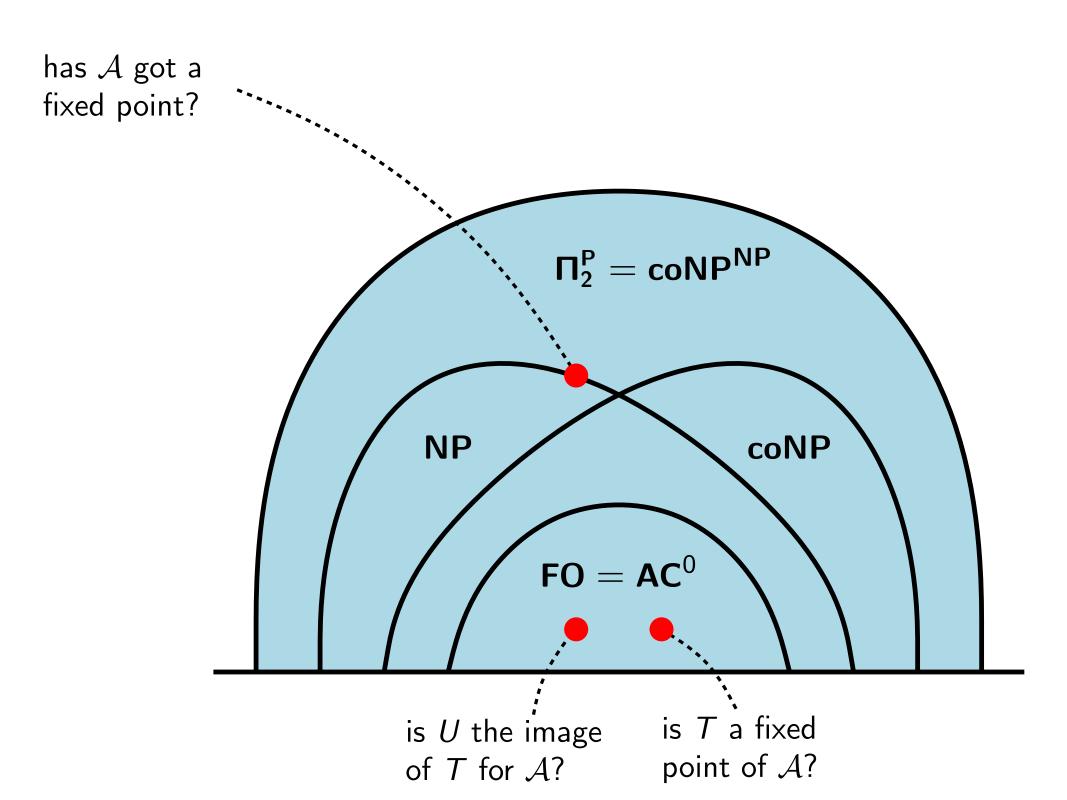
CNF formula $\forall V_1 \exists V_2 \varphi$

