



**UNIVERSITÀ DEGLI STUDI
DI MILANO-BICOCCA**

A
MILANO TEAM LTD*
Production

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A long time ago in papers far,
far away....

Theorem IV

UNBOUNDED DEPTH

Confluent P systems with active membranes
with UNBOUNDED-DEPTH membrane
structures characterise PSPACE in polyno-
mial time....

Theorem V

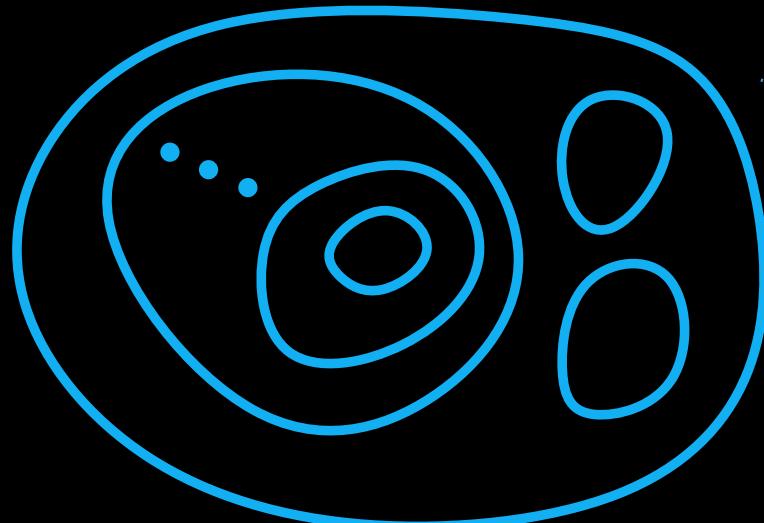
SHALLOW DEPTH

Confluent P systems with active membranes with SHALLOW (i.e., depth-1) membrane structures characterise $P^{\#P}$ in polynomial time. . .

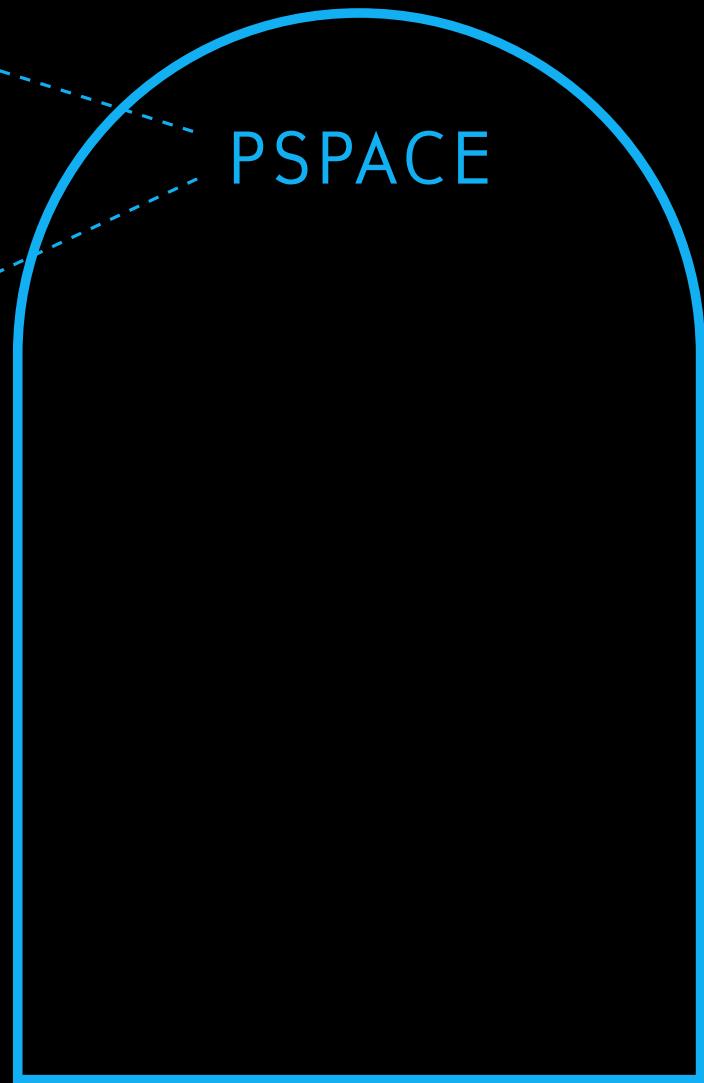
Theorem VI

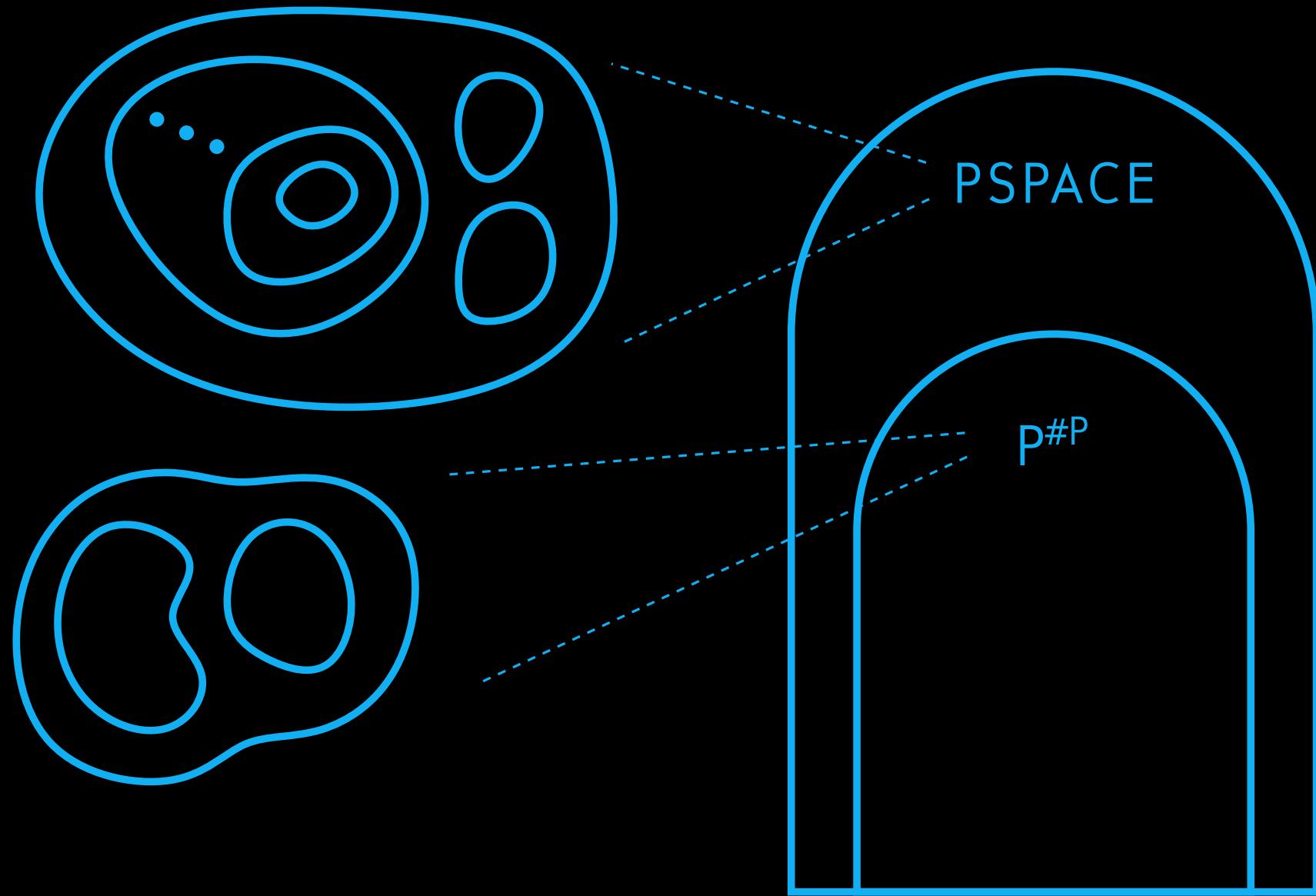
MILANO THEOREM

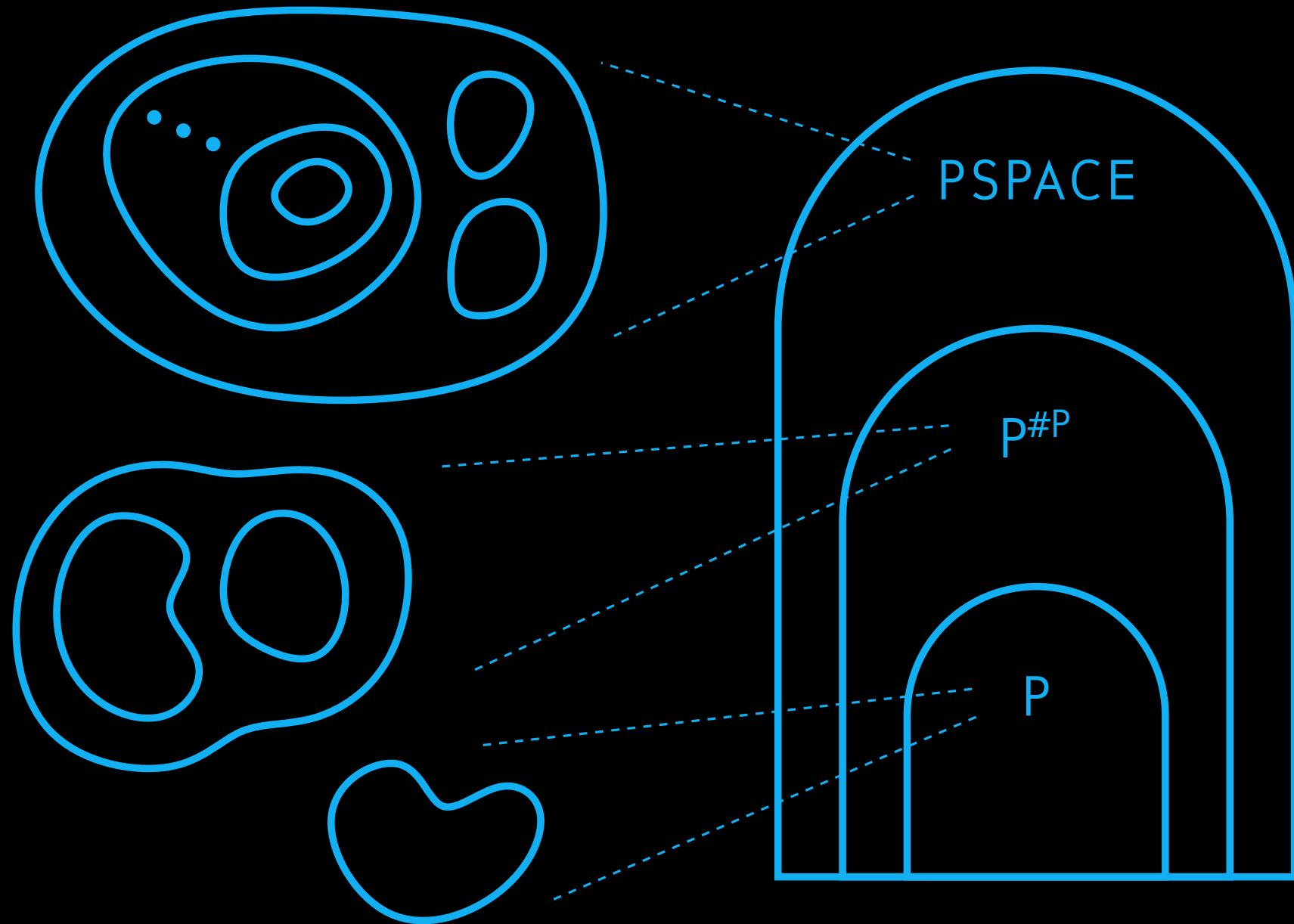
Confluent P systems with active membranes with DEPTH-0 membrane structures (i.e., single membranes) characterise P in polynomial time....



PSPACE







SHALLOW NON-CONFLUENT P SYSTEMS

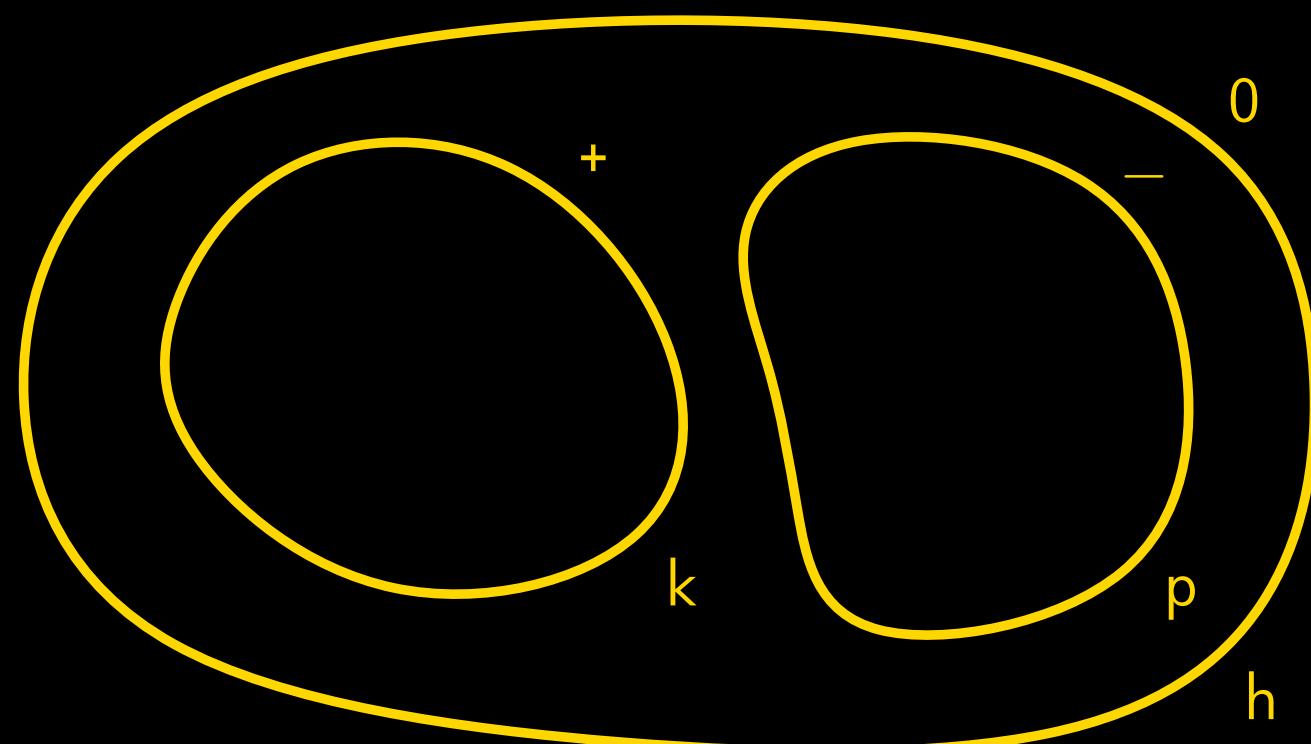
Theorem I

A NEW RESULT

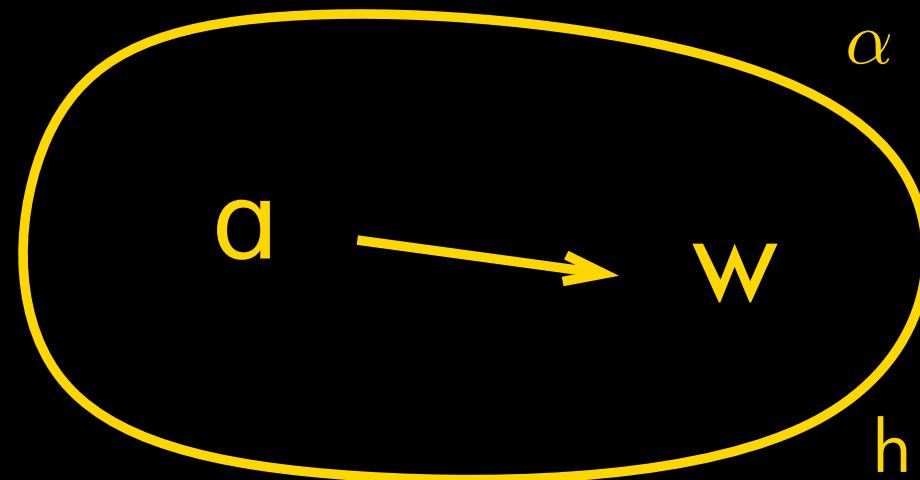
SHALLOW NON-CONFLUENT P systems with active membranes can simulate polynomial-SPACE nondeterministic Turing machines in polynomial TIME, and thus solve all PSPACE problems and restore efficiency to the galaxy....

