## Solving a special case of the P conjecture using dependency graphs with dissolution

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P systems with active membranes without charges

$[a \rightarrow b c] 1$
$[C] 1 \rightarrow[f] 1\left[\begin{array}{l}\sigma \\ 8\end{array}\right]$
$[f] 1 \rightarrow[] 1 f$
$d[]_{1} \rightarrow[d]_{1}$
$[d]_{1} \rightarrow[]_{1} d$

## The P conjecture

[I]t was shown that [...] for solving NP-complete problems [in polynomial time] two charges are enough.

Can the polarizations be completely avoided? [...] The feeling is that this is not possible

Dependency graphs

$\left[[y e s]_{1}\right]_{0}$


## Dependency graphs


$[a \rightarrow b c]_{1}$
$[f]_{1} \rightarrow[]_{1} f$
$d[]_{1} \rightarrow[d]_{1}$
$[c]_{1} \rightarrow[f]_{1}[g]_{1}$
$[f]_{0} \rightarrow[]_{0}$ yes
$[d]_{1} \rightarrow[]_{1} d$

## Dependency graphs


$\left[[\text { yes }]_{1}\right]_{0}$ $\underset{\left[[c]_{1}\right]_{0}}{\checkmark}\left[[f]_{1}\right]_{0} \longrightarrow[f]_{0} \longrightarrow$ yes
$\left[[g]_{1}\right]_{0}$

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## Dependency graphs


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## Dependency graphs


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## $\longrightarrow\left[[b]_{1}\right]_{0}$ <br> $\left[[a]_{1}\right]_{0}$

$\left[[y e s]_{1}\right]_{0}$

$a a^{a}$






Dependency graphs can be constructed and explored in polynomial time

## Dependency graphs can be constructed and explored in polynomial time

The P conjecture is true for P systems without dissolution rules

# Dependency graphs can be constructed and explored in polynomial time 

The $P$ conjecture is true for $P$ systems without dissolution rules

And false for those with both non-elementary division and dissolution (they reach PSPACE)

In $P$ systems without dissolution the result actually depends on one object

## In P systems without dissolution the result

 actually depends on one objectConsider a restricted version of P systems with dissolution:

- monodirectional
- shallow
- deterministic

The result of the computation depends on at most two objects

$$
\mathcal{C}_{0} \longrightarrow \mathcal{C}_{1} \longrightarrow \mathcal{C}_{2} \ldots \ldots \ldots \ldots \mathcal{C}_{t-1} \longrightarrow \mathcal{C}_{t}
$$

The result of the computation depends on at most two objects for each computation

$$
\mathcal{C}_{0} \longrightarrow \mathcal{C}_{1} \longrightarrow \mathcal{C}_{2} \ldots \ldots-\cdots \mathcal{C}_{t-1} \longrightarrow \mathcal{C}_{t}
$$

The result of the computation depends on at most two objects

there exists a sequence of small configurations
$\left[\begin{array}{ll}\left.[a b]_{k}\right]_{h} & {\left[[a]_{k}\right]_{h}}\end{array}\right.$
$[a]_{h}$ yes no

The result of the computation depends on at most two objects

and there exists another sequence of configurations

The result of the computation depends on at most two objects

such that the diagram
"commutes" (same result)

## Generalised dependency graphs




$[a \rightarrow b c]_{1}$
$[d]_{0} \rightarrow[]_{0}$ yes
$[e]_{1} \rightarrow e$
$[f]_{1} \rightarrow[g]_{1}[h]_{1}$
$[b \rightarrow d]_{1}$
$[b]_{0} \rightarrow[]_{0}$ no
$[g]_{1} \rightarrow g$
$[c \rightarrow e]_{1}$
$[d]_{1} \rightarrow d$
$[h]_{1} \rightarrow h$

$[a \rightarrow b c]_{1}$
$[b \rightarrow d]_{1}$
$[c \rightarrow e]_{1}$
$[d]_{1} \rightarrow d$
$[e]_{1} \rightarrow e$
$[f]_{1} \rightarrow[g]_{1}[h]_{1}$
$[g]_{1} \rightarrow g$
$[h]_{1} \rightarrow h$

$[a \rightarrow b c]_{1}$
$[b \rightarrow d]_{1}$
$[c \rightarrow e]_{1}$
$[d]_{1} \rightarrow d$
$[e]_{1} \rightarrow e$
$[f]_{1} \rightarrow[g]_{1}[h]_{1}$
$[g]_{1} \rightarrow g$
$[h]_{1} \rightarrow h$

$[a \rightarrow b c]_{1}$
$[d]_{0} \rightarrow[]_{0}$ yes
$[e]_{1} \rightarrow e$
$[f]_{1} \rightarrow[g]_{1}[h]_{1}$
$[b \rightarrow d]_{1}$
$[b]_{0} \rightarrow[]_{0}$ no
$[g]_{1} \rightarrow g$
$[c \rightarrow e]_{1}$
$[d]_{1} \rightarrow d$
$[h]_{1} \rightarrow h$
$\left[a_{1}\right]_{0}$
$\left[\left[\begin{array}{ll}a & \left.d]_{1}\right]_{0}\end{array} \quad\left[\left[\begin{array}{ll}a & \left.]_{1}\right]_{0}\end{array}\right.\right.\right.\right.$

$[a \rightarrow b c]_{1}$
$[b \rightarrow d]_{1}$
$[d]_{0} \rightarrow[]_{0}$ yes
$[e]_{1} \rightarrow e$
$[f]_{1} \rightarrow[g]_{1}[h]_{1}$
$[c \rightarrow e]_{1}$
$[b]_{0} \rightarrow[]_{0}$ no
$[g]_{1} \rightarrow g$
$[h]_{1} \rightarrow h$









$e$ is a troublemaker for $\left[[a]_{1}\right]_{0}$








A configuration $\mathcal{C}$ of the P system is untroubled if it contains a vertex connected to yes but none of its troublemakers

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If $\mathcal{C}$ is untroubled and $\mathcal{C} \rightarrow \mathcal{D}$, then $\mathcal{D}$ is
untroubled

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Theorem. A P system accepts iff its initial configuration is untroubled

The graph has $O$ (alphabet ${ }^{2} \times$ labels) vertices and is constructed by iterating over the rules

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Theorem. We can check in polynomial time if the $P$ system accepts

The monodirectional, shallow, deterministic P conjecture is true

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$$
\mathrm{DPMC}_{\mathcal{D}}^{[\star]}=\mathbf{P}=\mathrm{DMC}_{\mathcal{D}}^{[\star]}
$$

## Open problems

Prove the result for confluent (not just deterministic) $P$ systems

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Use generalised dependency graphs for other variants of $P$ systems to prove $\mathbf{P}$ upper bound or find "borderlines" for efficiency

# Thanks for your attention! <br> Grazie per l'attenzione! 

Any questions?