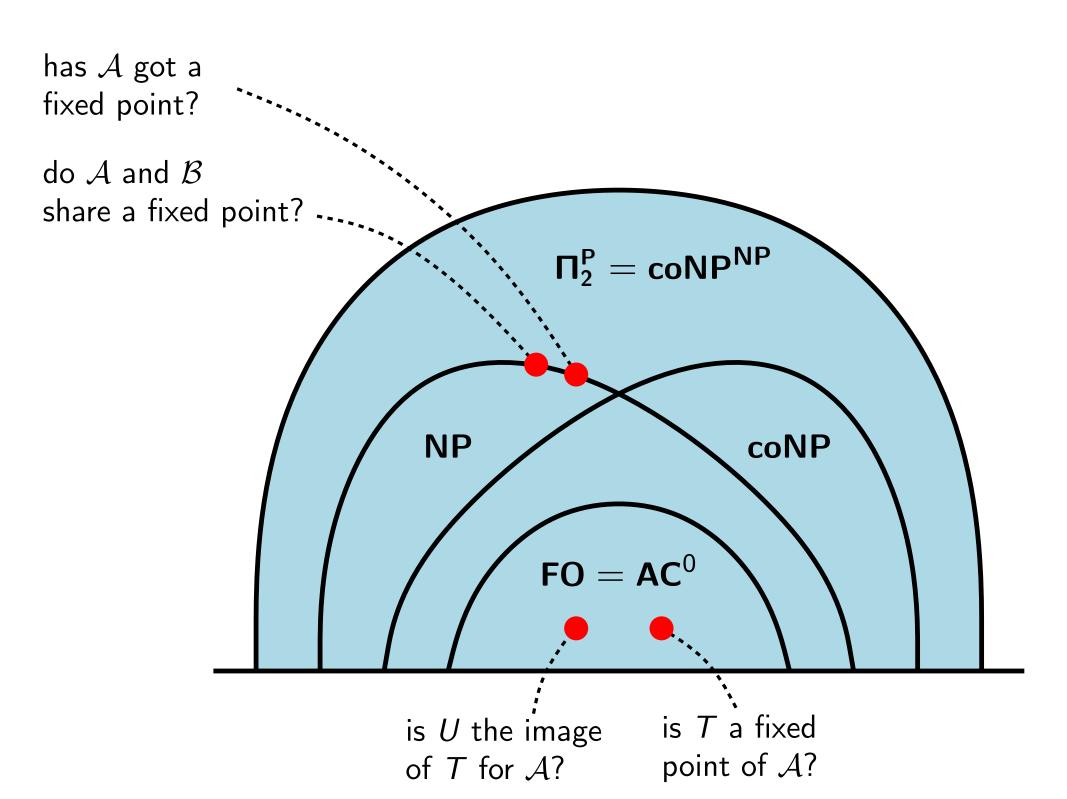


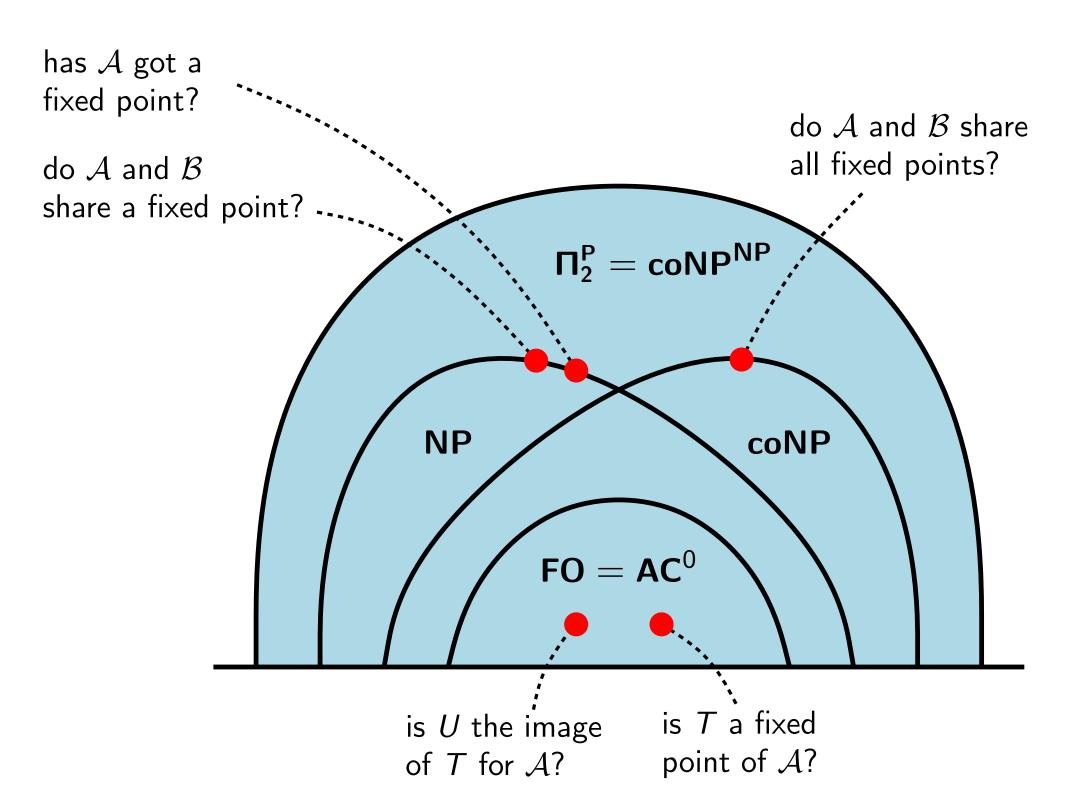


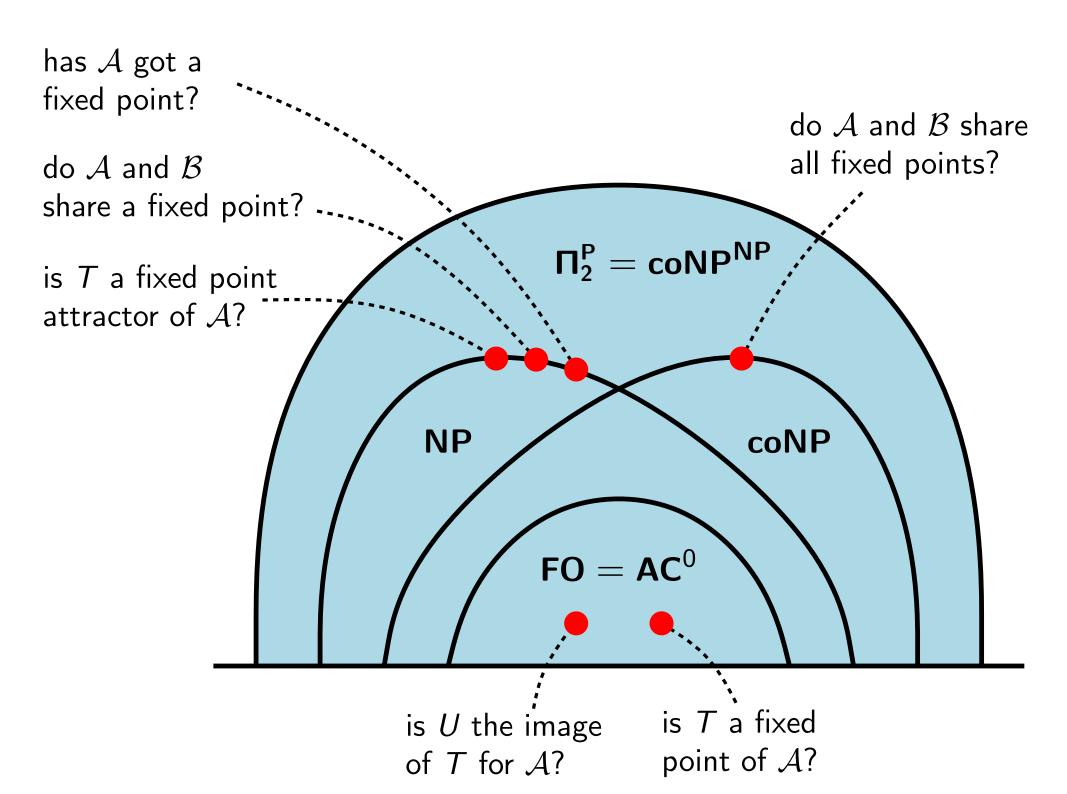


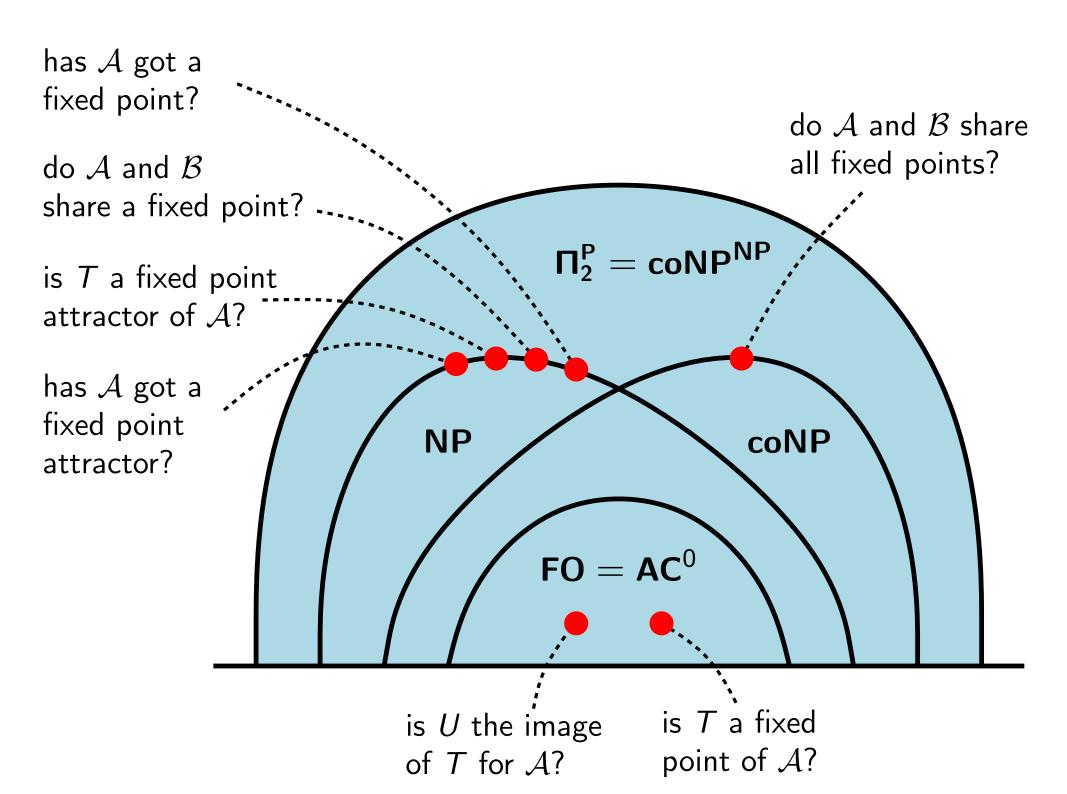