Definition I

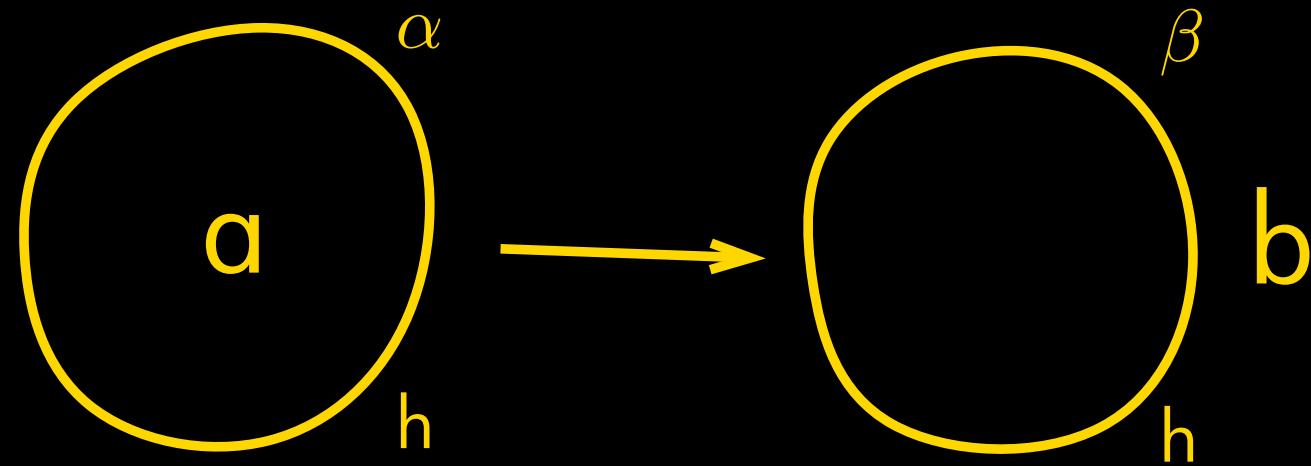
P SYSTEMS WITH ACTIVE MEMBRANES



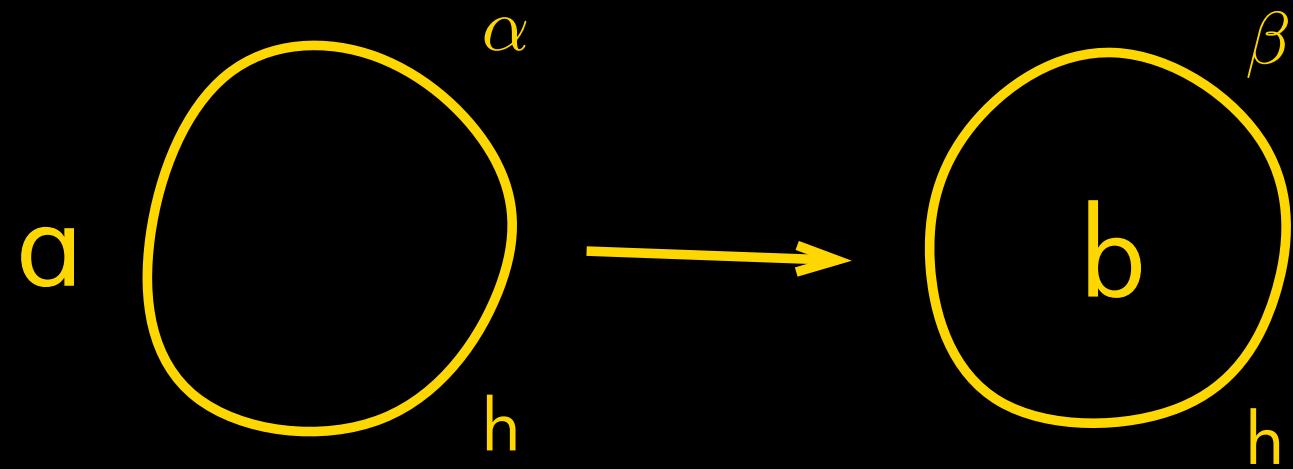
OBJECT EVOLUTION

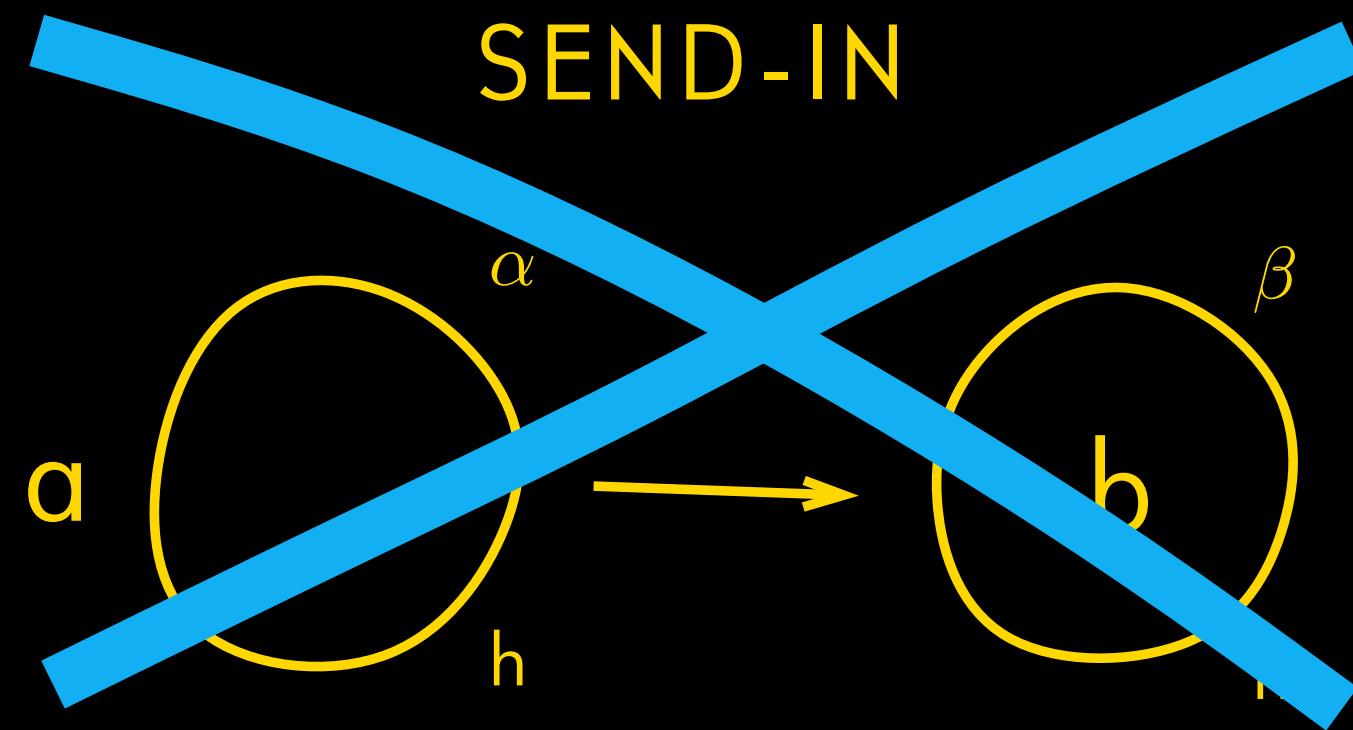


SEND-OUT

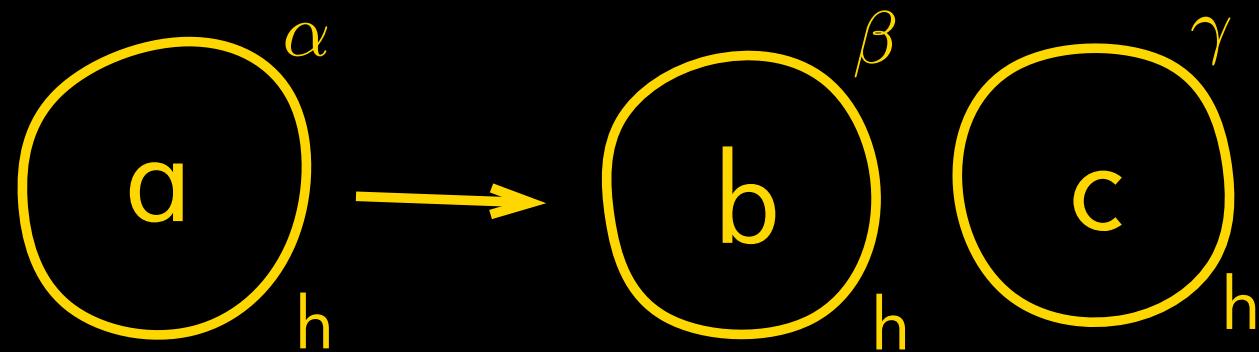


SEND-IN





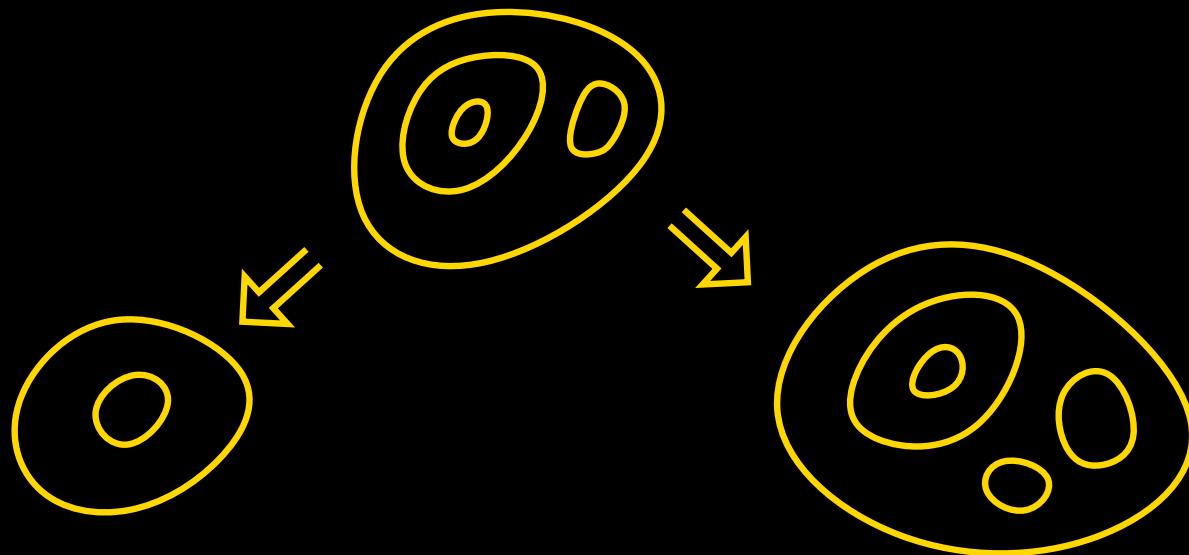
ELEMENTARY DIVISION



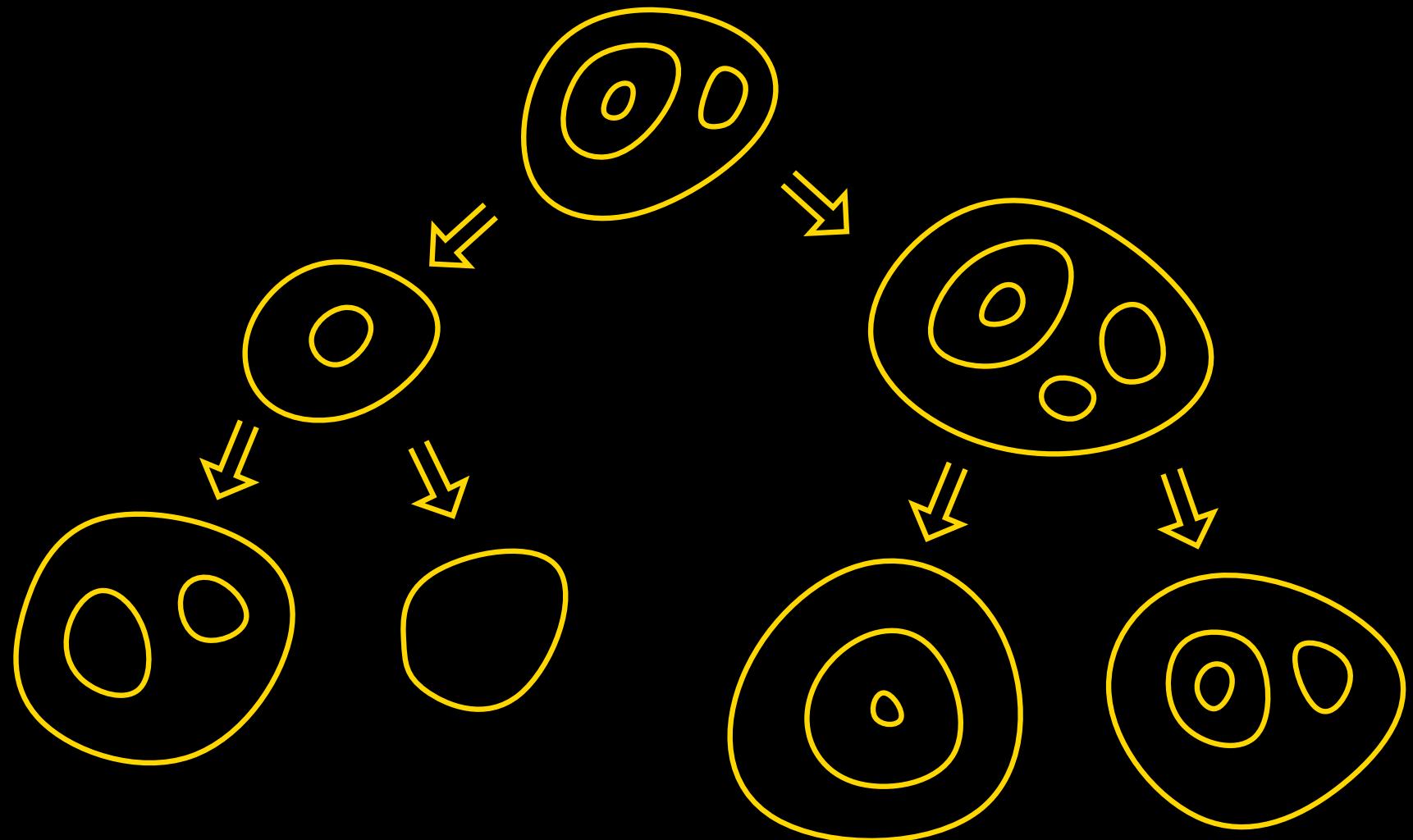
NON-CONFLUENCE



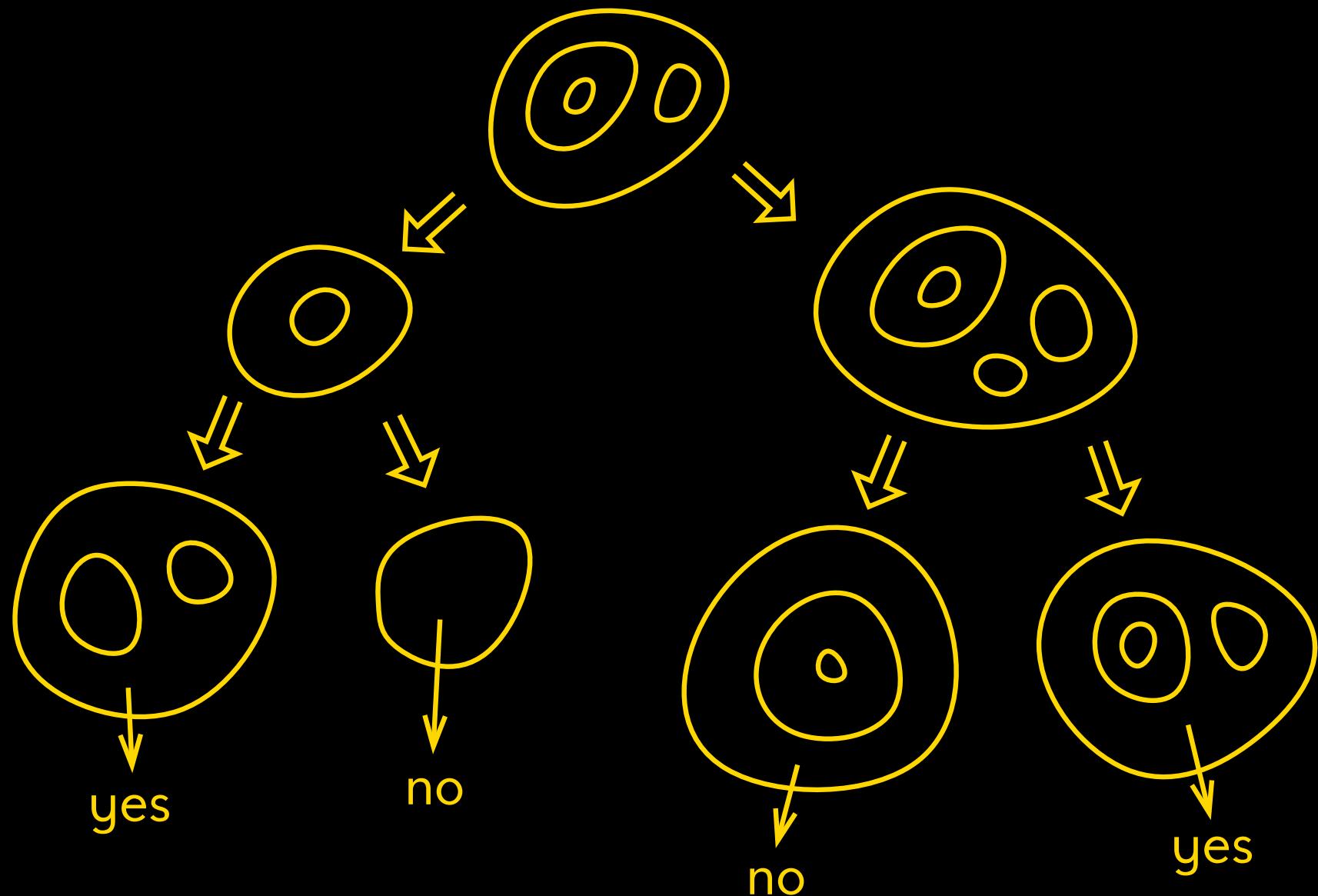
NON-CONFLUENCE



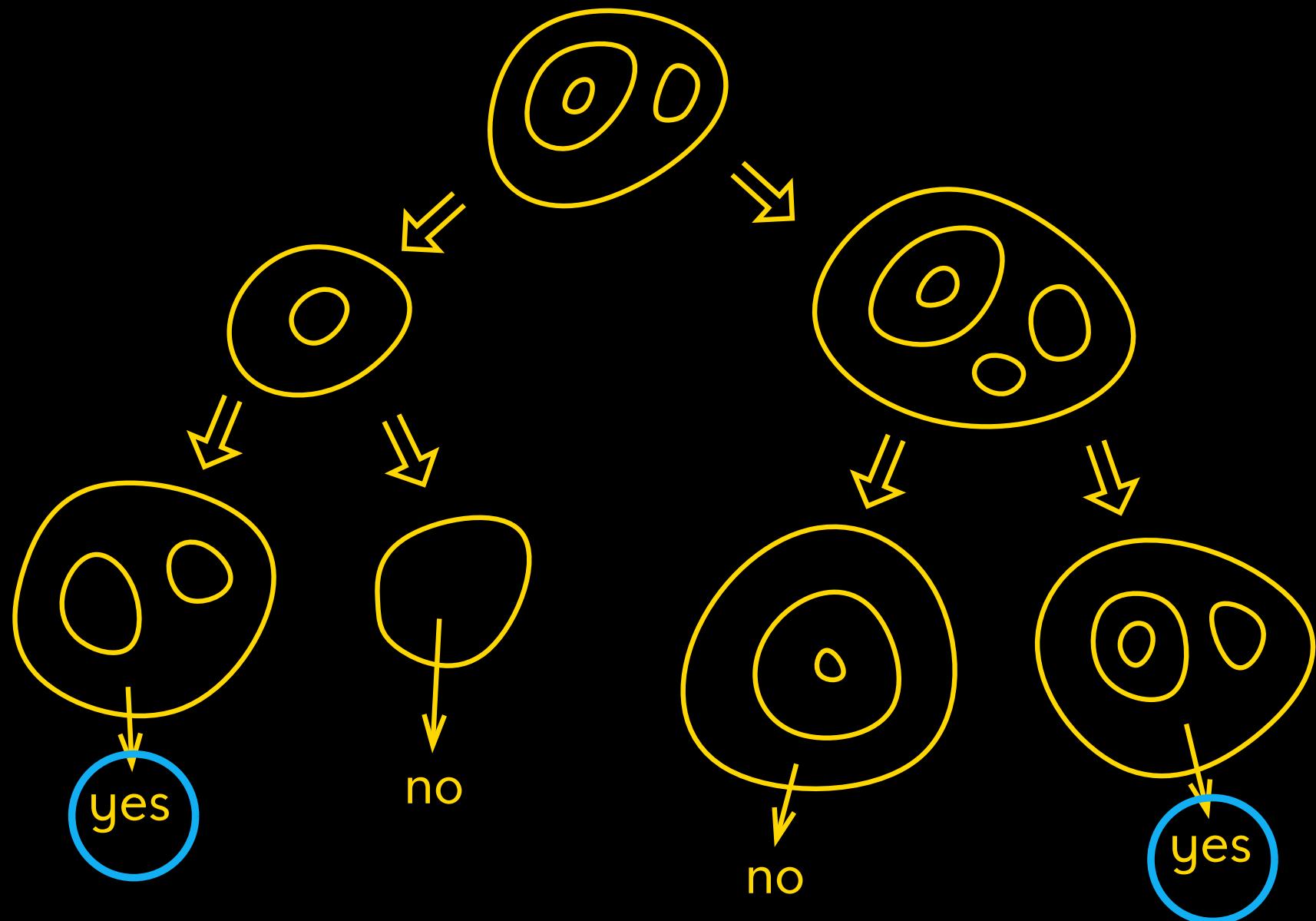
NON-CONFLUENCE



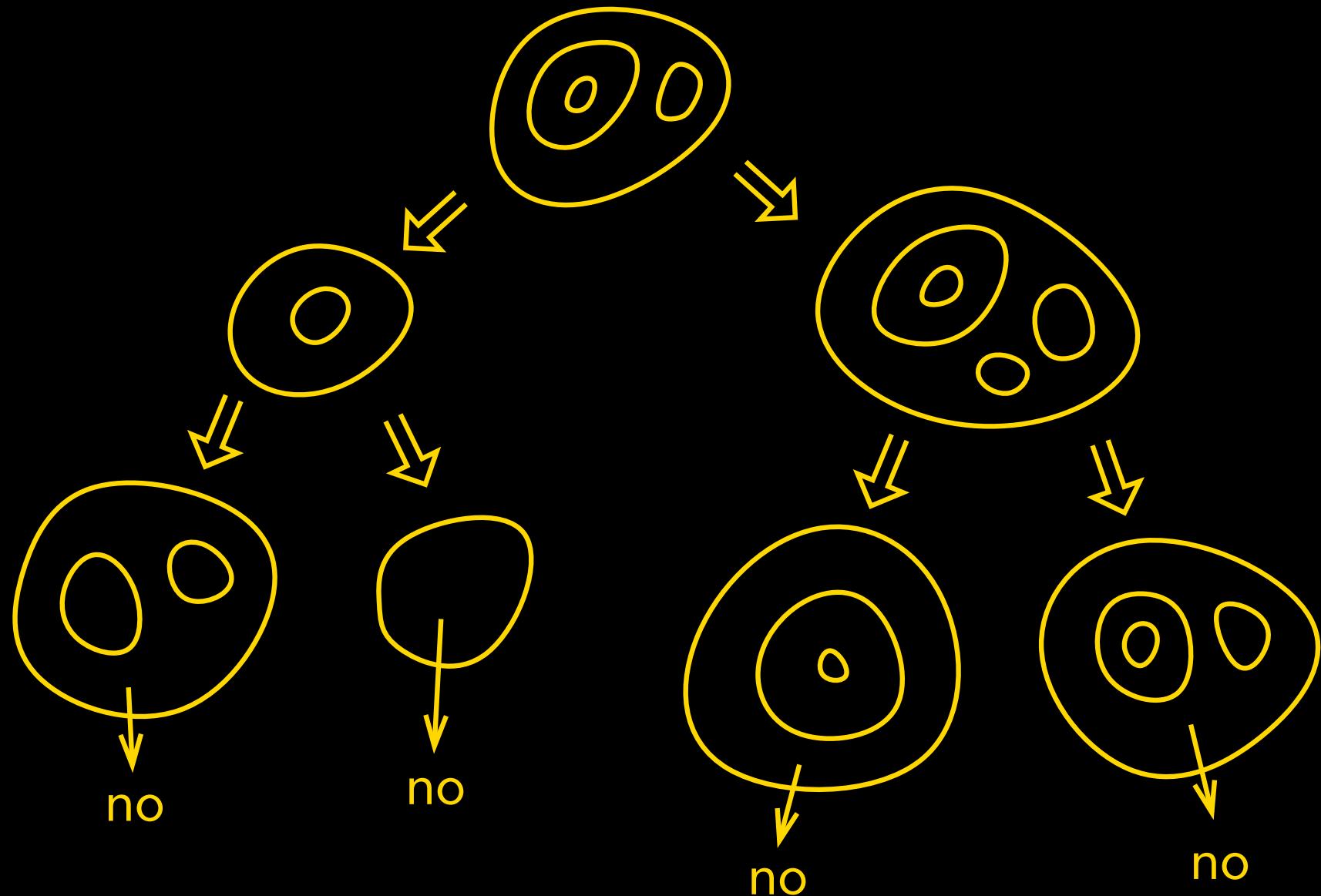
NON-CONFLUENCE



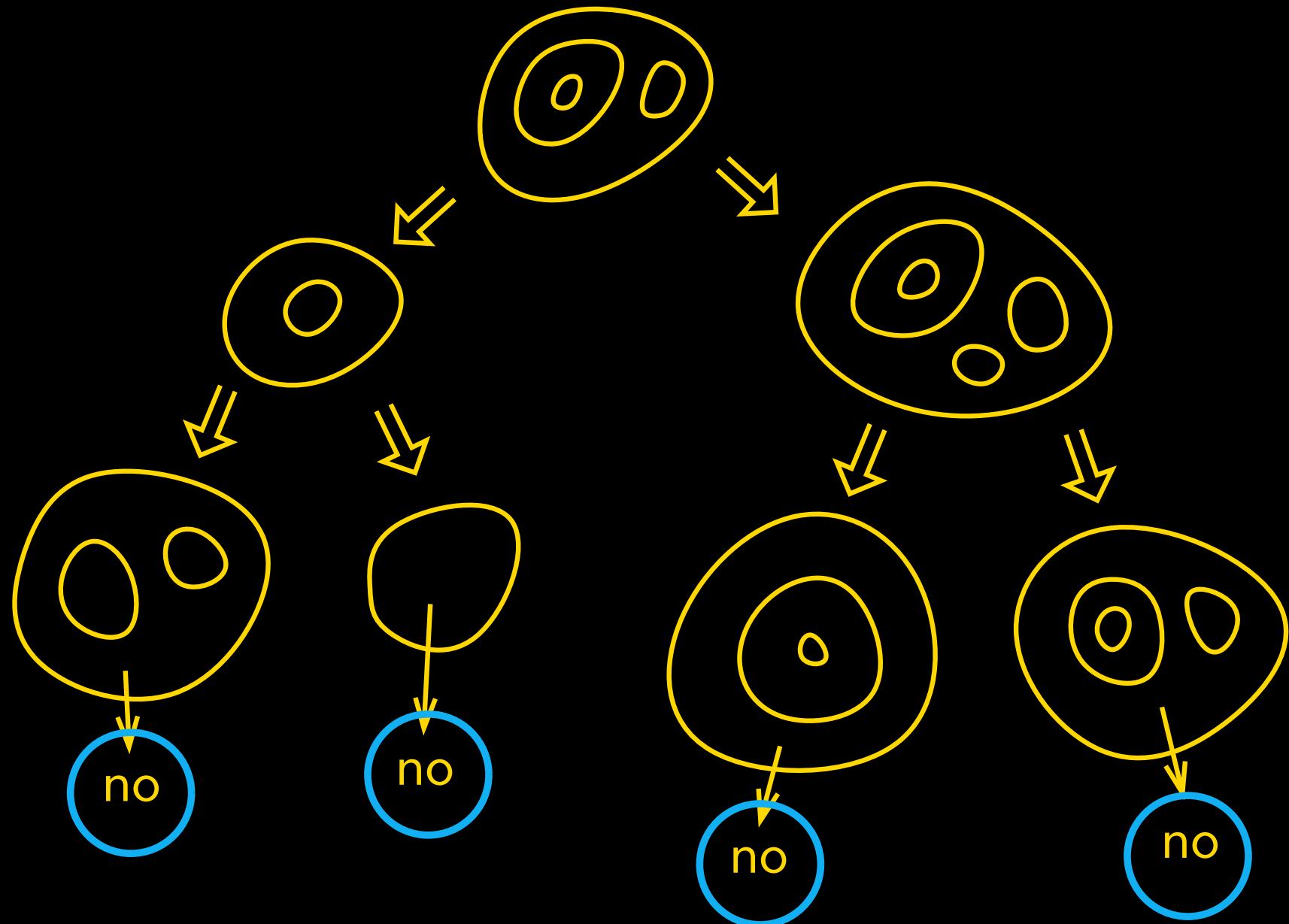
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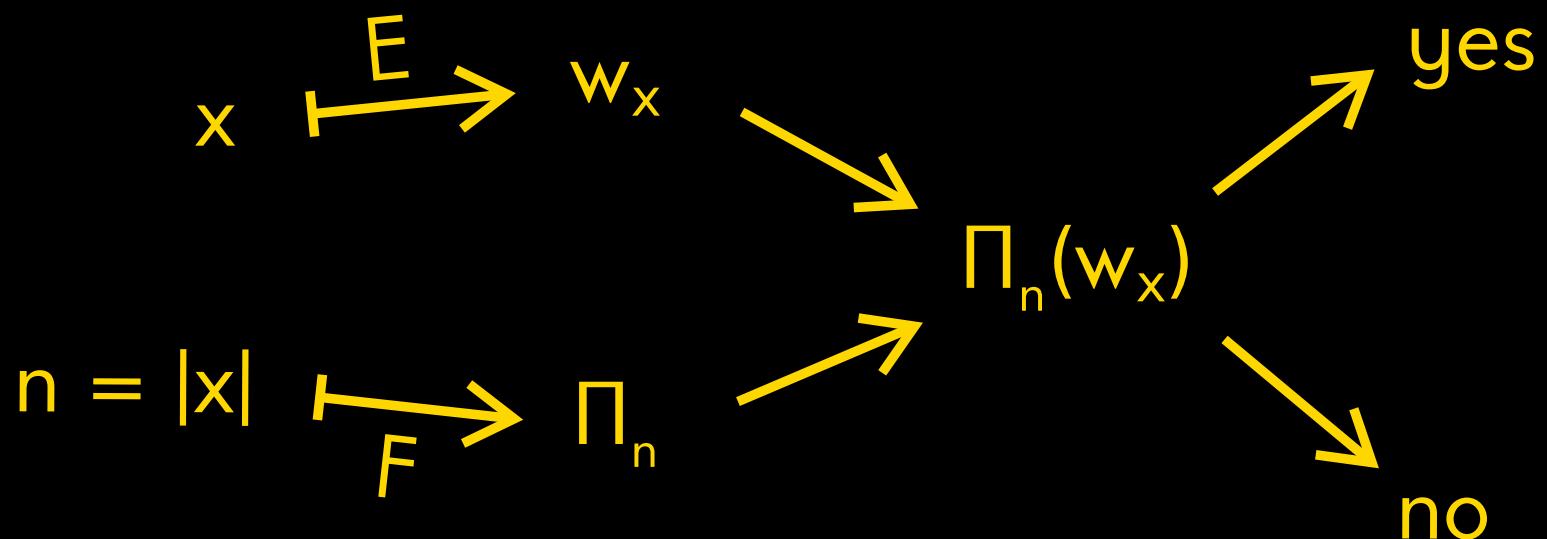
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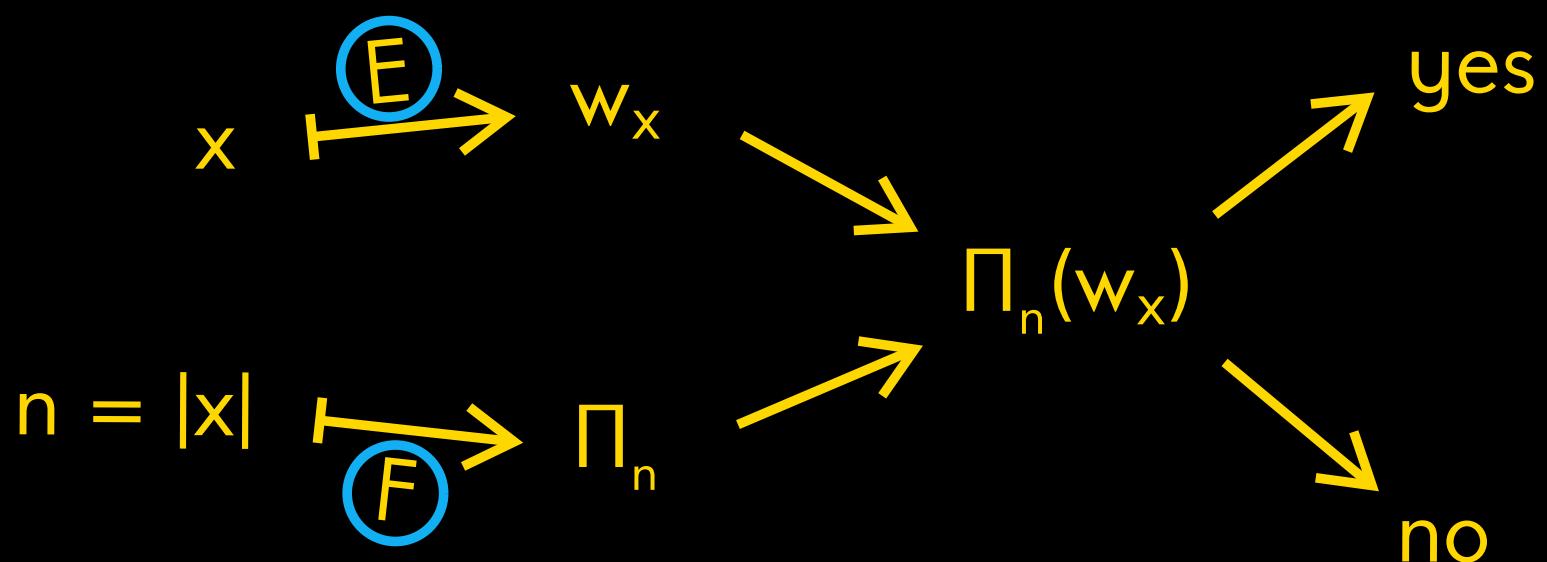
NON-CONFLUENCE



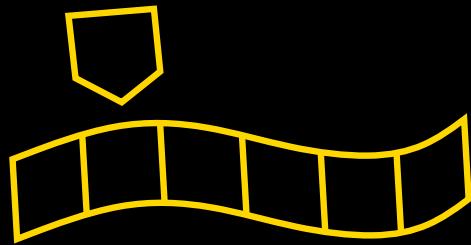
UNIFORM FAMILY Π



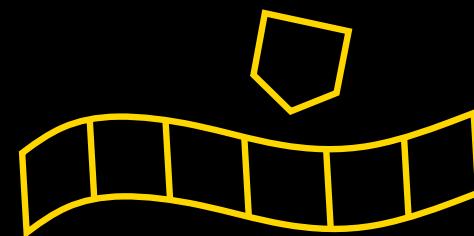
UNIFORM FAMILY Π



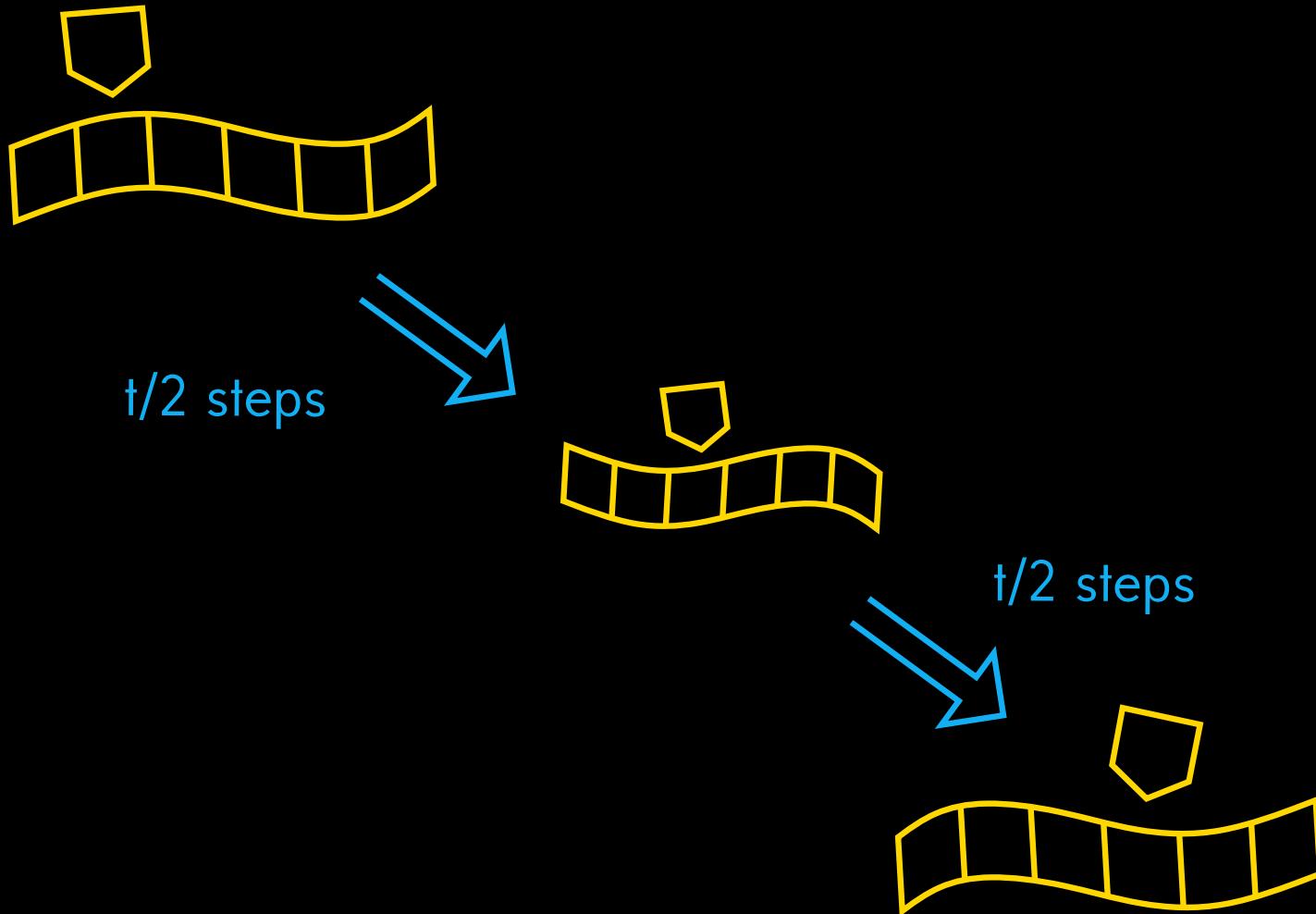
TM COMPUTATIONS



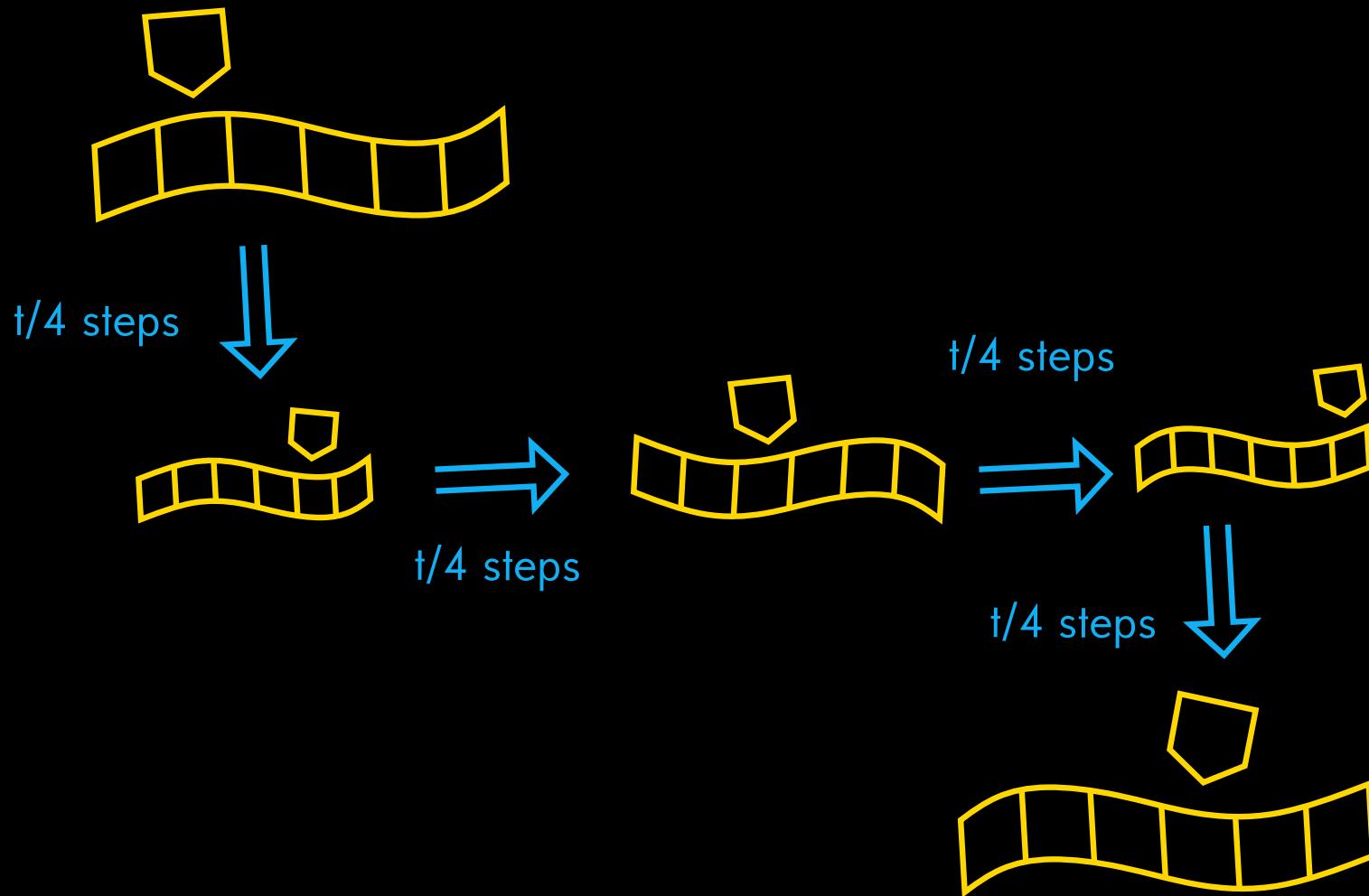
t steps

A large blue arrow points from the initial state on the left towards the final state on the right, with the text "t steps" written above it.

TM COMPUTATIONS



TM COMPUTATIONS

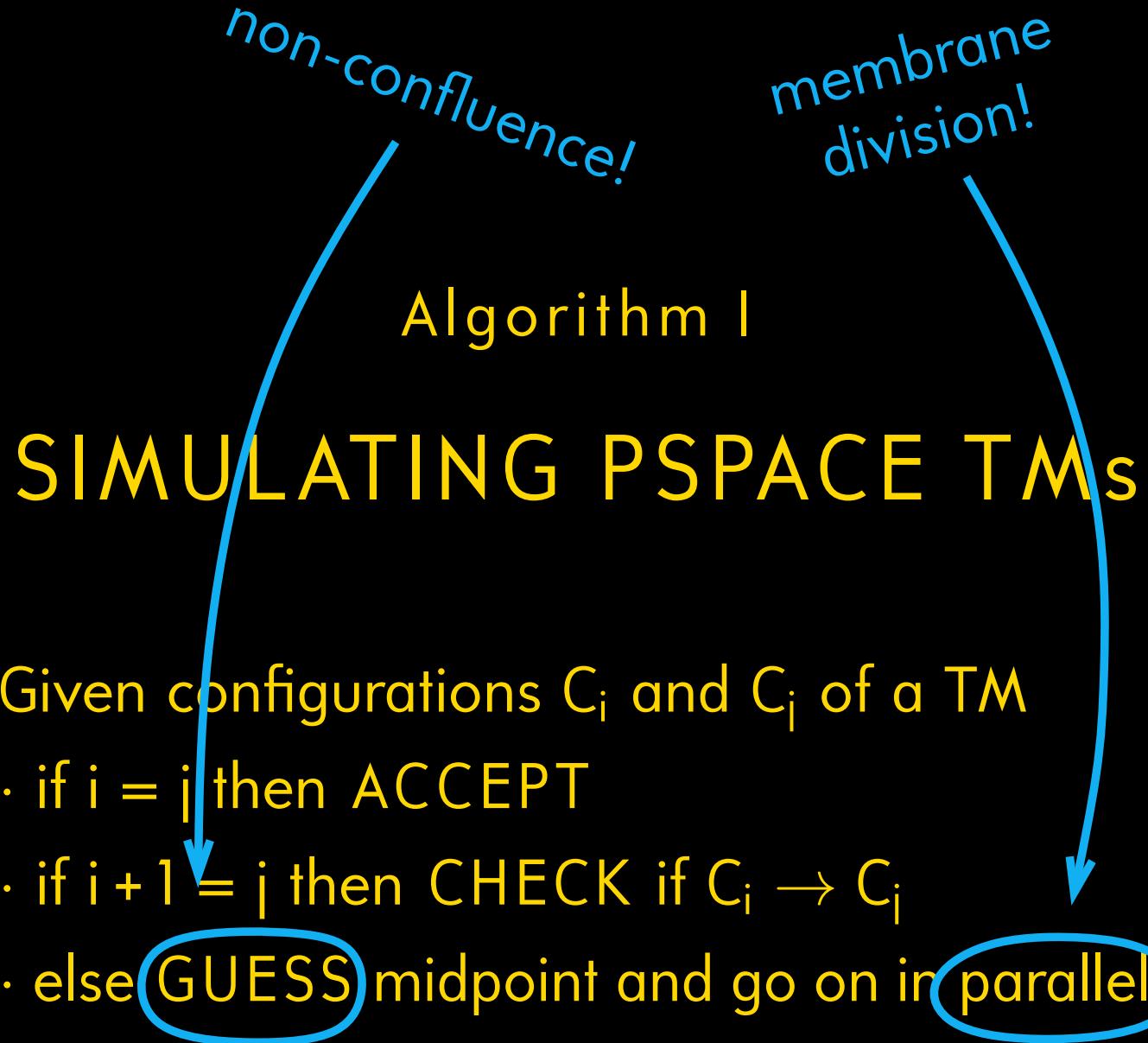


Algorithm I

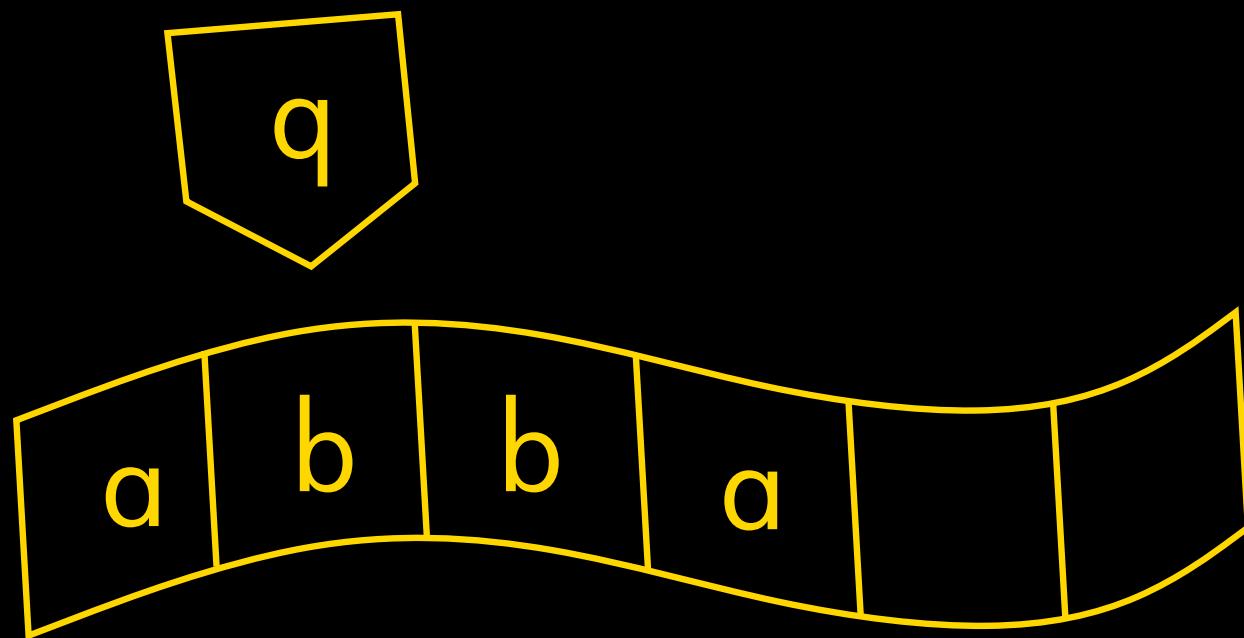
SIMULATING PSPACE TMs

Given configurations C_i and C_j of a TM

- if $i = j$ then ACCEPT
- if $i + 1 = j$ then CHECK if $C_i \rightarrow C_j$
- else GUESS midpoint and go on in parallel