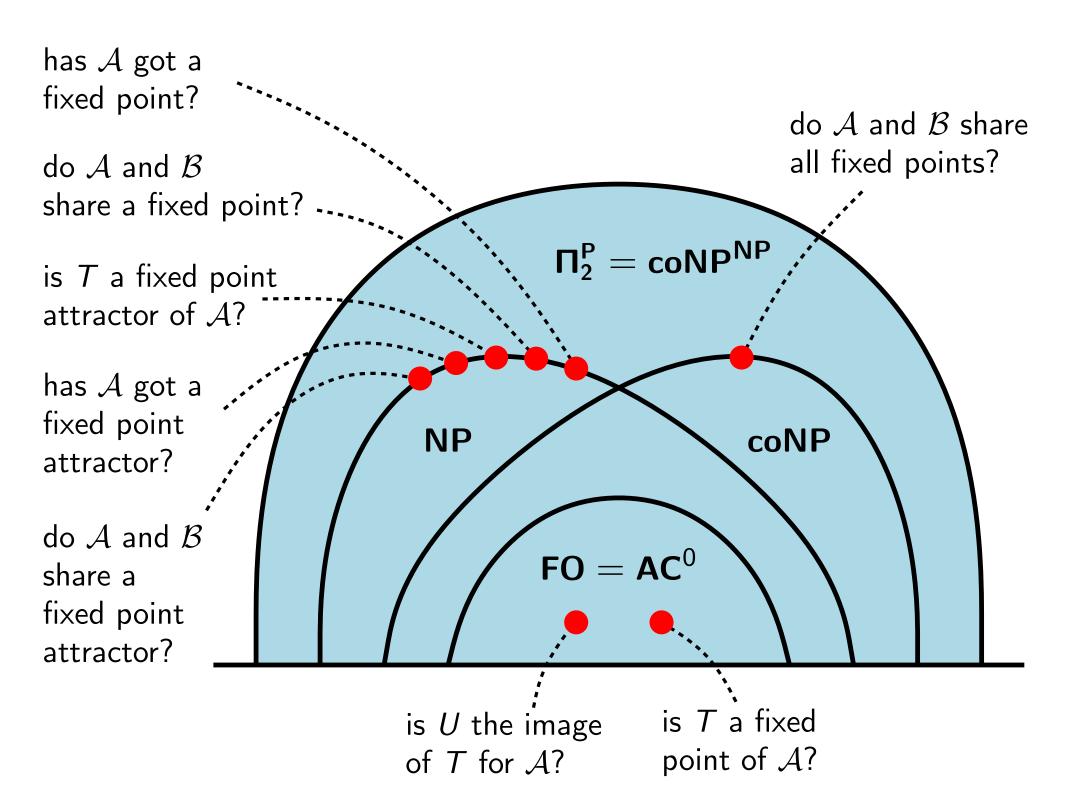


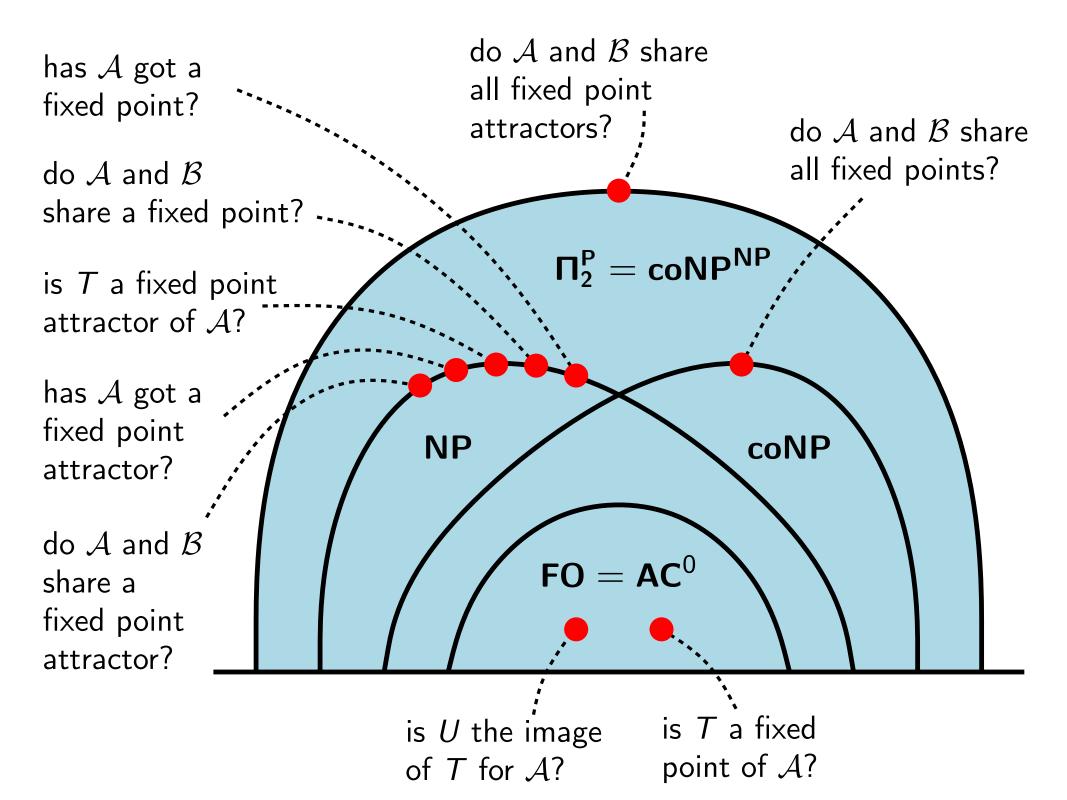












Open problems

- Complexity of reachability
- Complexity of finding cycles
- Complexity of finding global attractors

SPOILER: everything becomes PSPACE-complete! See our DCFS 2014 paper (preprint at http://aeporreca.org)

Dynamics of RS with context ("nondeterministic")
Finding minimal RS with given res_A

Köszönöm a figyelmet! Thanks for your attention!