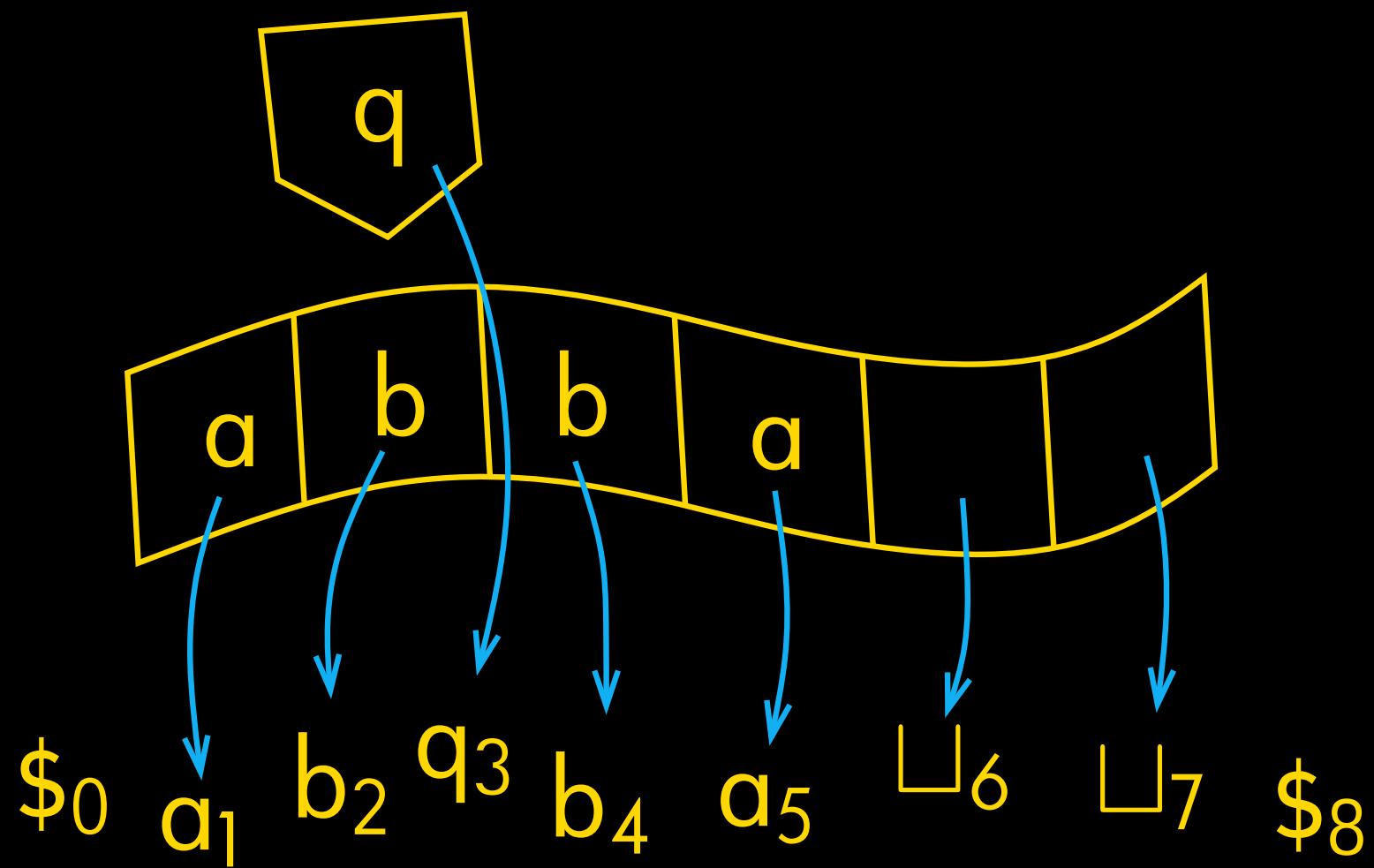


ENCODING TM CFGs

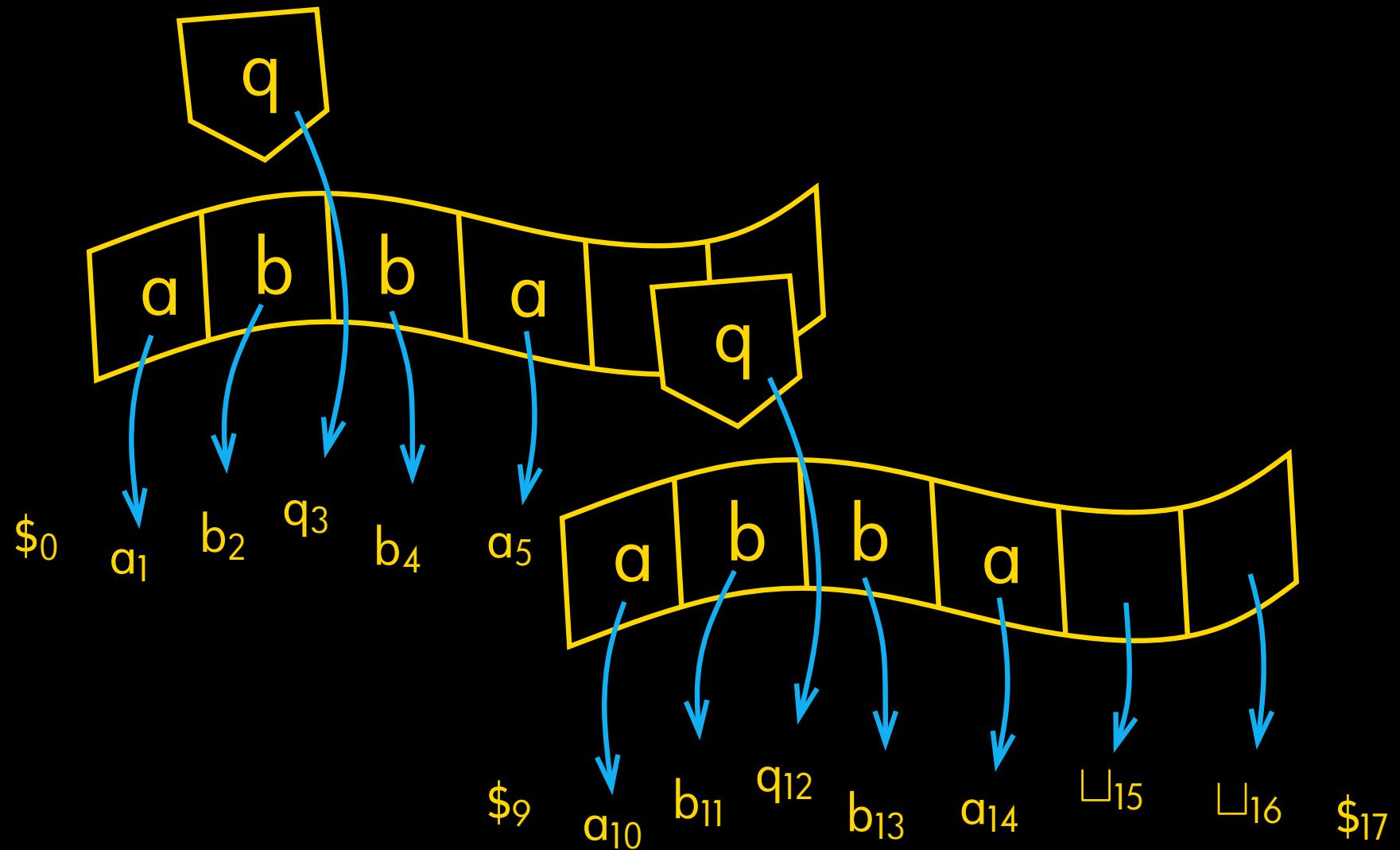


$\$_0 \ a_1 \ b_2 \ q_3 \ b_4 \ a_5 \ \sqcup_6 \ \sqcup_7 \ \$_8$

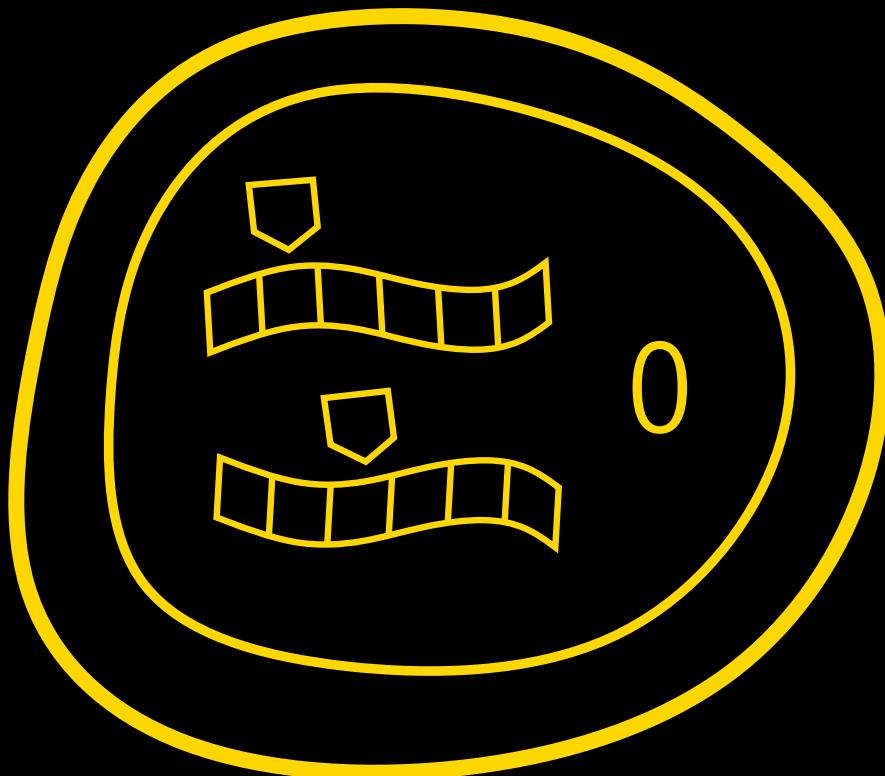
ENCODING TM CFGs



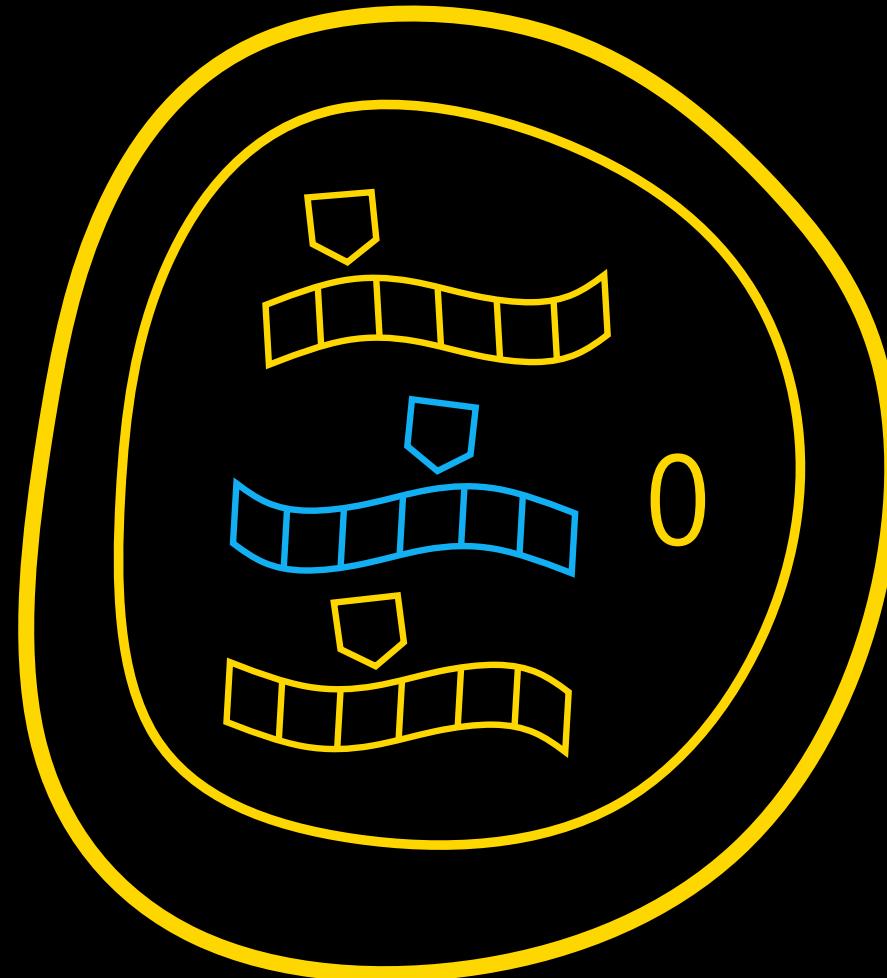
ENCODING TWO TM CFGs



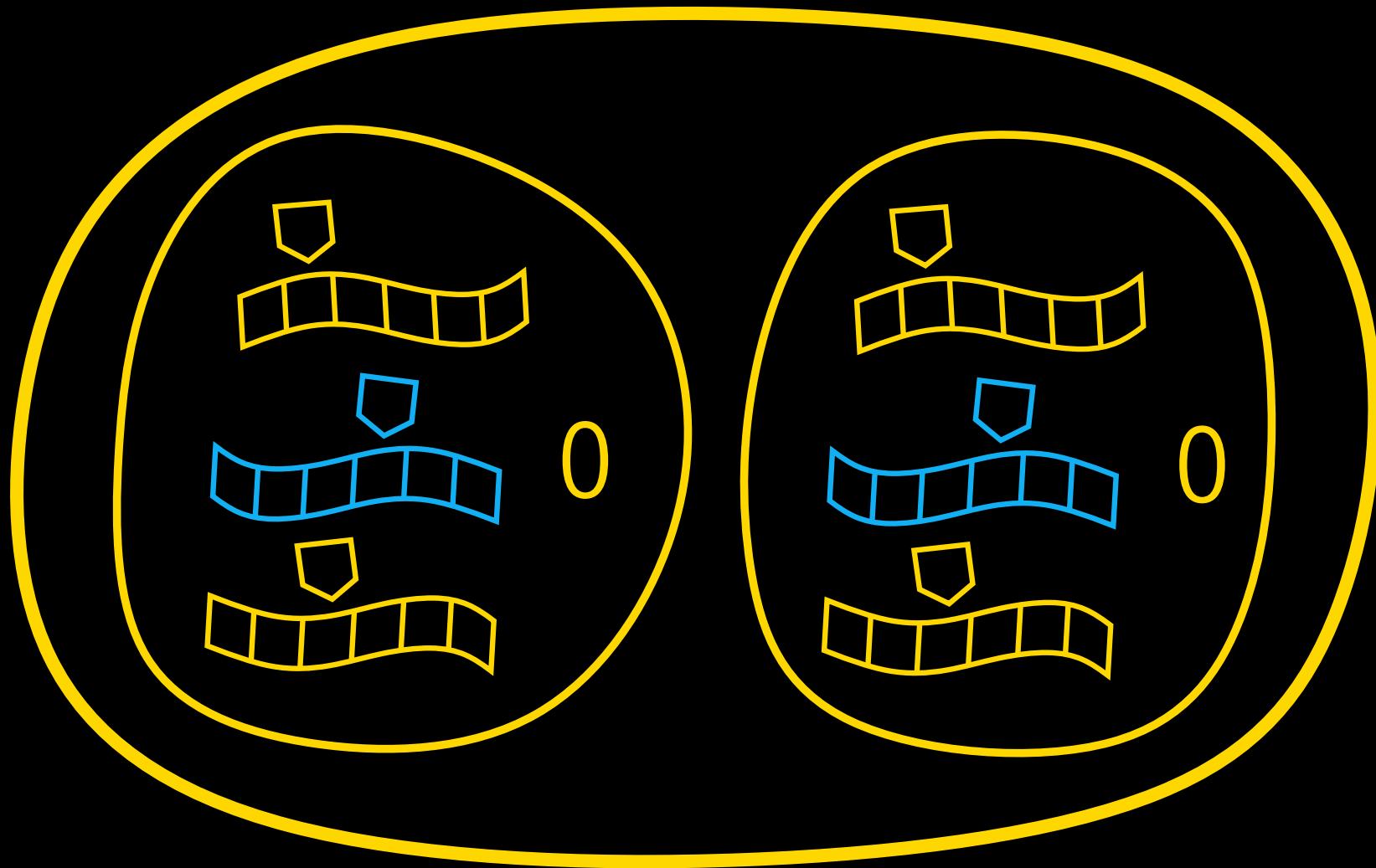
Algorithm I IMPLEMENTATION



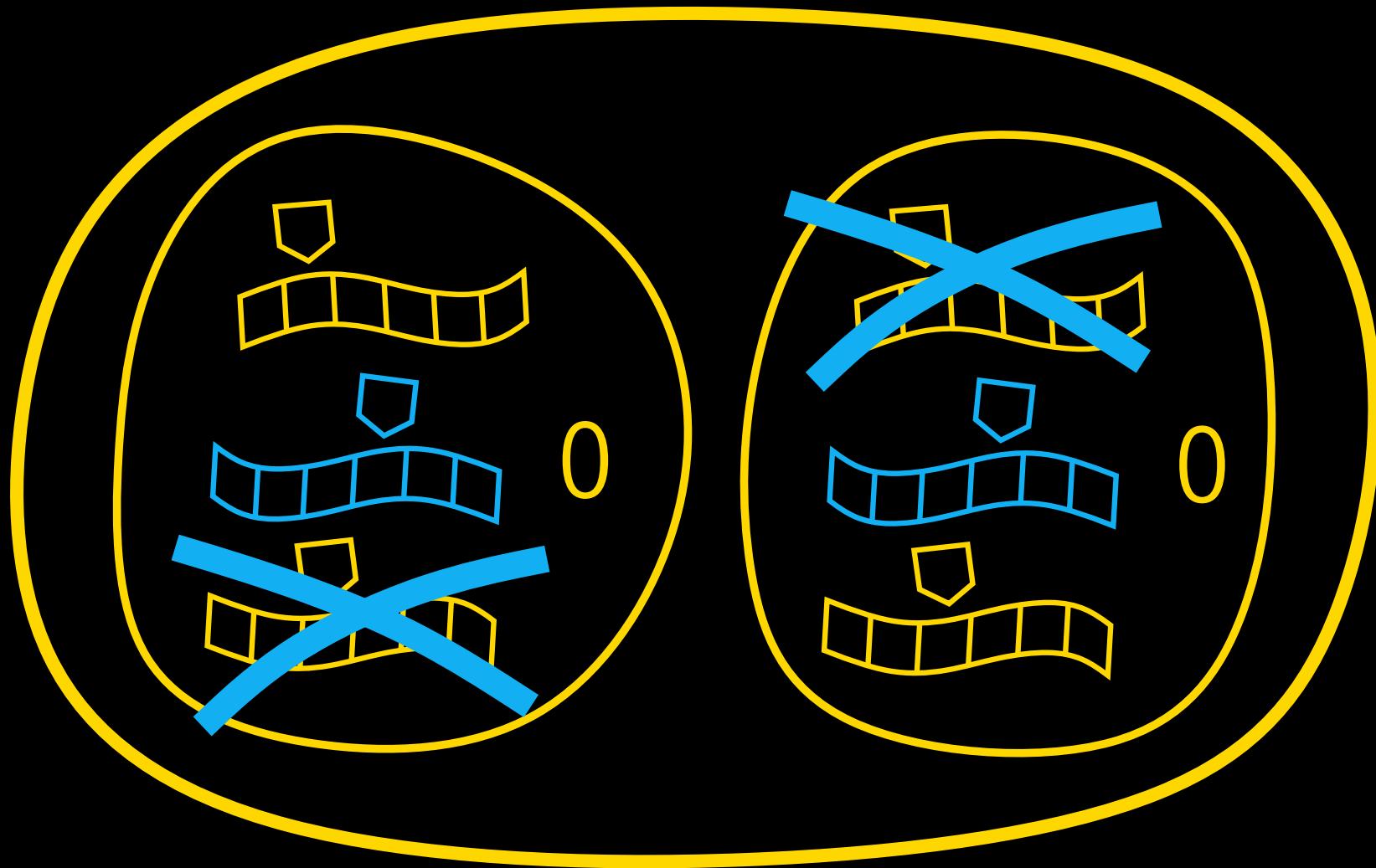
Algorithm I IMPLEMENTATION



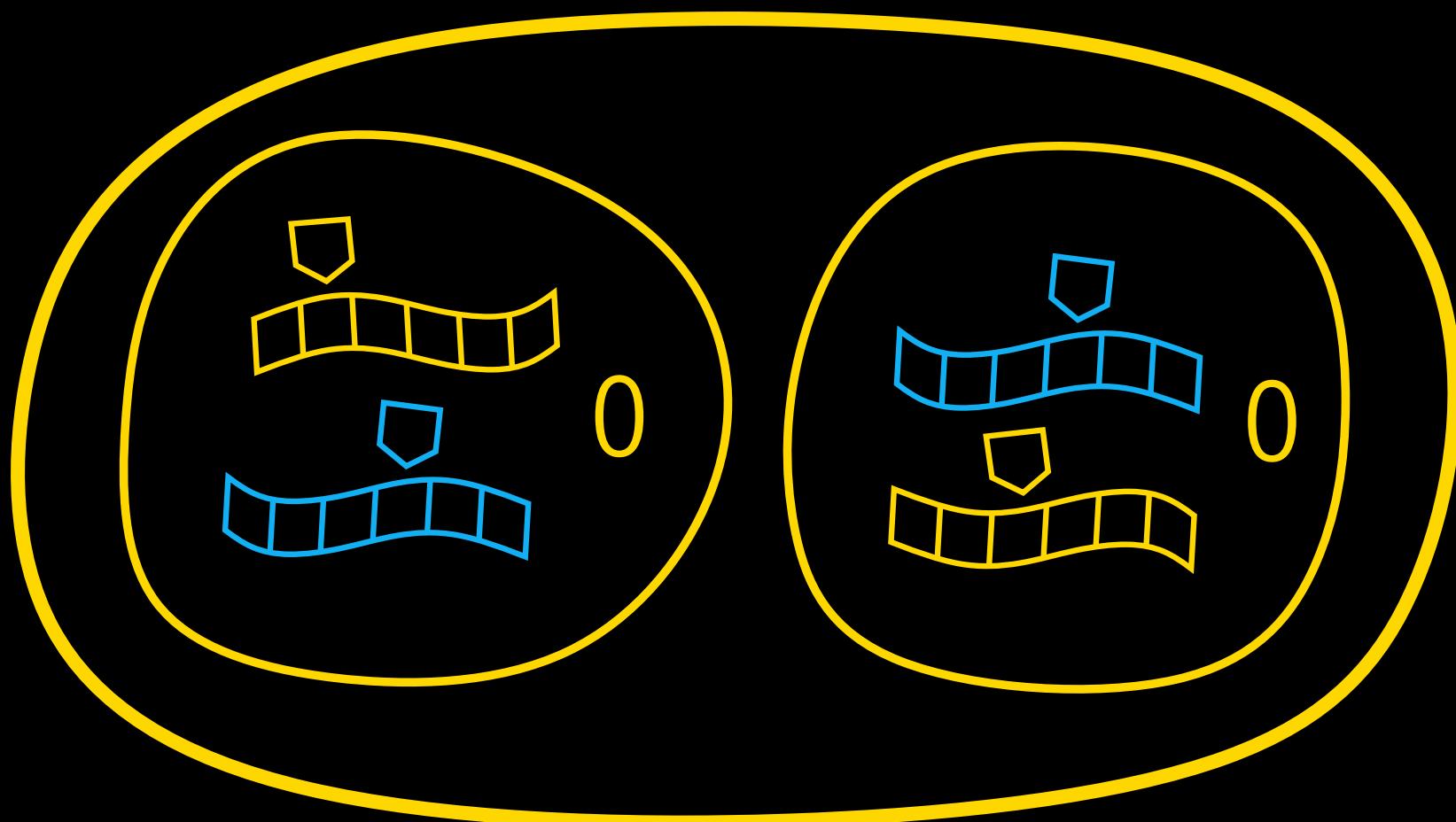
Algorithm I IMPLEMENTATION



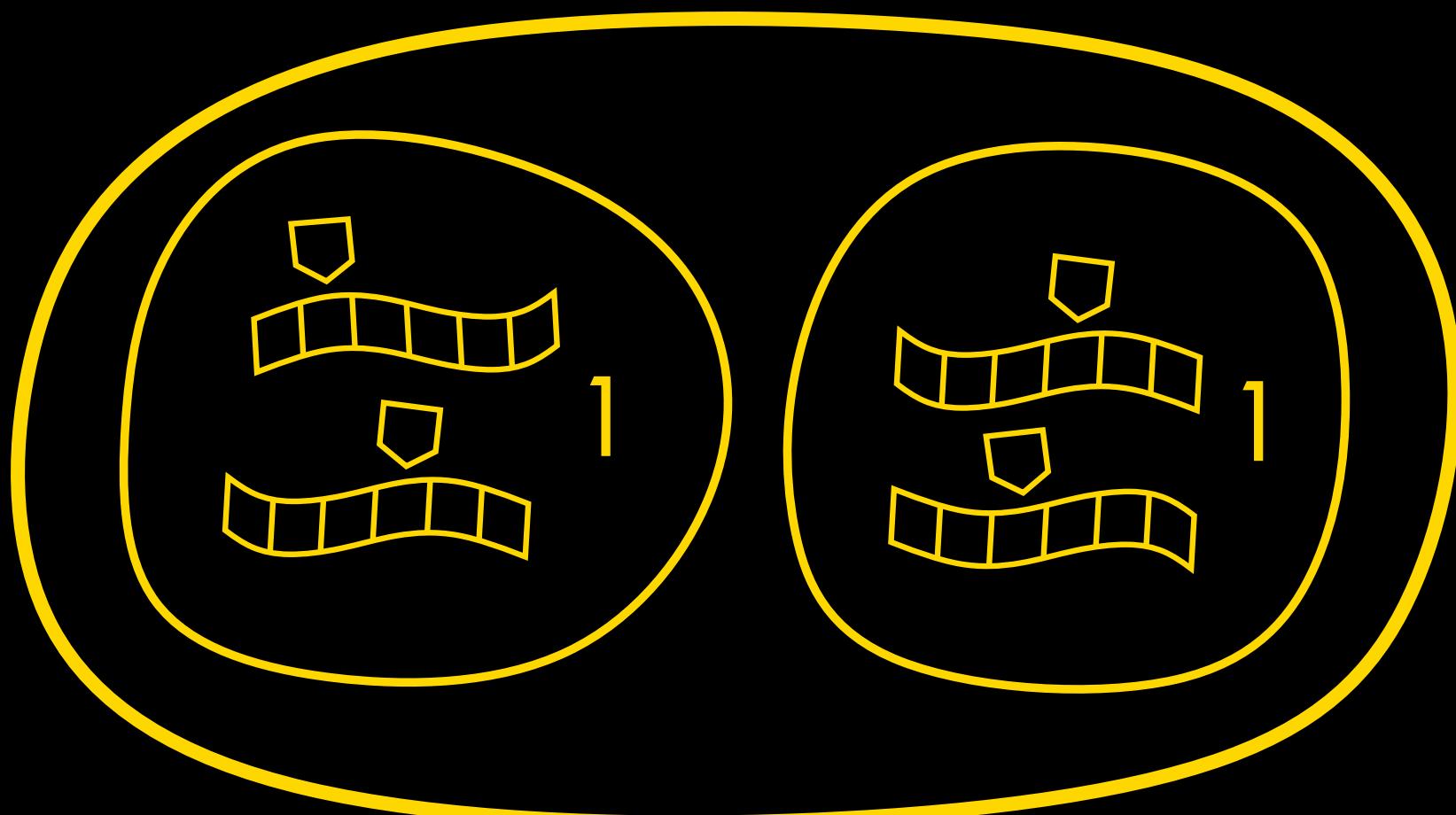
Algorithm I IMPLEMENTATION



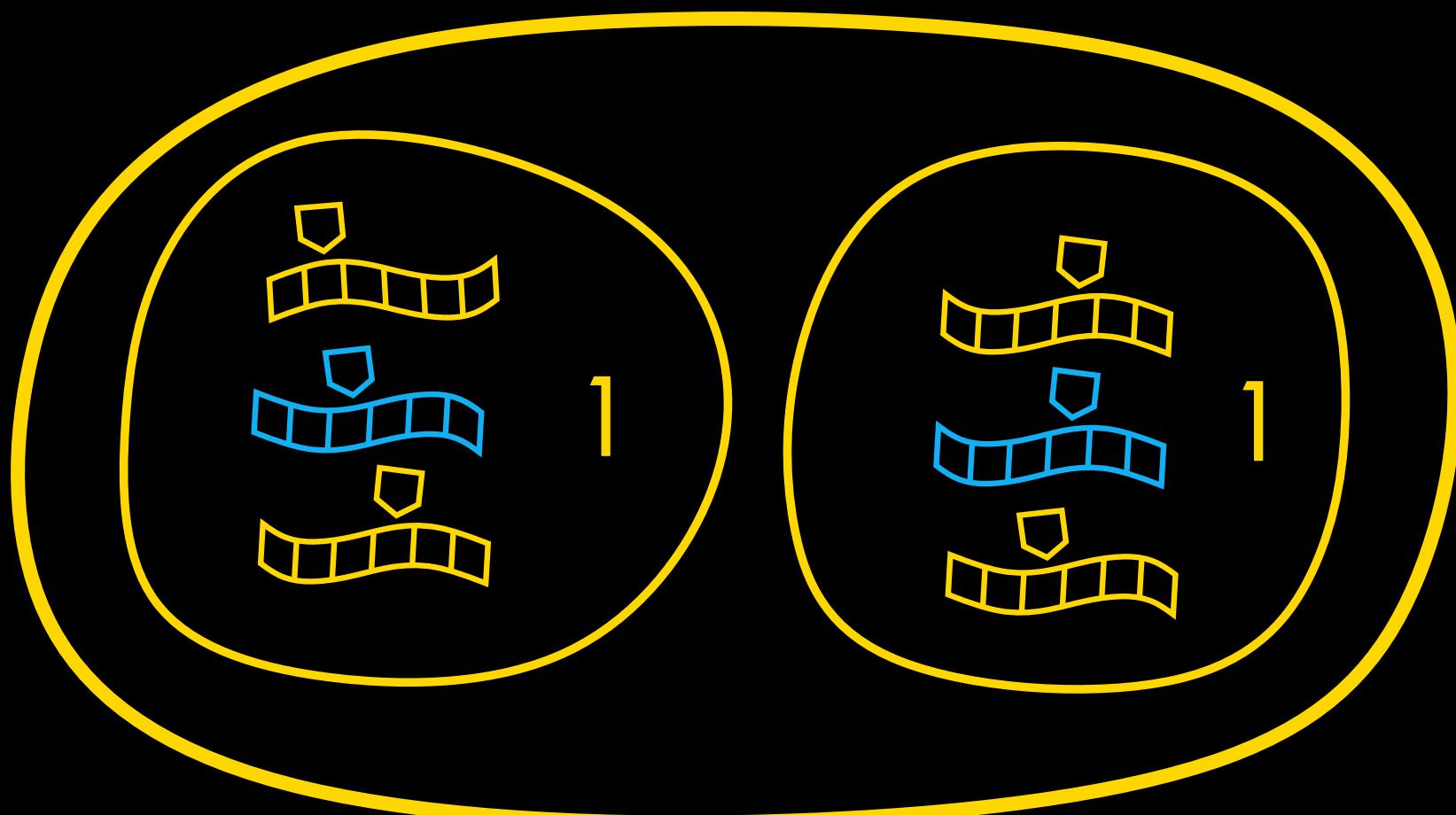
Algorithm I IMPLEMENTATION



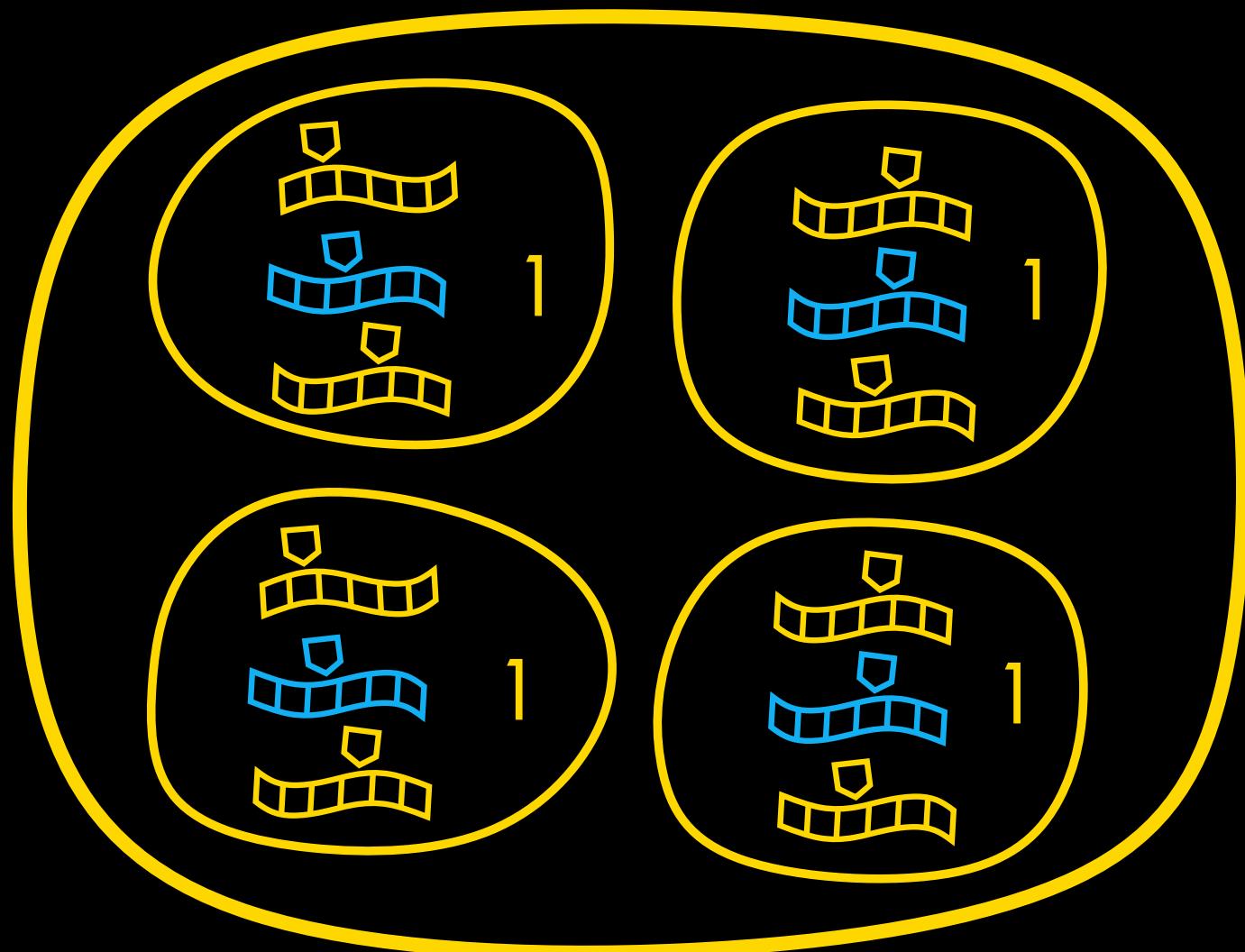
Algorithm I IMPLEMENTATION



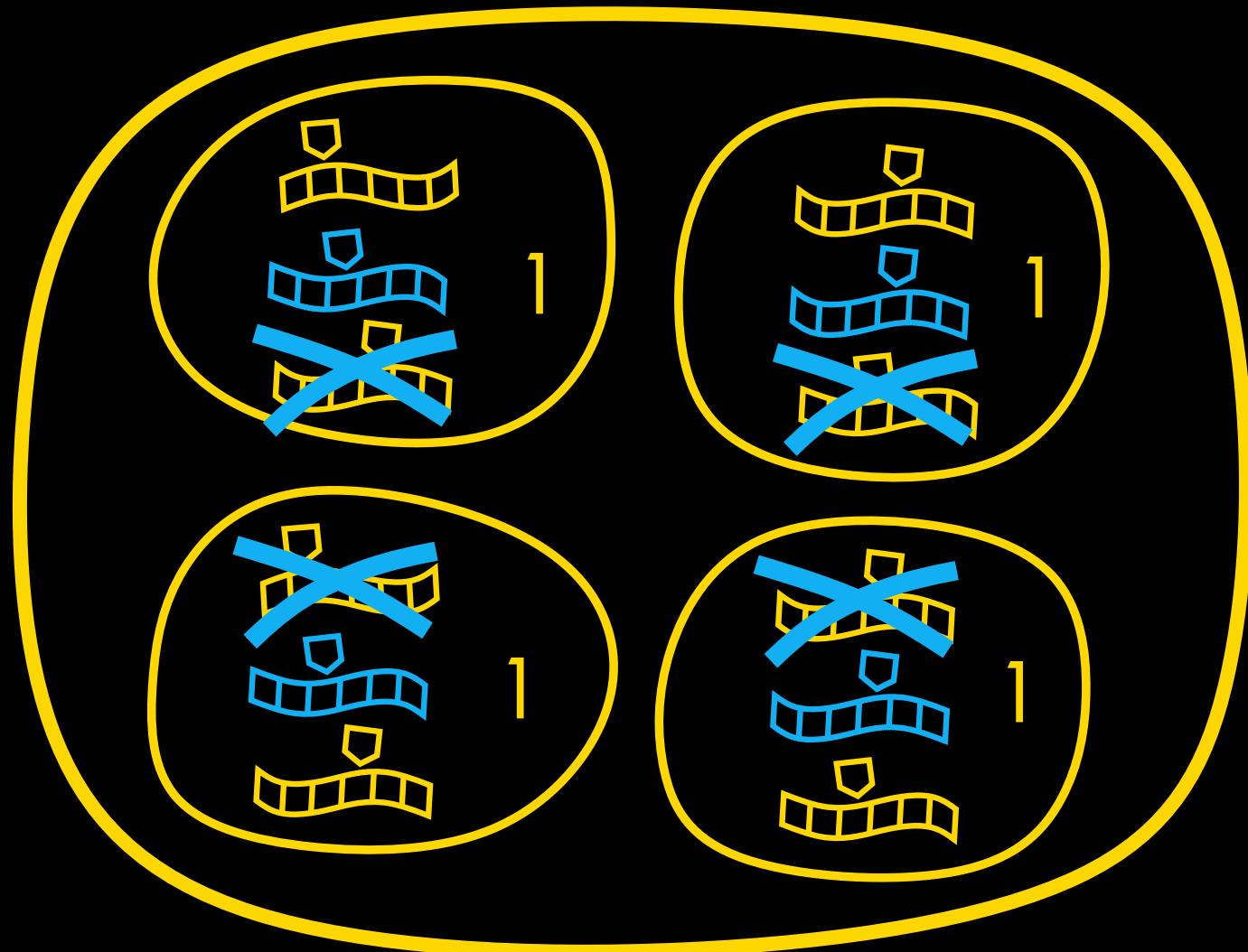
Algorithm I IMPLEMENTATION



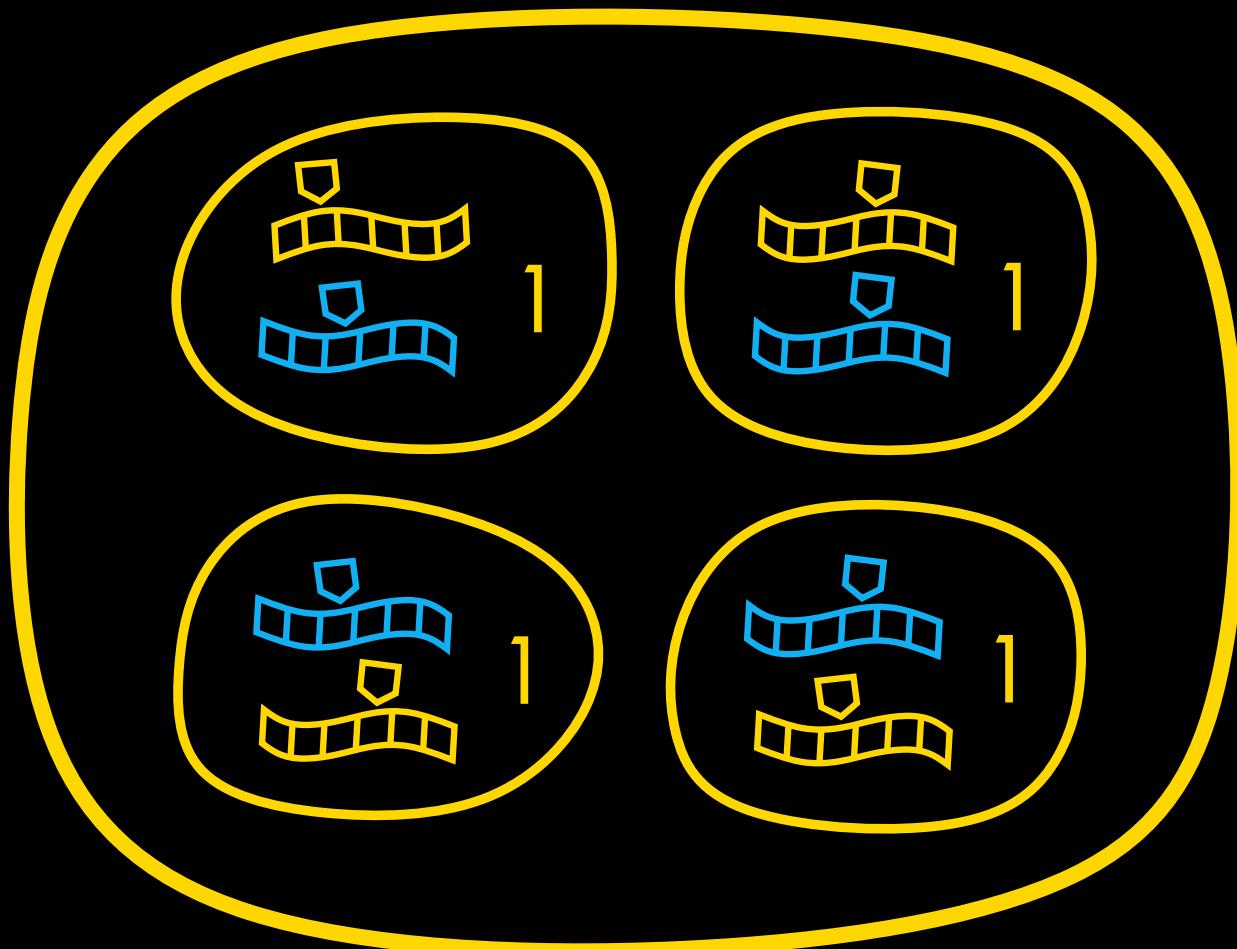
Algorithm I IMPLEMENTATION



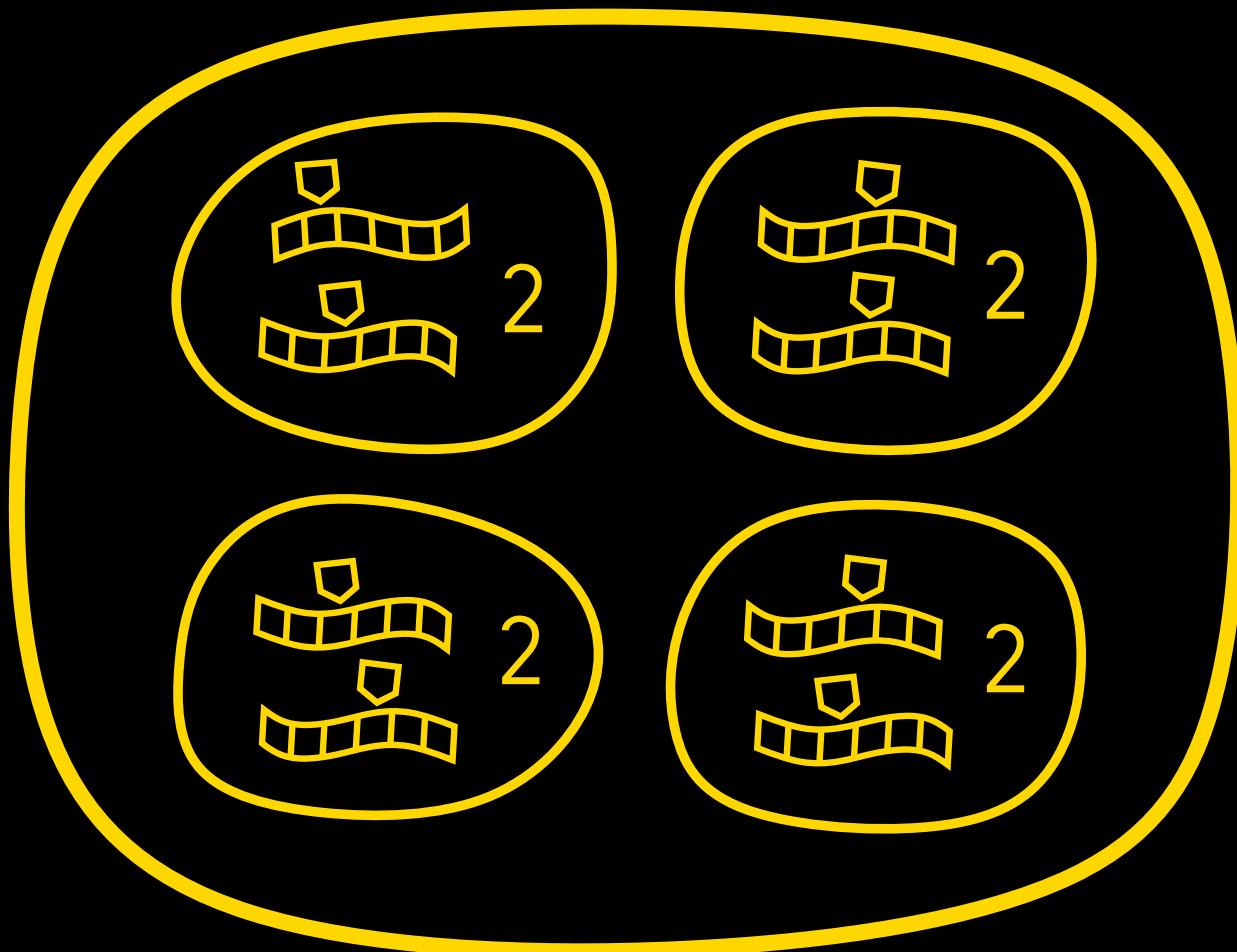
Algorithm I IMPLEMENTATION



Algorithm I IMPLEMENTATION

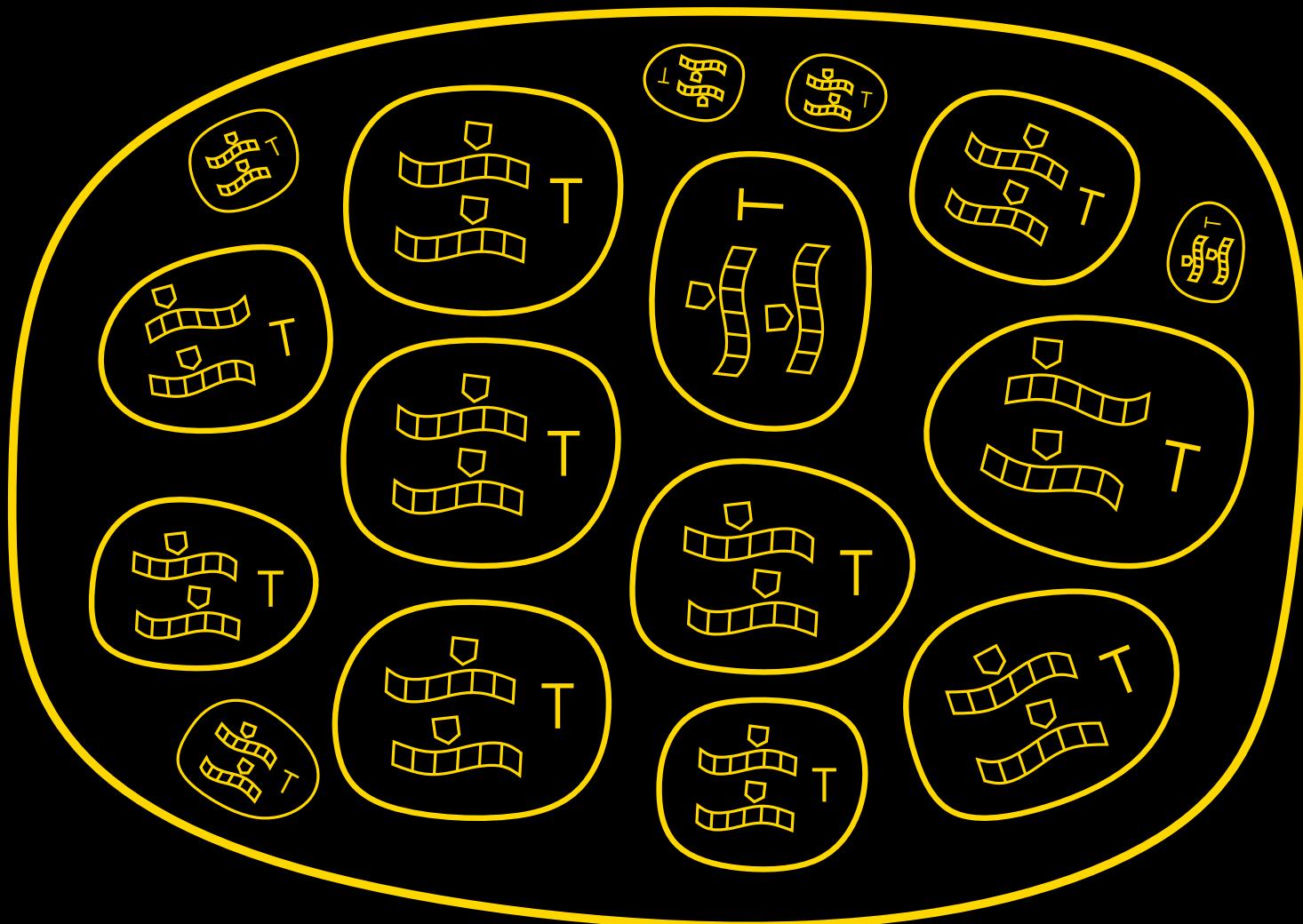


Algorithm I IMPLEMENTATION

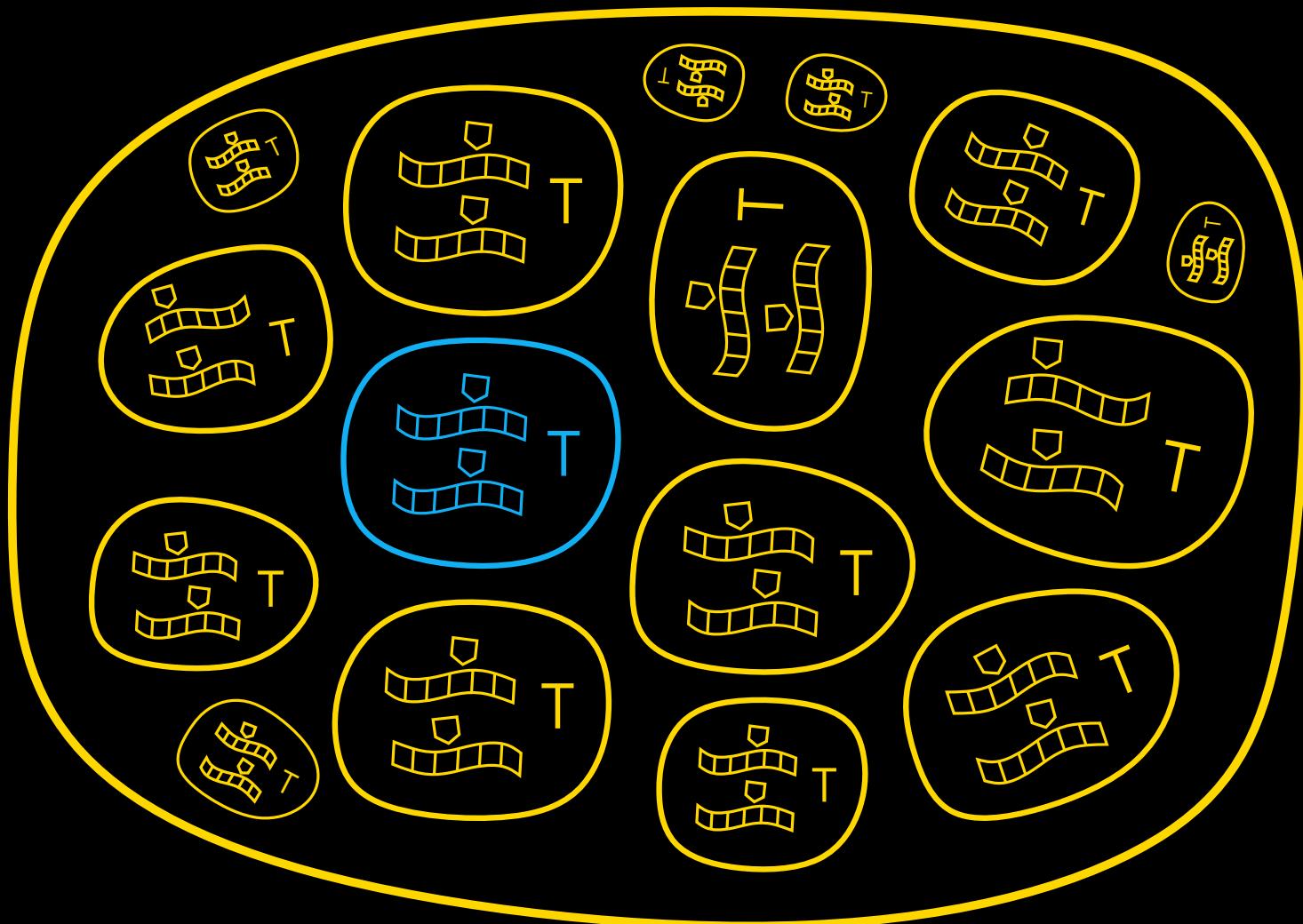


After $T = \log(\max \text{ time})$ many,
many steps....

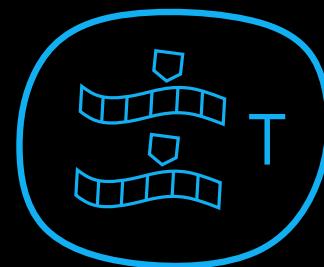
Algorithm I IMPLEMENTATION



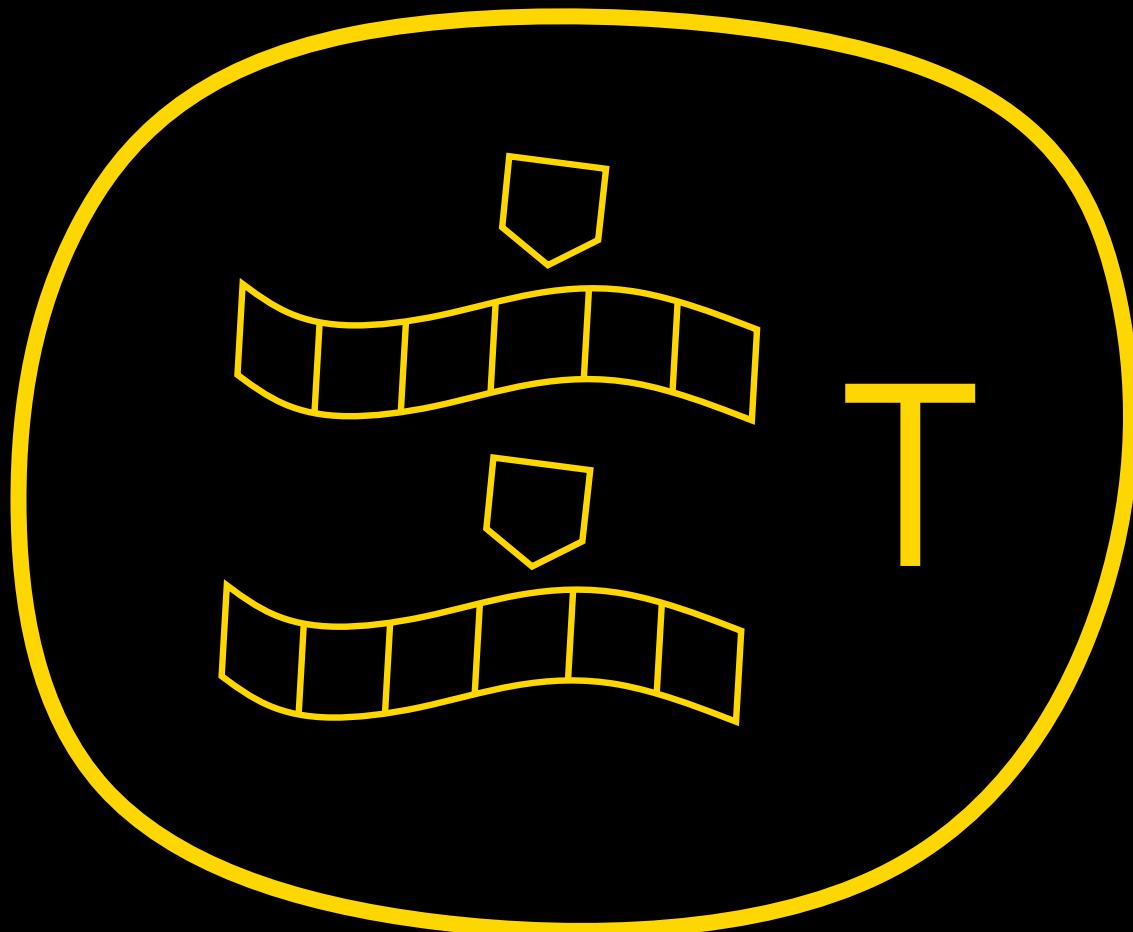
Algorithm I IMPLEMENTATION



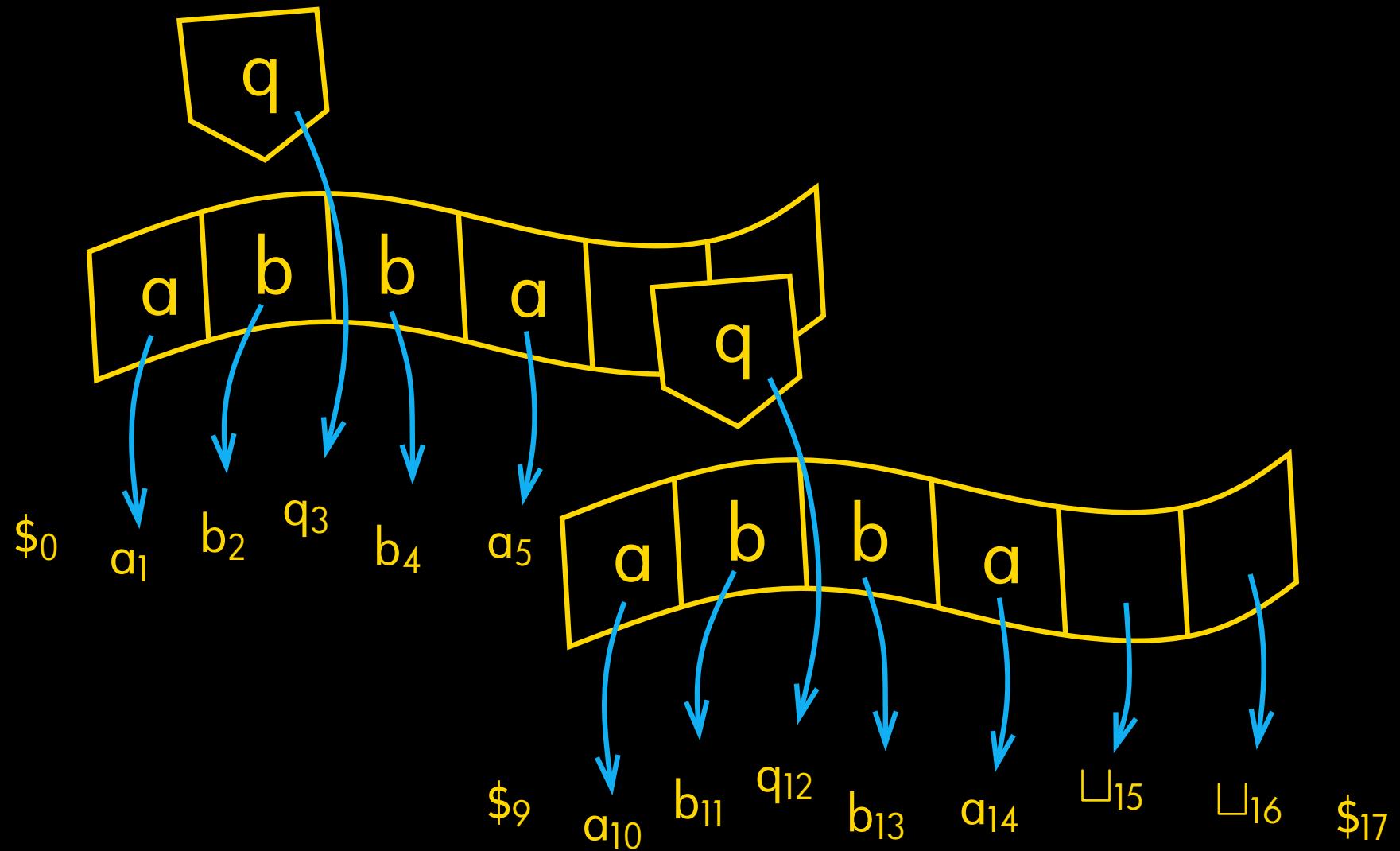
Algorithm I IMPLEMENTATION



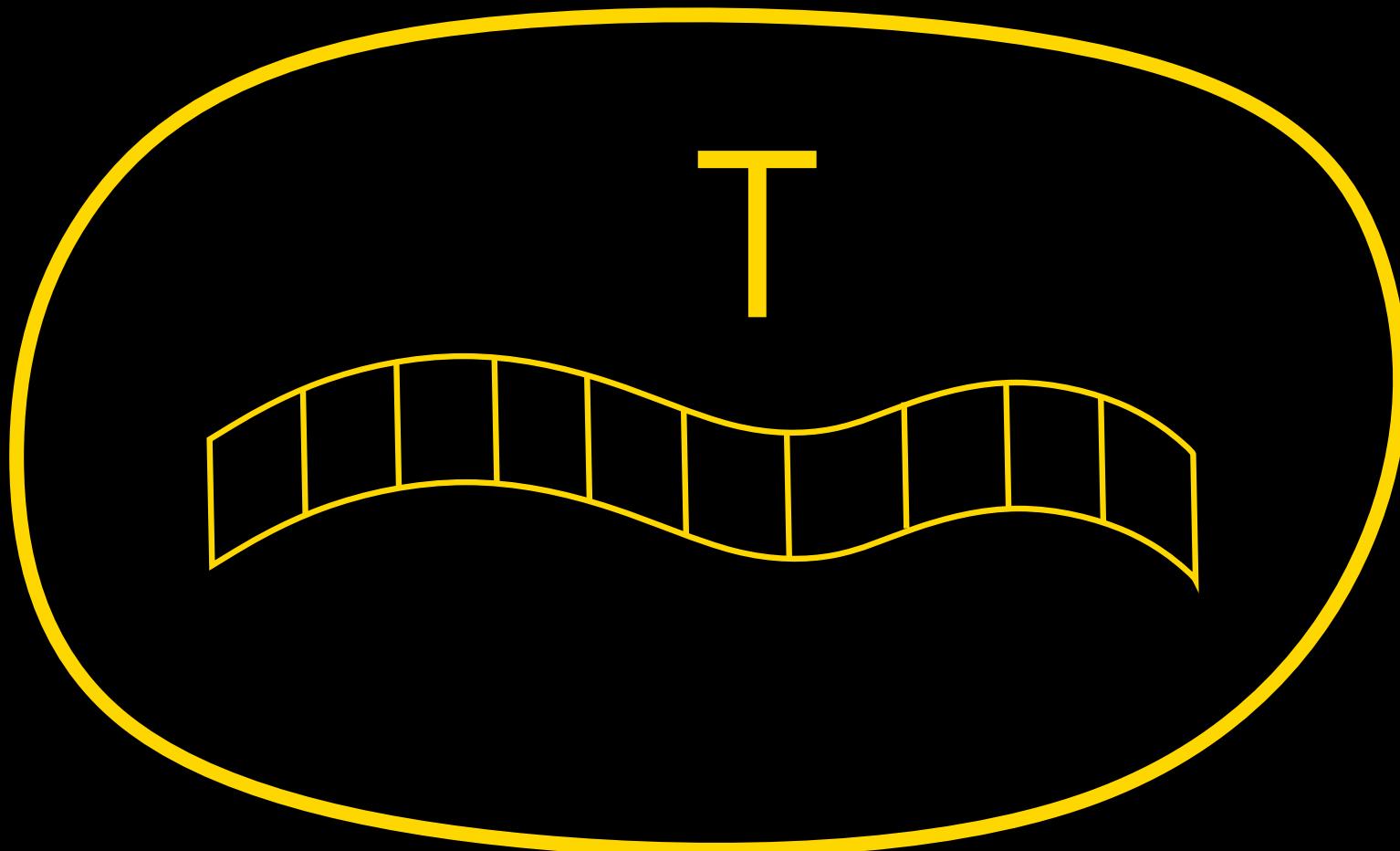
Algorithm I IMPLEMENTATION



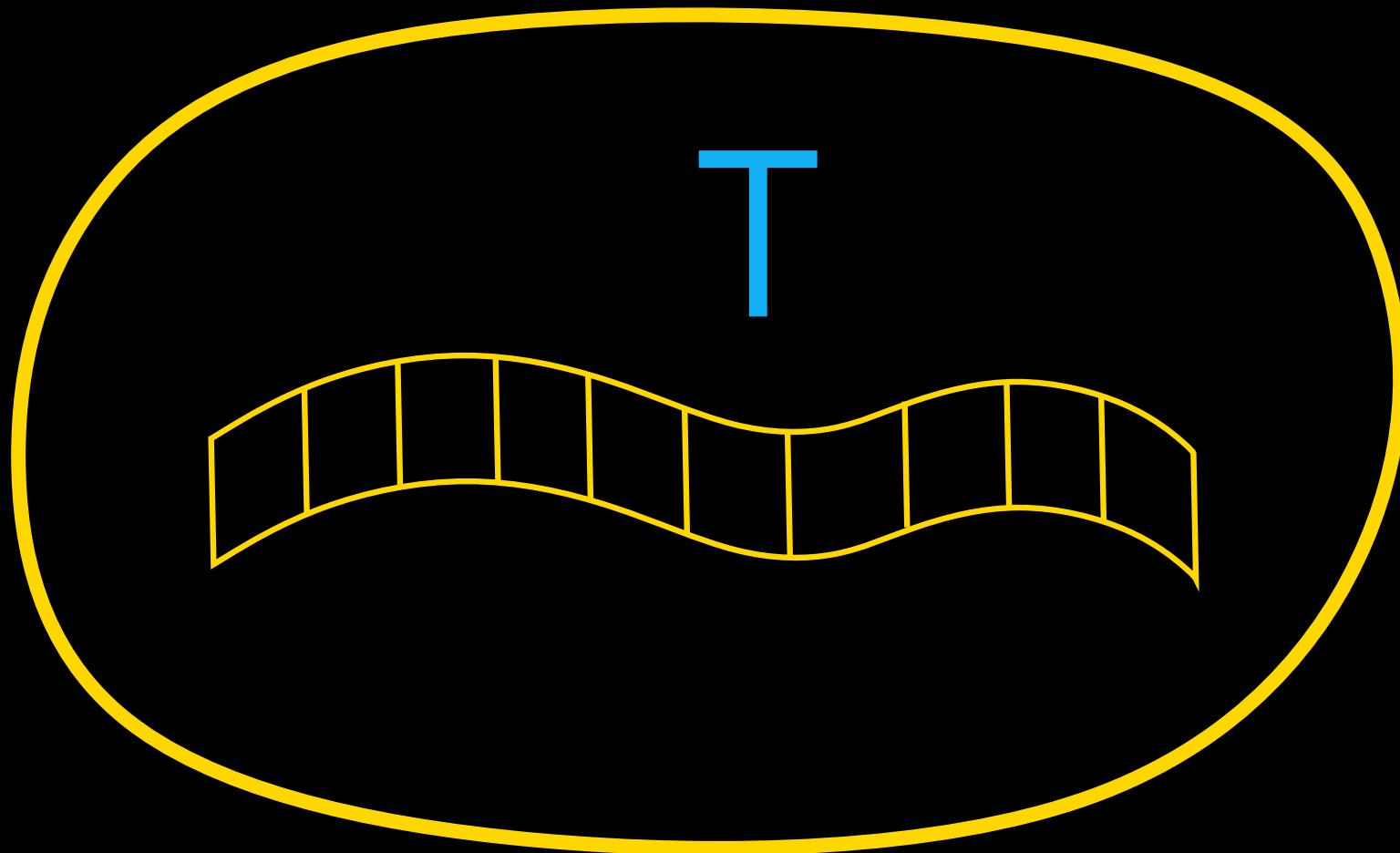
ENCODING TWO TM CFGs



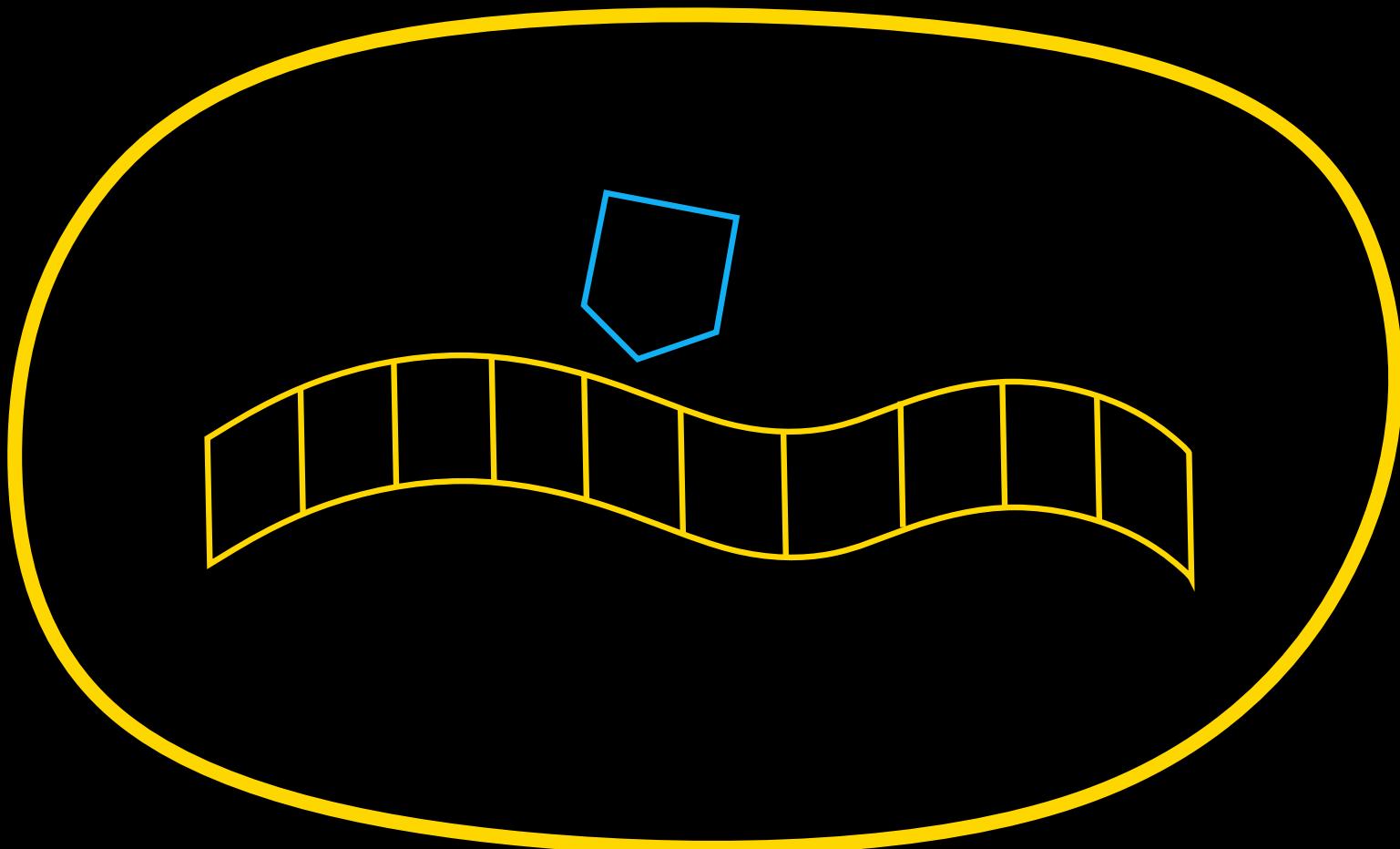
Algorithm I IMPLEMENTATION



Algorithm I IMPLEMENTATION

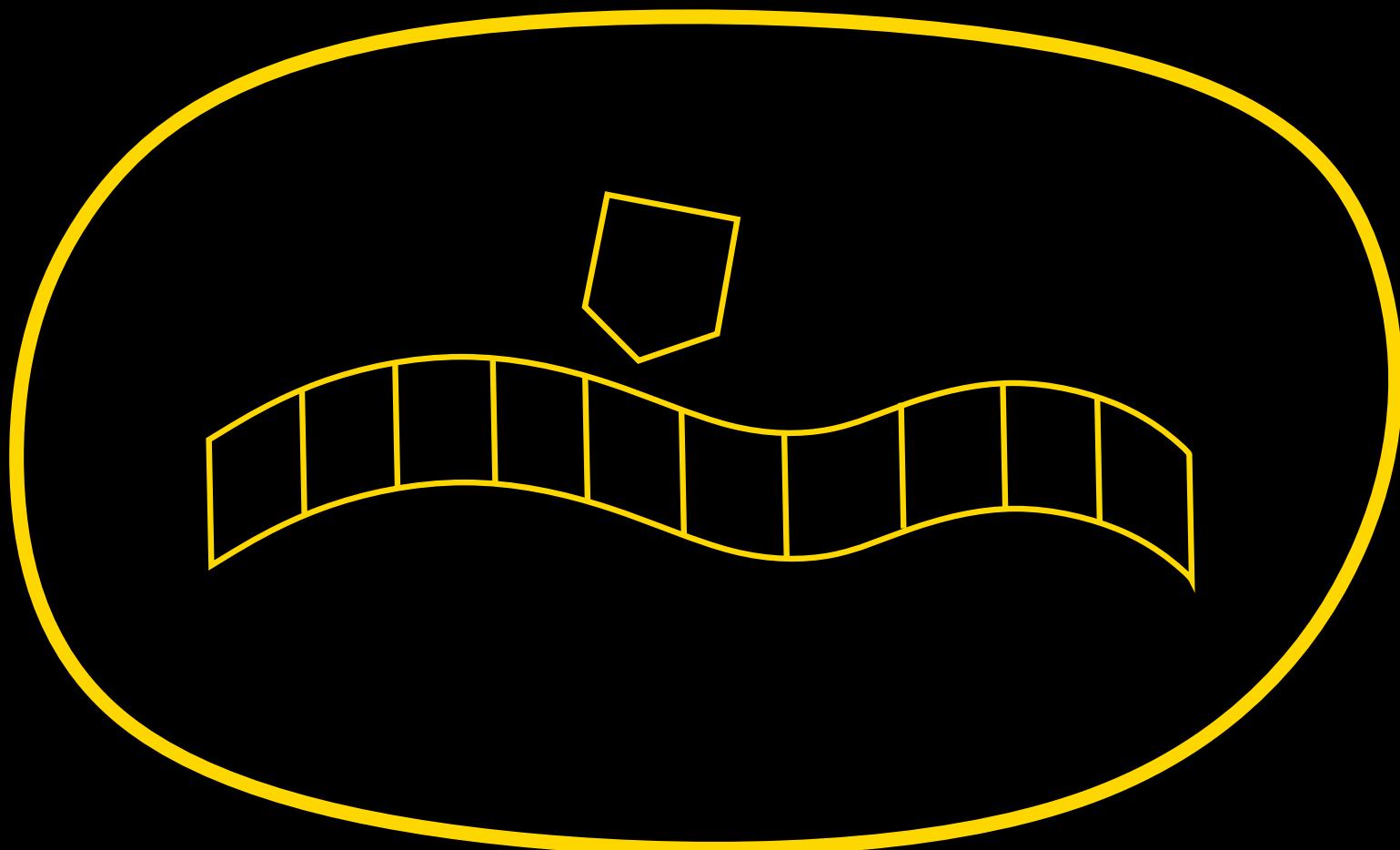


Algorithm I IMPLEMENTATION



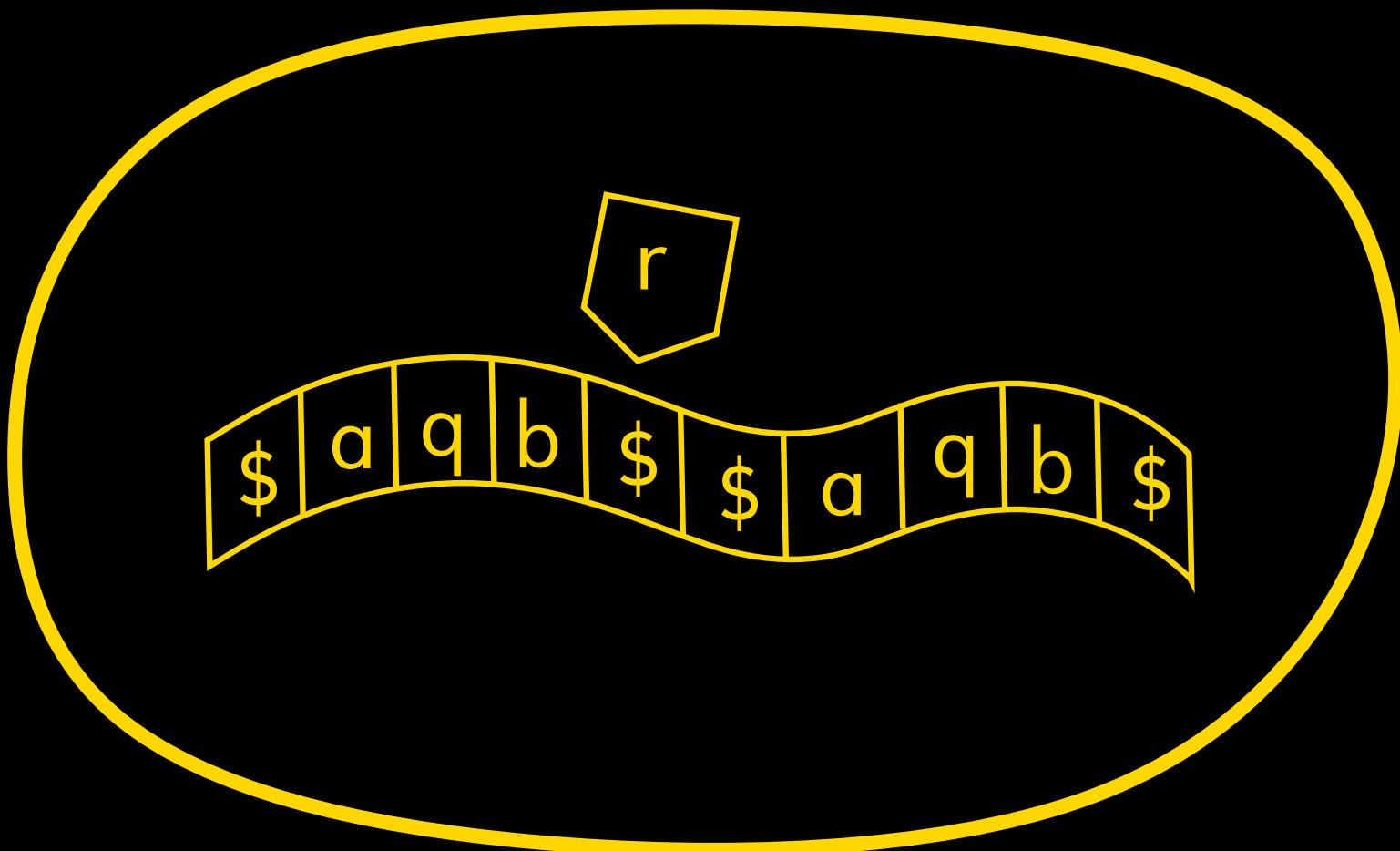
Algorithm II

SIMULATING A TM



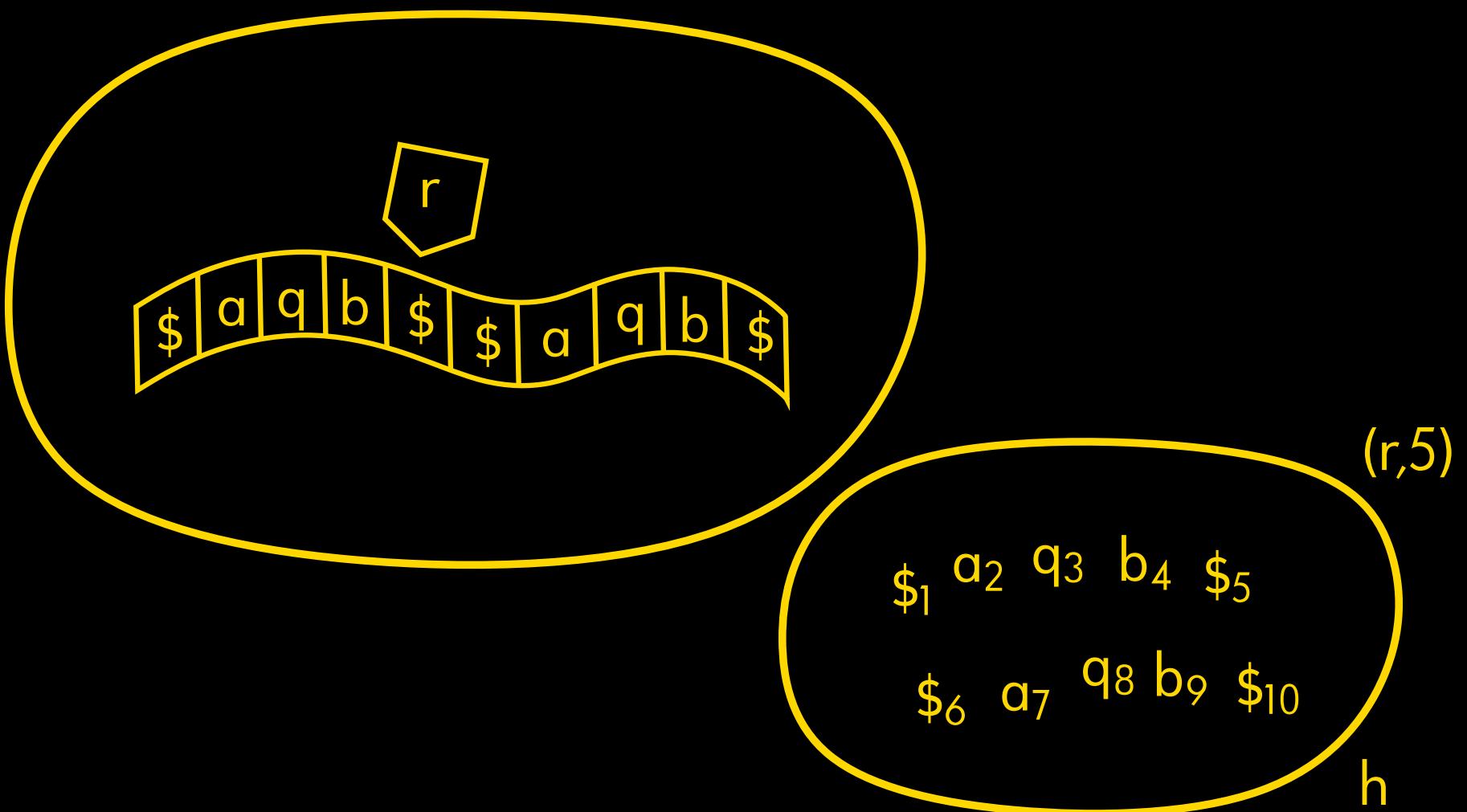
Algorithm II

SIMULATING A TM



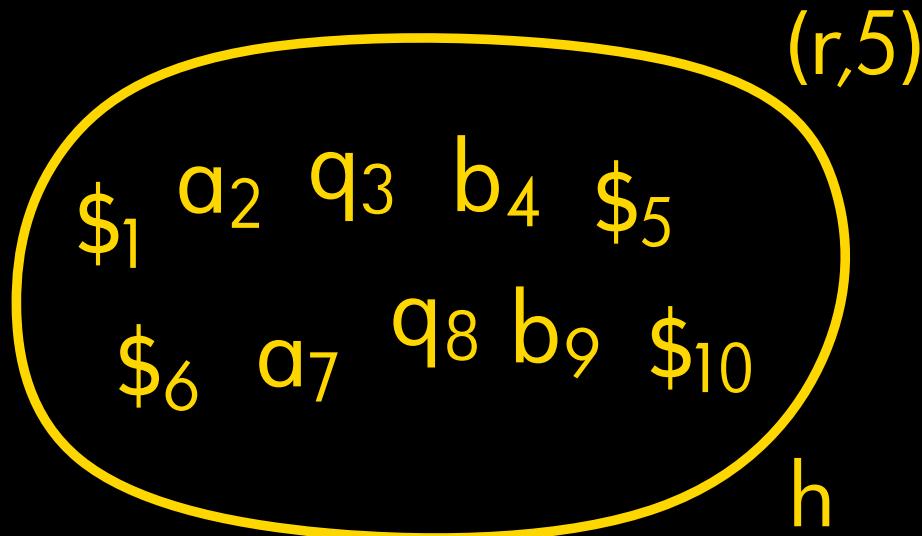
Algorithm II

SIMULATING A TM



Algorithm II

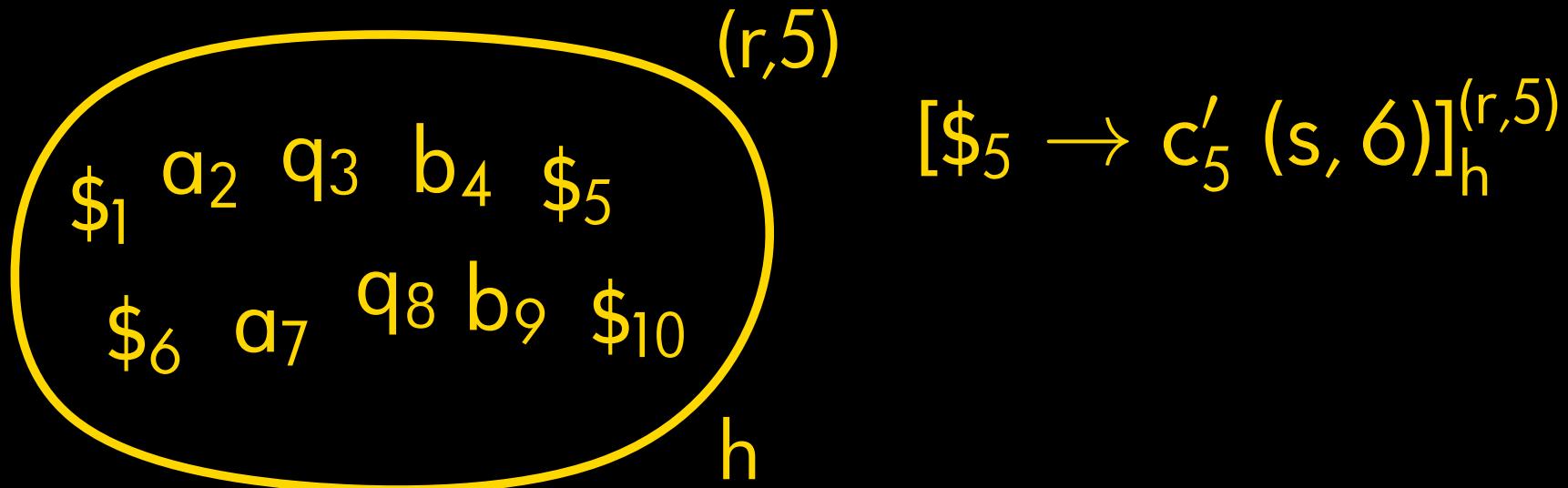
SIMULATING A TM



$$\delta(r, \$) = (s, c, +1)$$

Algorithm II

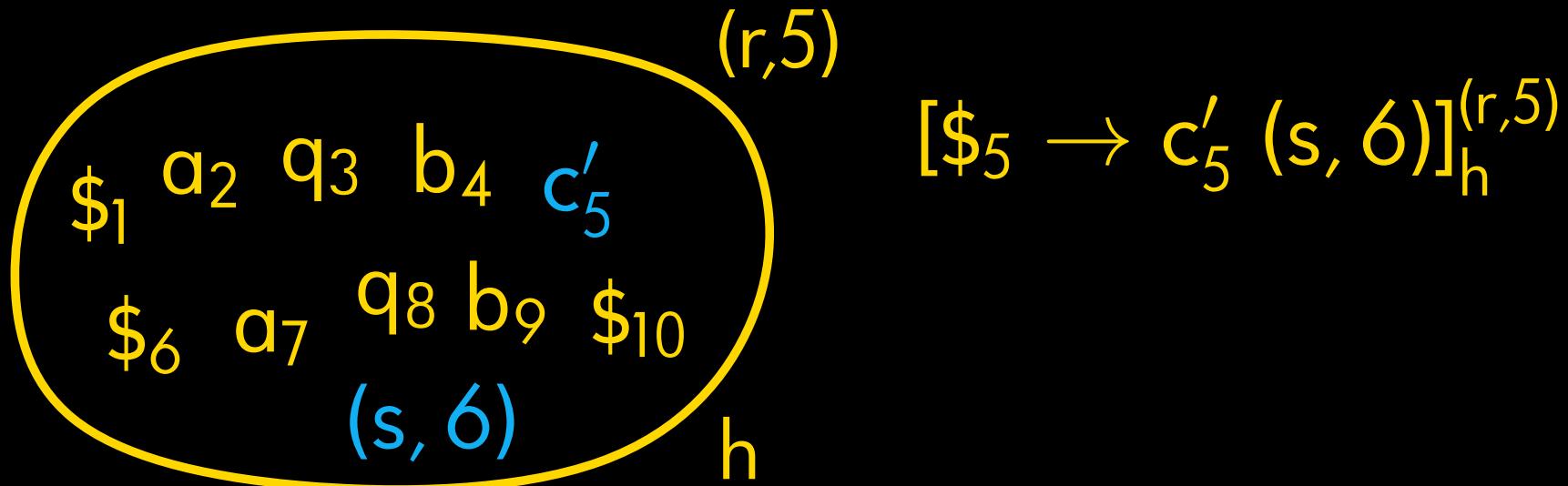
SIMULATING A TM



$$\delta(r, \$) = (s, c, +1)$$

Algorithm II

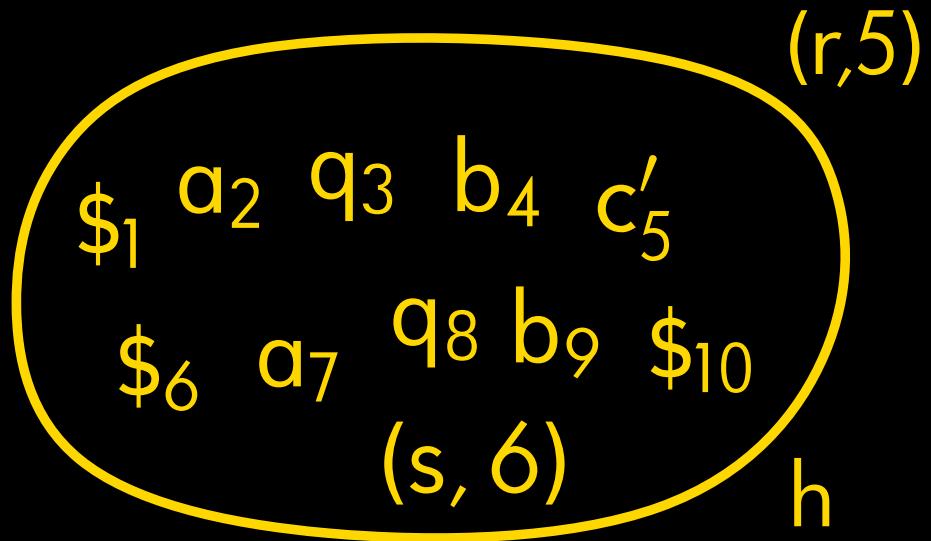
SIMULATING A TM



$$\delta(r, \$) = (s, c, +1)$$

Algorithm II

SIMULATING A TM

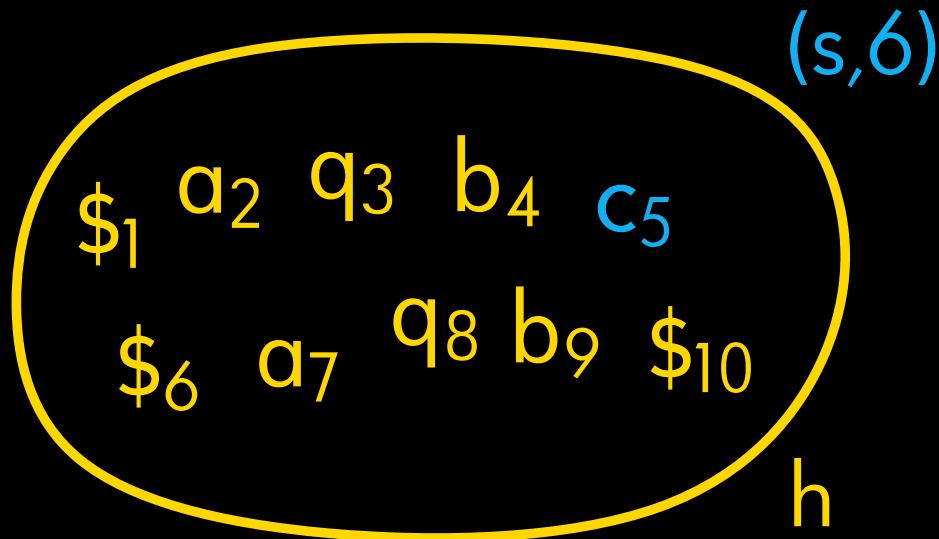


$[\$_5 \rightarrow c'_5 \ (s, 6)]_h^{(r,5)}$
 $[c'_5 \rightarrow c_5]_h^{(r,5)}$
 $[(s, 6)]_h^{(r,5)} \rightarrow []_h^{(s,6)} \ #$

$$\delta(r, \$) = (s, c, +1)$$

Algorithm II

SIMULATING A TM

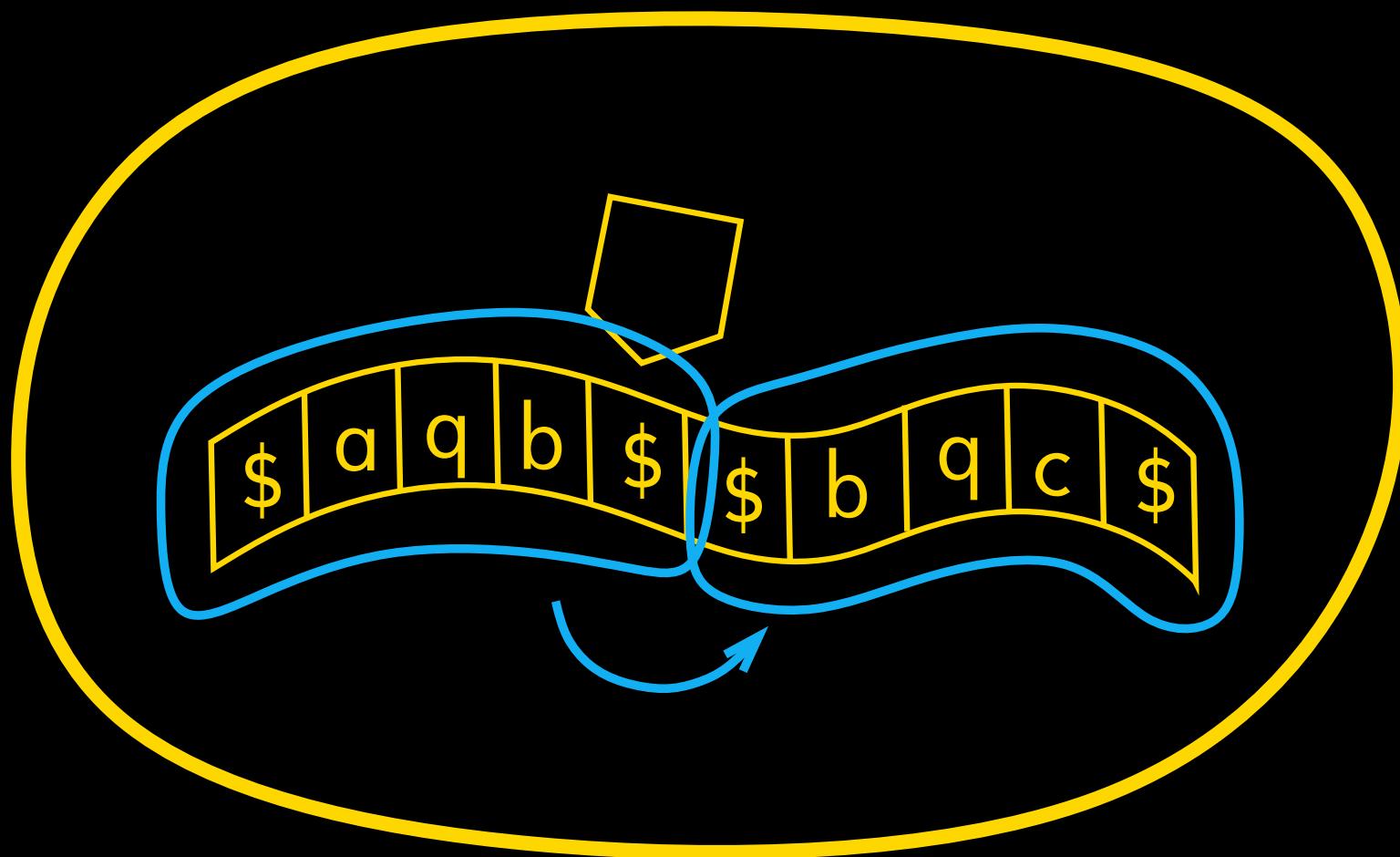


$$\begin{aligned} & [\$_5 \rightarrow c'_5 \ (s, 6)]_h^{(r,5)} \\ & [c'_5 \rightarrow c_5]_h^{(r,5)} \\ & [(s, 6)]_h^{(r,5)} \rightarrow []_h^{(s,6)} \ # \end{aligned}$$

$$\delta(r, \$) = (s, c, +1)$$

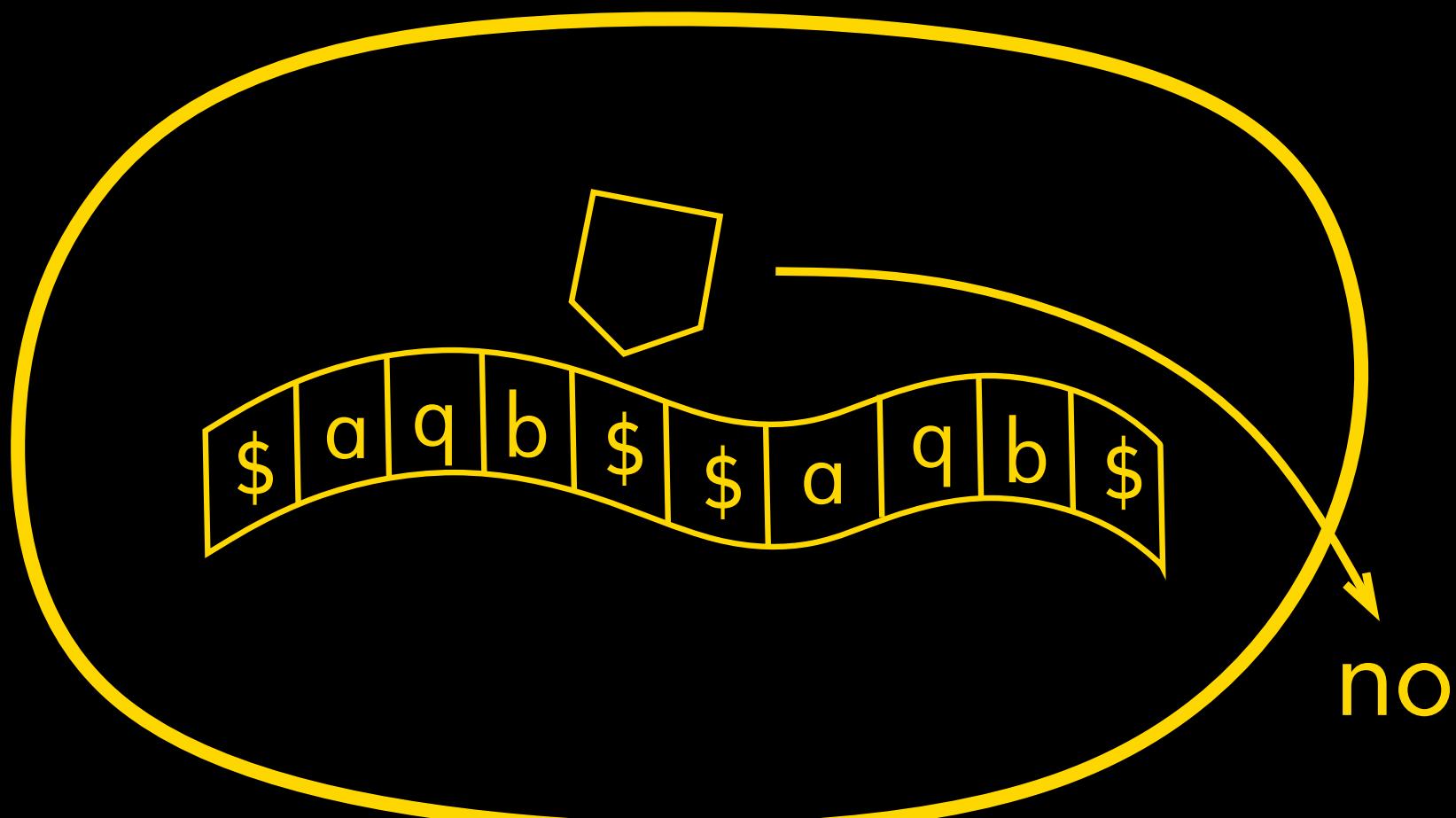
Algorithm II

SIMULATING A TM

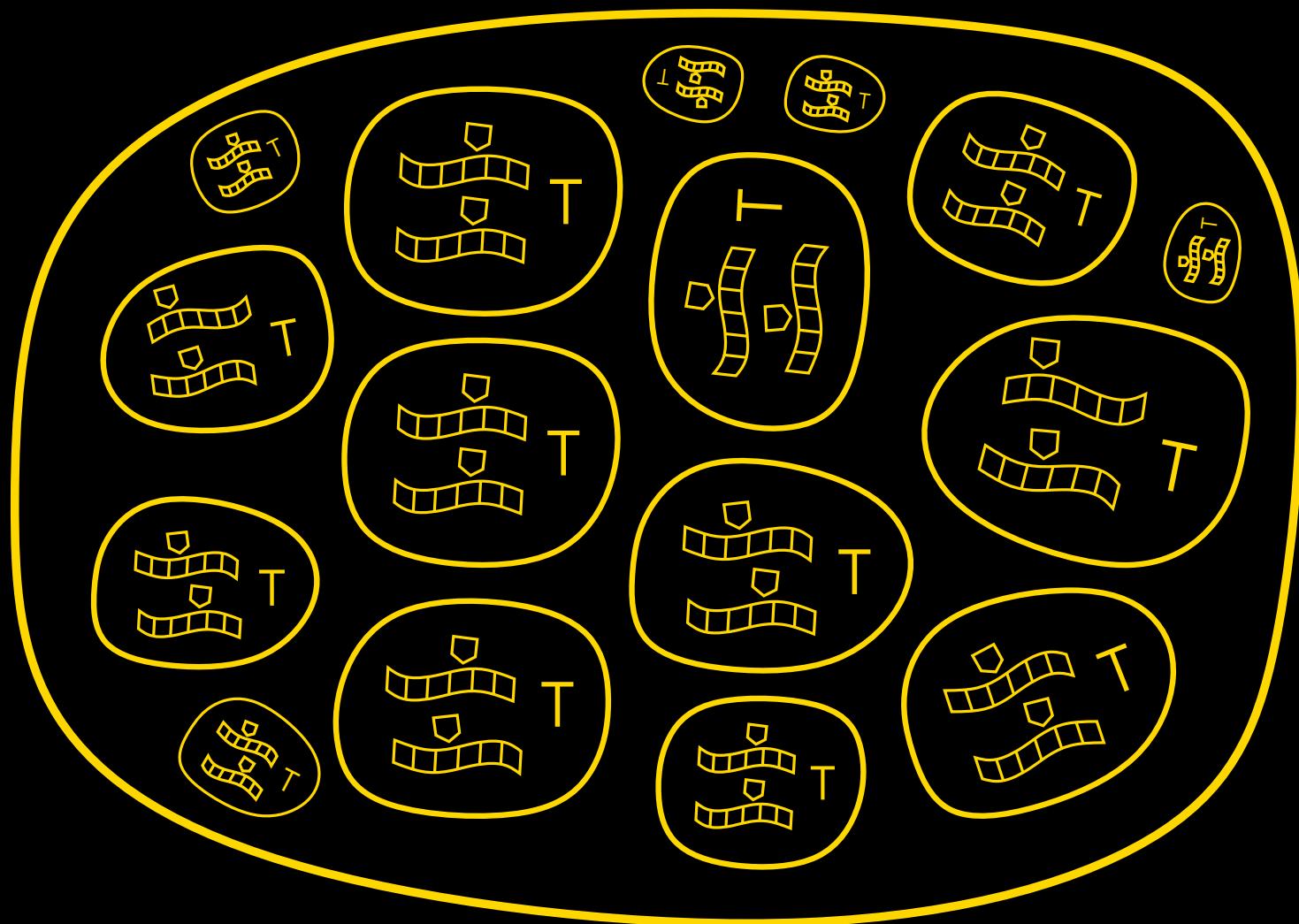


Algorithm II

SIMULATING A TM

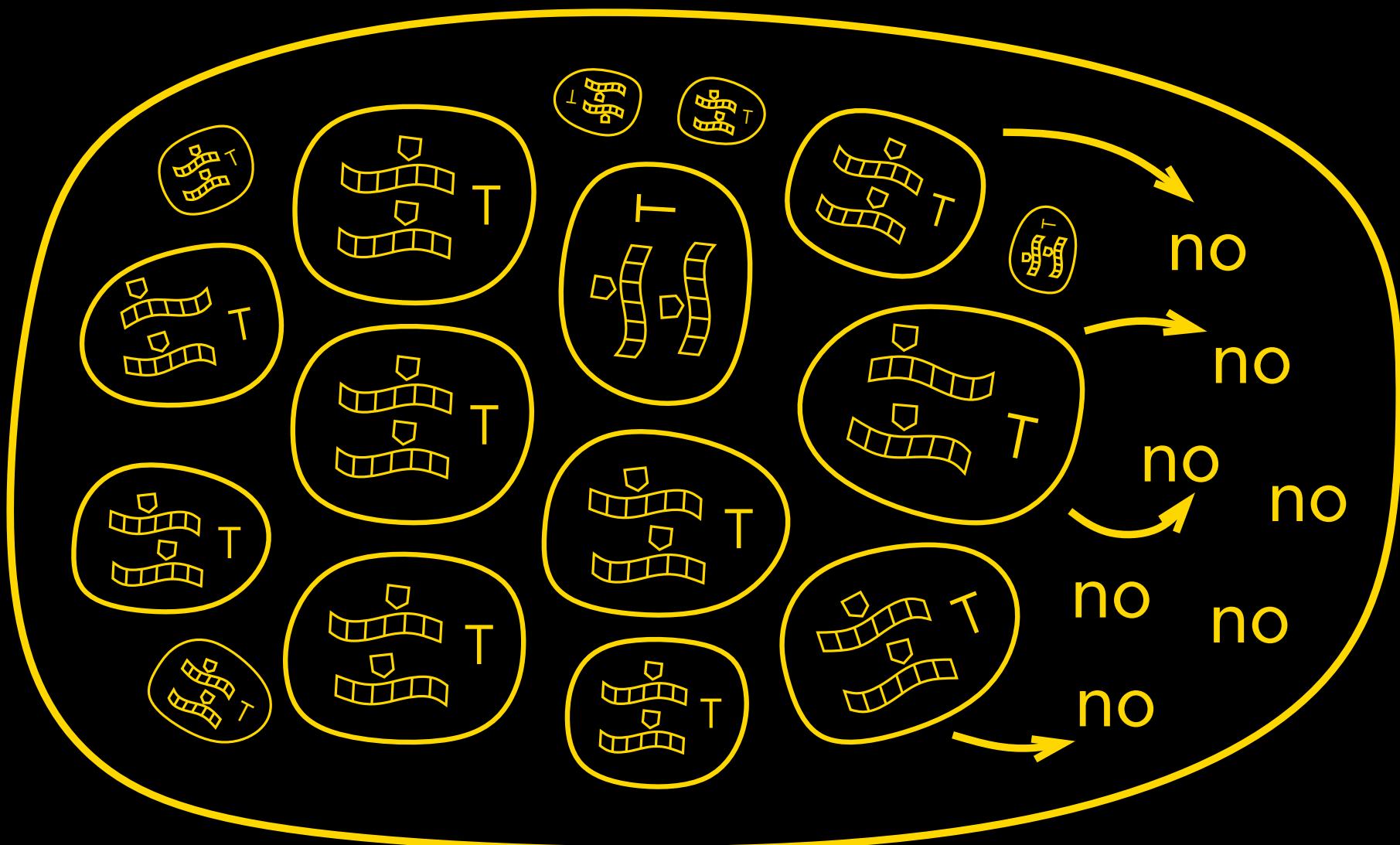


Algorithm I IMPLEMENTATION



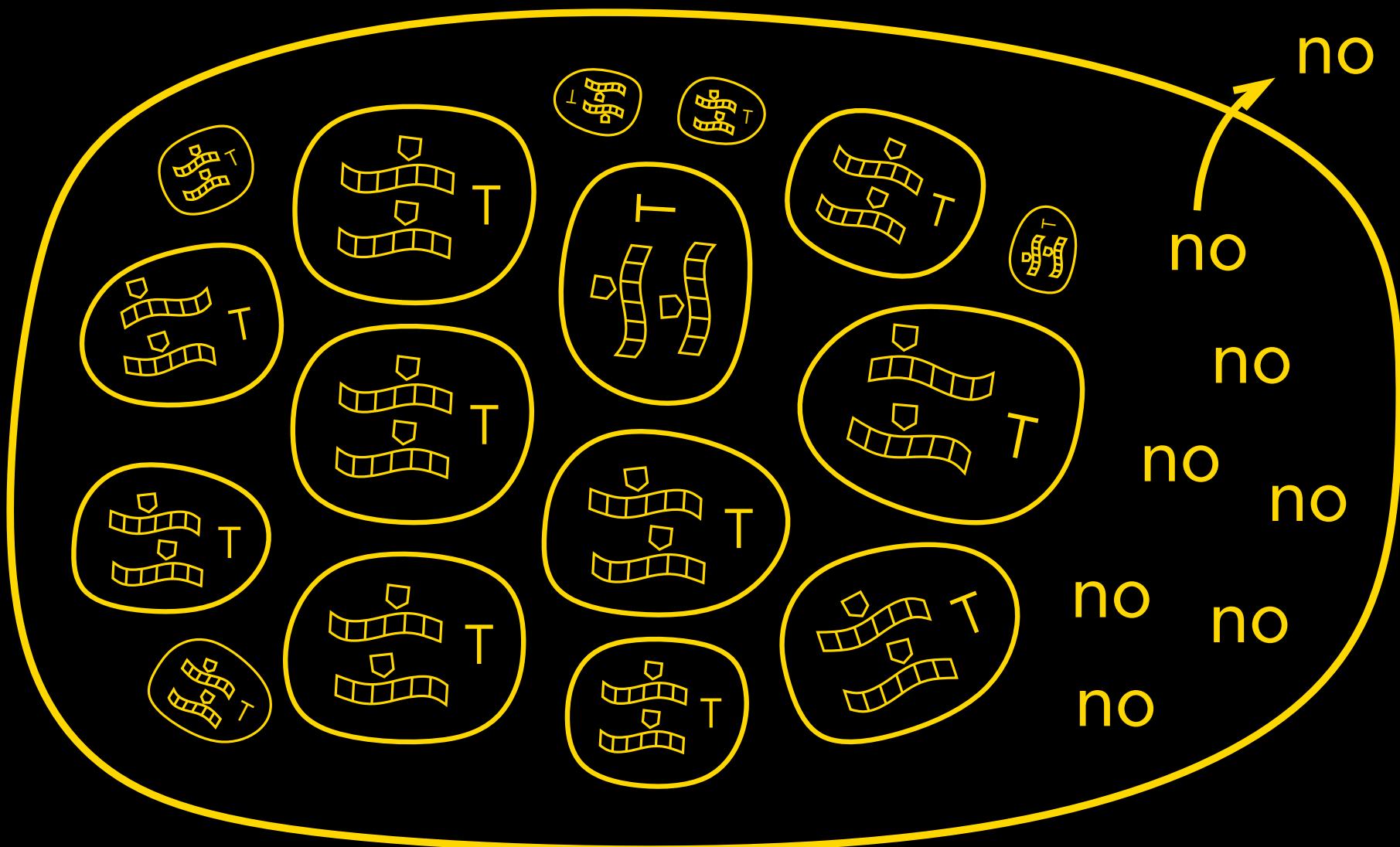
Algorithm I

IMPLEMENTATION

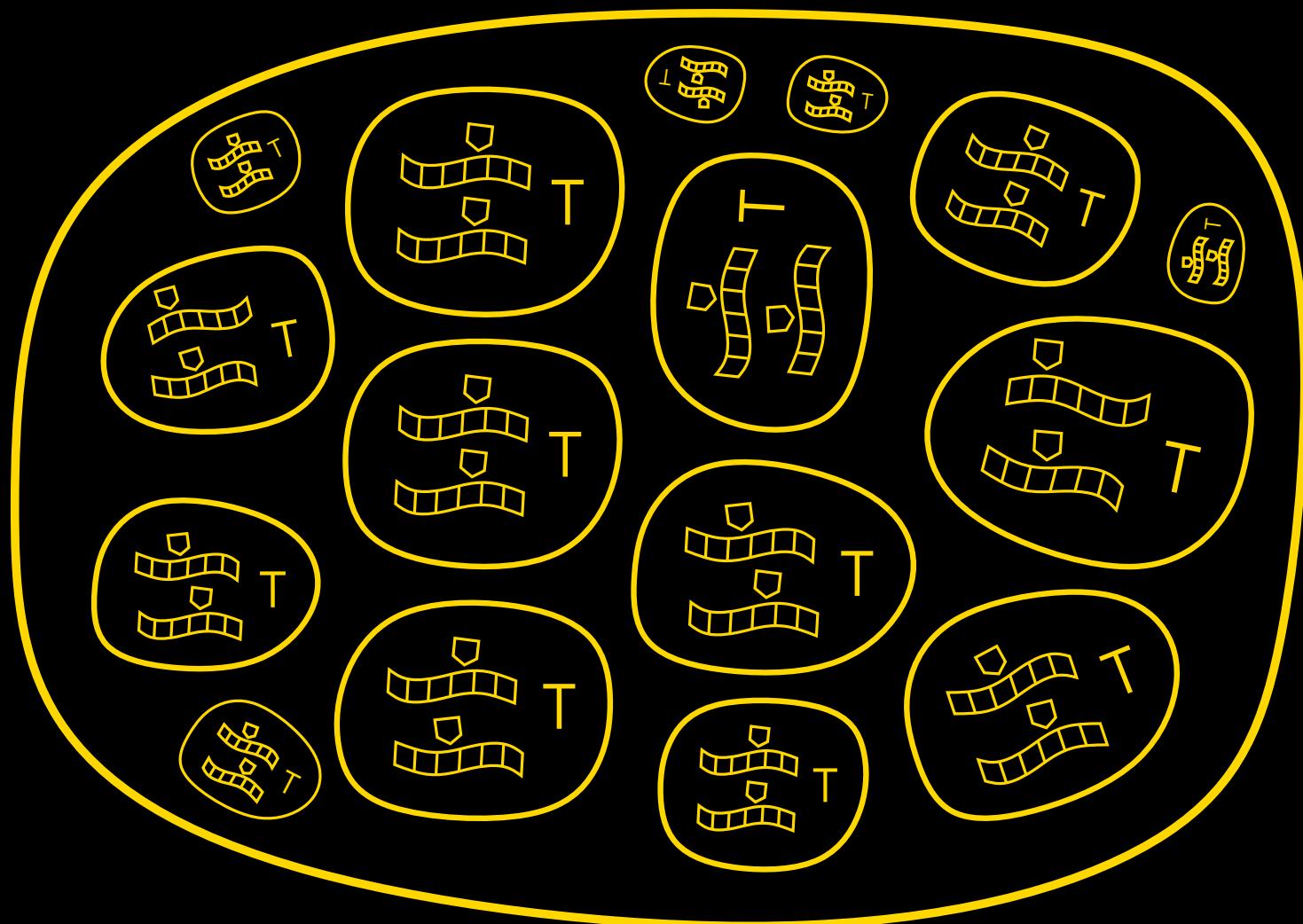


Algorithm I

IMPLEMENTATION

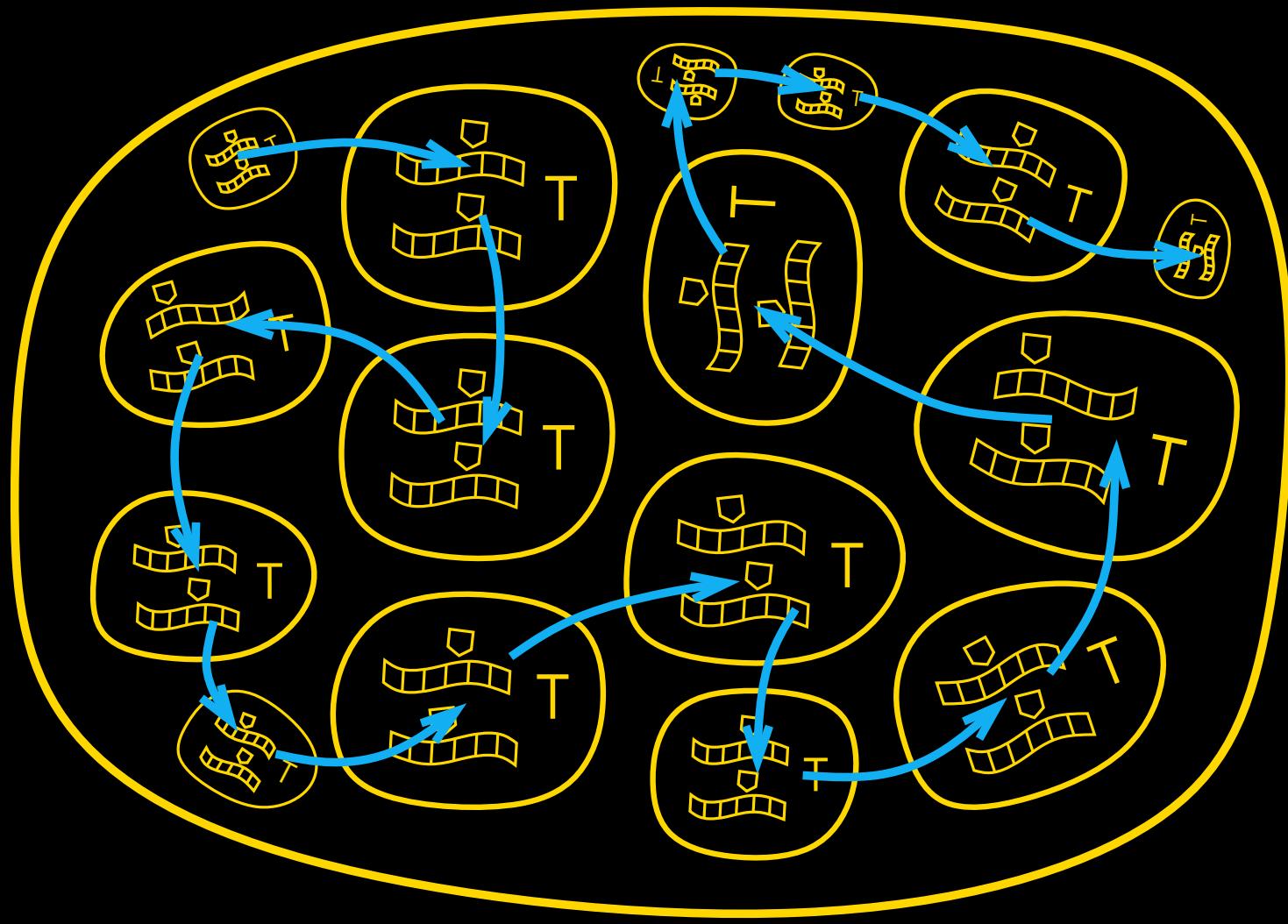


Algorithm I IMPLEMENTATION

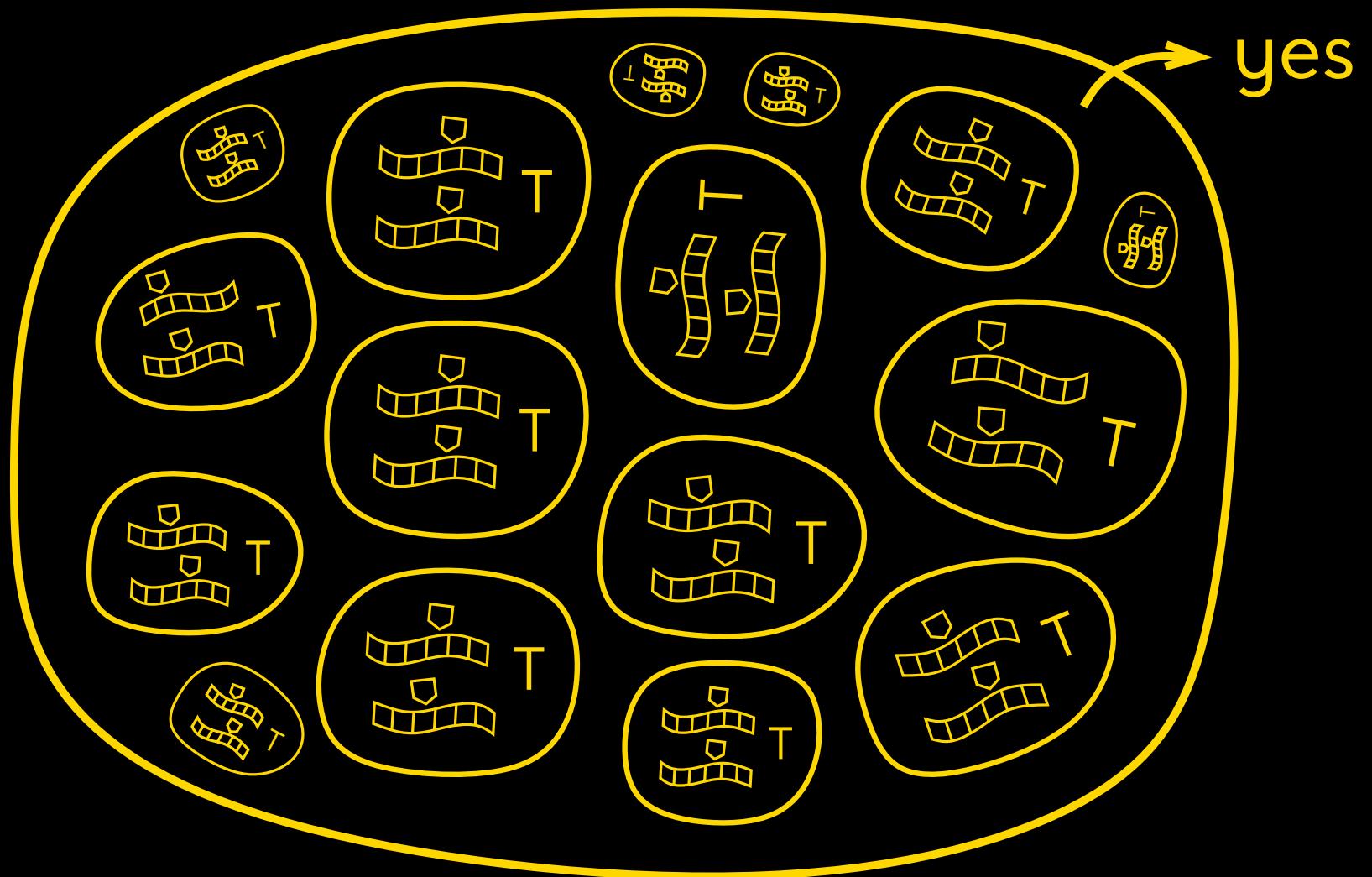


Algorithm I

IMPLEMENTATION



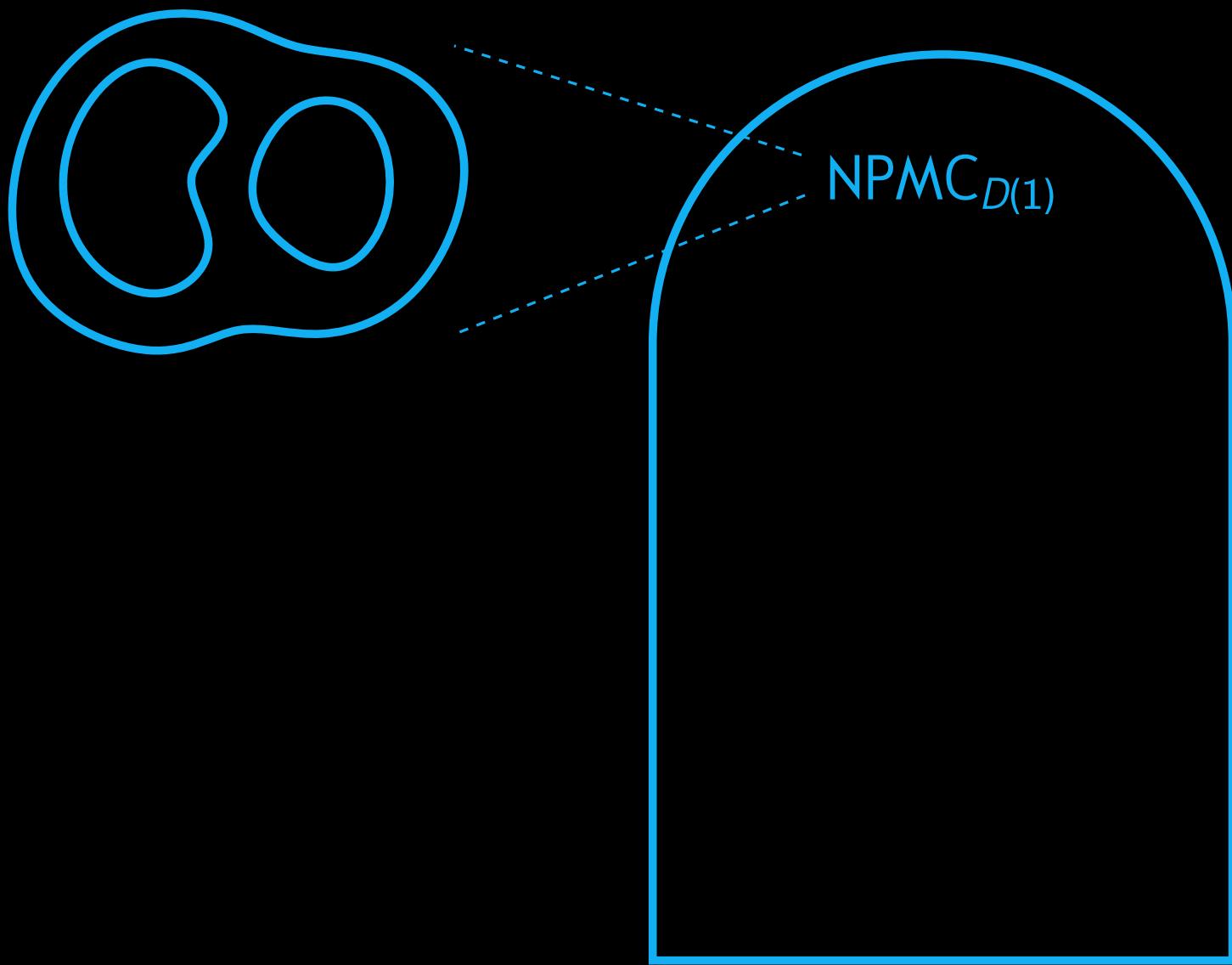
Algorithm I IMPLEMENTATION

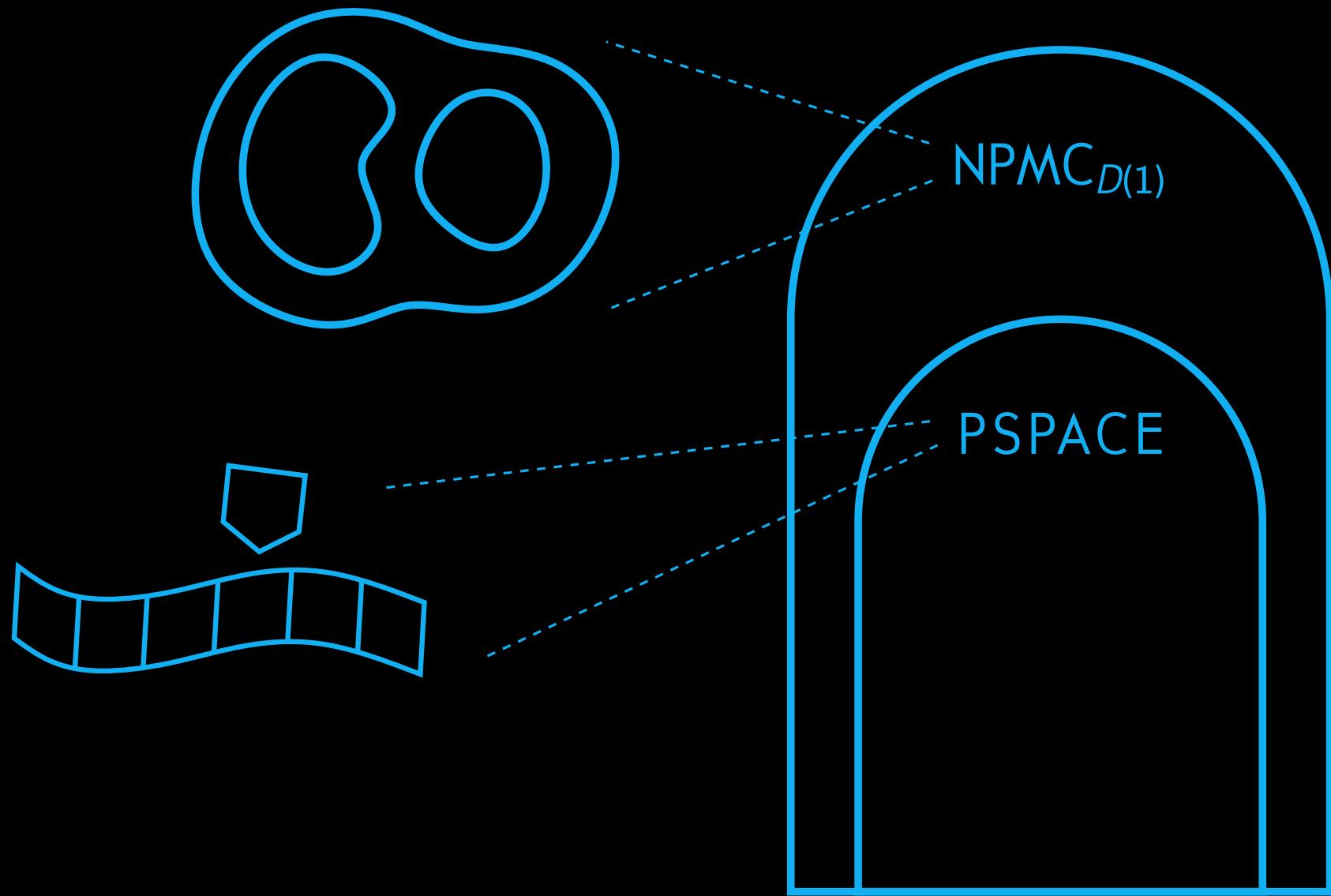


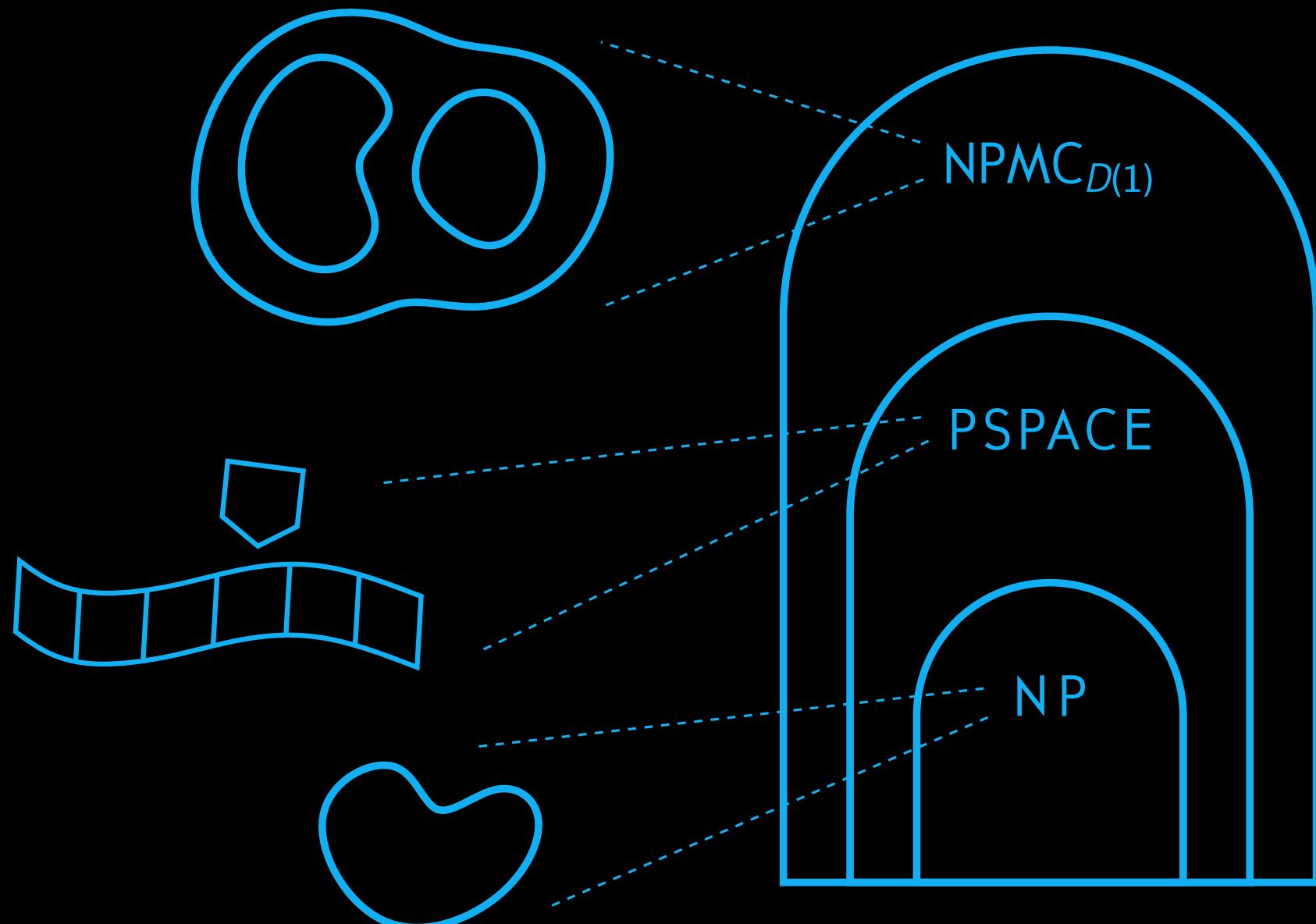
Theorem I

A NEW RESULT

SHALLOW NON-CONFLUENT P systems with active membranes can simulate polynomial-SPACE nondeterministic Turing machines in polynomial TIME, and thus solve all PSPACE problems and restore efficiency to the galaxy....







Theorem I'

MORE SPECIFICALLY

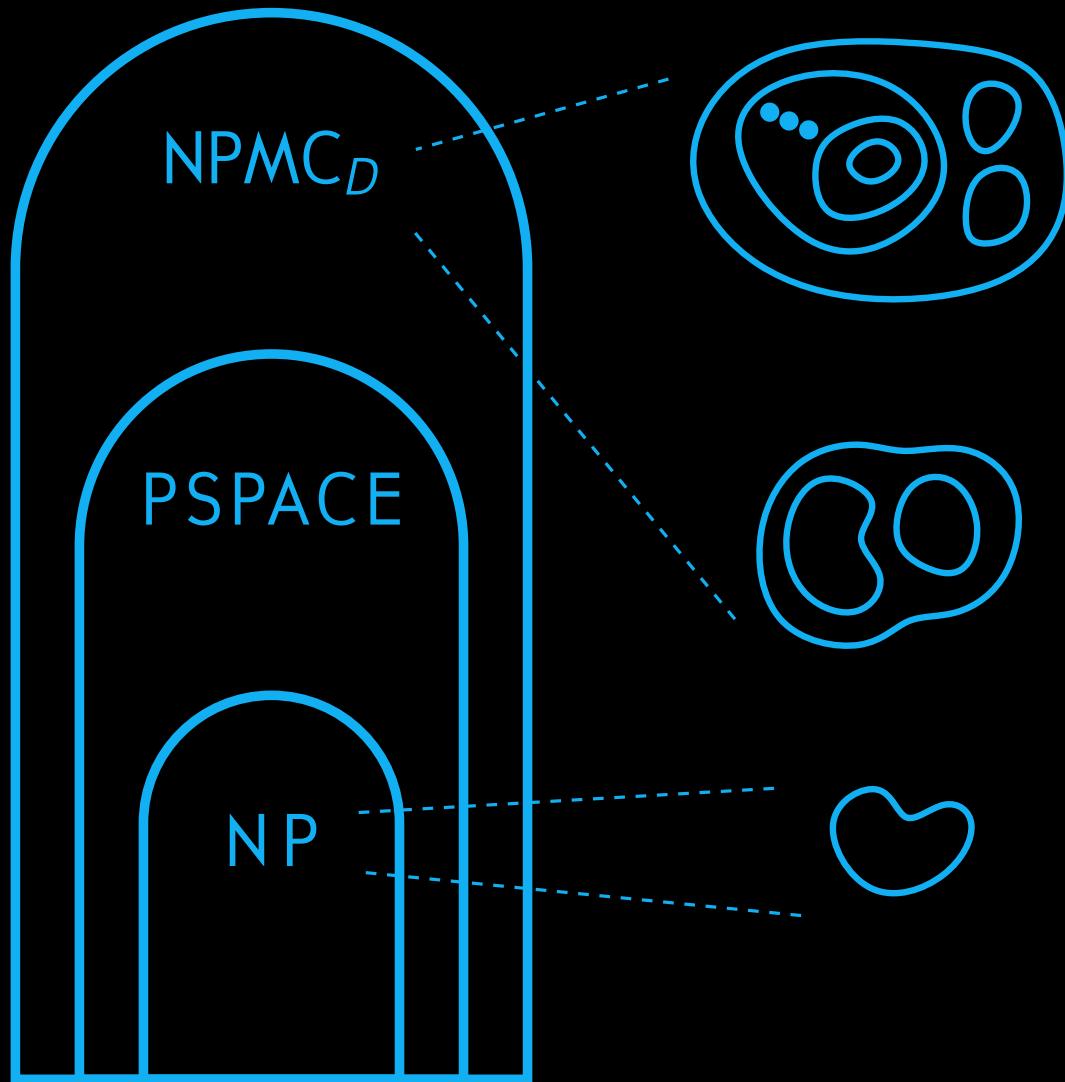
SHALLOW MONODIRECTIONAL NON-CONFLUENT P systems with active membranes can simulate polynomial-SPACE nondeterministic Turing machines in polynomial TIME, and thus solve all PSPACE problems and restore efficiency to the galaxy....

Theorem I'

MORE SPECIFICALLY

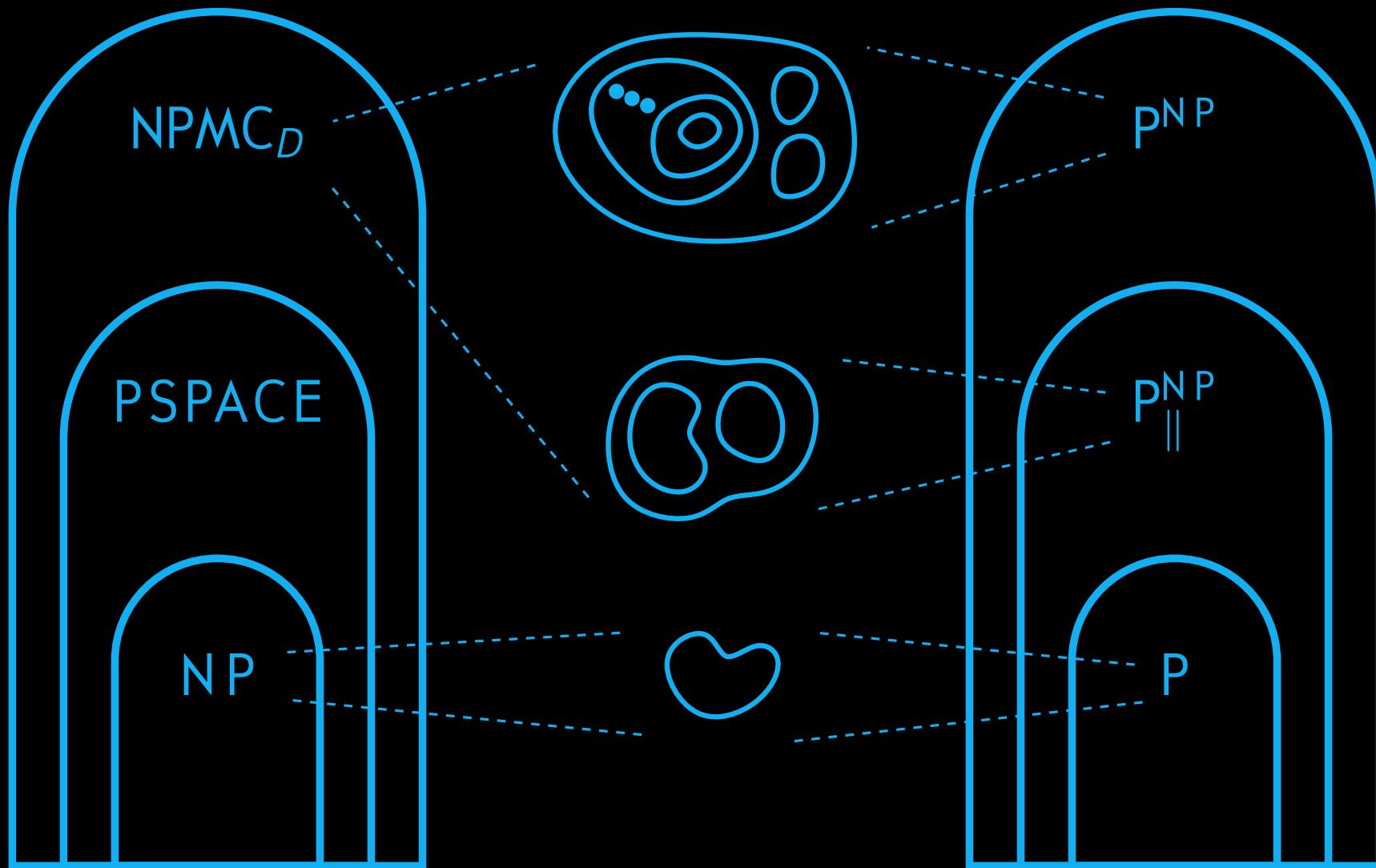
SHALLOW MONODIRECTIONAL NON-
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NON-CONFLUENT



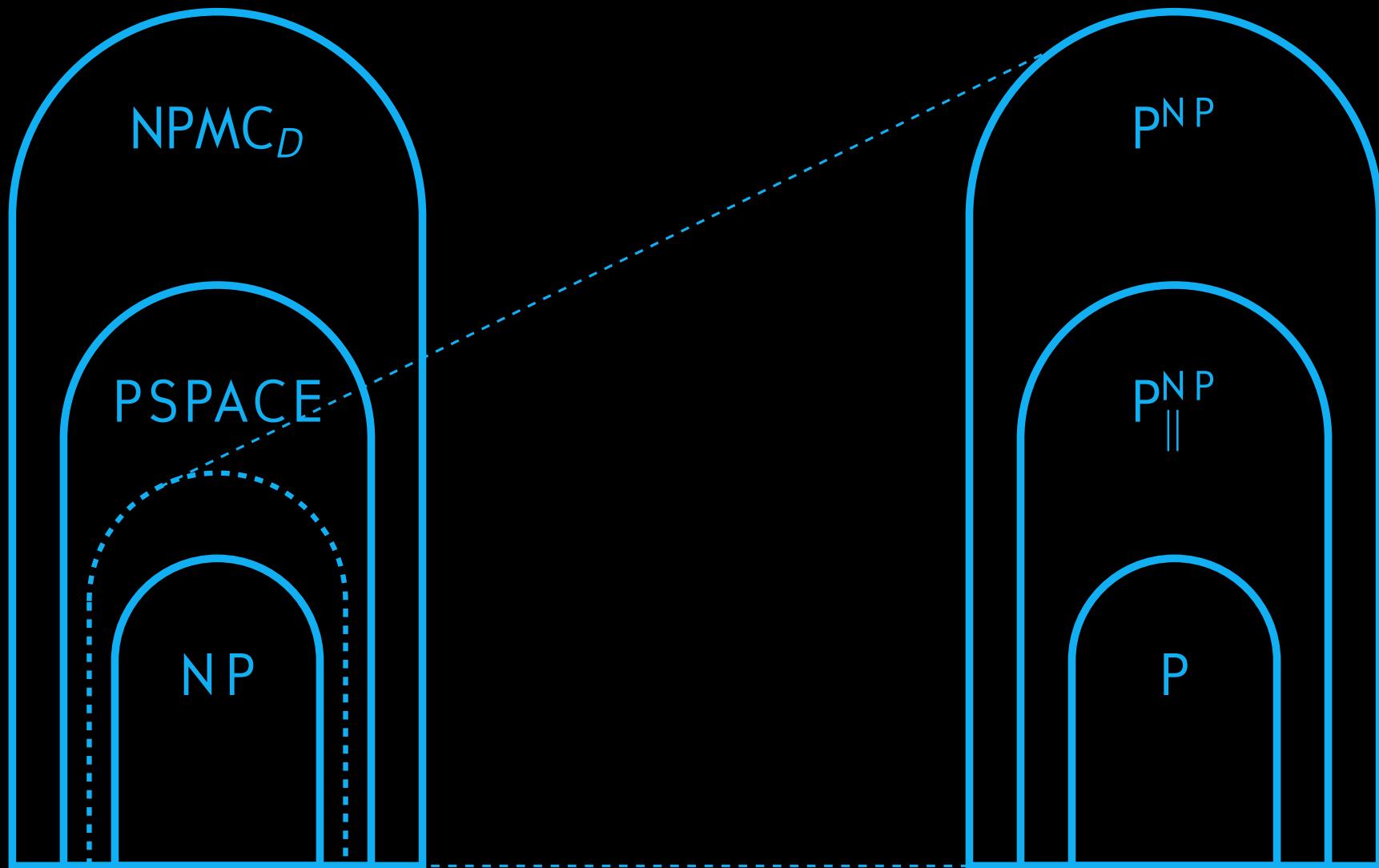
NON-CONFLUENT

CONFLUENT



NON-CONFLUENT

CONFLUENT



Open Problem I

UPPER BOUNDS

UPPER BOUNDS for polynomial-time non-confluent P systems of depth 1 and unbounded depth are still unknown....

Open Problem II

INTERMEDIATE CLASSES

Find a combination of features (e.g., available rules) in order to characterise non-confluently COMPLEXITY CLASSES between NP and PSPACE....

Open Problem III

OTHER MODELS

TISSUE P SYSTEMS with division look similar to P systems with active membranes of depth 1. Maybe they have the same power when non-confluent too....

Thanks for your Attention!
Grazie per la vostra Attenzione!
ANY QUESTIONS?

